



ON THE HELLY PROPERTY OF SOME INTERSECTION GRAPHS

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SOBRE A PROPRIEDADE HELLY DE ALGUNS GRAFOS DE INTERSEÇÃO

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Um grafo EPG é um grafo de aresta-interseção de caminhos sobre uma grade. Nesta tese de doutorado exploraremos principalmente os grafos EPG, em particular os grafos B_1 -EPG. Entretanto, outras classes de grafos de interseção serão estudadas, como as classes de grafos VPG, EPT e VPT, além dos parâmetros número de Helly e número de Helly forte nos grafos EPG e VPG. Apresentaremos uma prova de NP -completude para o problema de reconhecimento de grafos B_1 -EPG-Helly. Investigamos os parâmetros número de Helly e o número de Helly forte nessas duas classes de grafos, EPG e VPG, a fim de determinar limites inferiores e superiores para esses parâmetros. Resolvemos completamente o problema de determinar o número de Helly e o número de Helly forte para os grafos B_k -EPG e B_k -VPG, para cada valor k .

Em seguida, apresentamos o resultado de que todo grafo B_1 -EPG Chordal está simultaneamente nas classes de grafos VPT e EPT. Em particular, descrevemos estruturas que ocorrem em grafos B_1 -EPG que não suportam uma representação B_1 -EPG-Helly e assim definimos alguns conjuntos de subgrafos que delimitam subfamílias Helly. Além disso, também são apresentadas características de algumas famílias de grafos não triviais que estão propriamente contidas em B_1 -EPG-Helly.

Palavras-chave: EPG, EPT, Grafos de Interseção, NP -completude, Propriedade Helly, VPG, VPT.

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ON THE HELLY PROPERTY OF SOME INTERSECTION GRAPHS

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An EPG graph G is an edge-intersection graph of paths on a grid. In this doctoral thesis we will mainly explore the EPG graphs, in particular B_1 -EPG graphs. However, other classes of intersection graphs will be studied such as VPG, EPT and VPT graph classes, in addition to the parameters Helly number and strong Helly number to EPG and VPG graphs. We will present the proof of NP -completeness to Helly- B_1 -EPG graph recognition problem. We investigate the parameters Helly number and the strong Helly number in both graph classes, EPG and VPG in order to determine lower bounds and upper bounds for this parameters. We completely solve the problem of determining the Helly and strong Helly numbers, for B_k -EPG, and B_k -VPG graphs, for each value k .

Next, we present the result that every Chordal B_1 -EPG graph is simultaneously in the VPT and EPT graph classes. In particular, we describe structures that occur in B_1 -EPG graphs that do not support a Helly- B_1 -EPG representation and thus we define some sets of subgraphs that delimit Helly subfamilies. In addition, features of some non-trivial graph families that are properly contained in Helly- B_1 EPG are also presented.

Keywords: EPG, EPT, Helly property, Intersection graphs, NP -completeness, VPG, VPT.

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Chapter 1

Introduction

*Believe and you will understand;
faith precedes, follows intelligence.*

Saint Augustine

Graph Theory is a branch of Mathematics that is used by the Computer Science to describe and model several real and theoretical problems. This doctoral thesis is dedicated to solving some problems of Graph Theory. In particular, in this chapter, you will find a brief description of the related problems, the motivation of the study and, a summary of the organization of the text.

Graph Theory is based on relations between points that we call vertices interconnected (by elements denoted as edges) in a network. In this context we define a graph $G = (V, E)$, where $V(G)$ denotes the vertex set of G and $E(G)$ its edge set. The graph is the object that we use to model the relationship among elements of a set.

An *intersection graph* is a graph that represents the pattern of intersections of a family of sets. A graph G can be represented as an intersection graph when for each vertex v_i, v_j of G there are corresponding sets S_i, S_j such that $S_i \cap S_j \neq \emptyset$ if and only if $(v_i, v_j) \in E(G)$. In this doctoral thesis, we are interested in the study of intersection graphs. Issues related to intersection graphs have been attracting the attention of researchers since the 1960, e.g. [33], and to the present day, see [62, 64].

First, we know that every graph is an intersection graph, i.e. any graph can be represented by some intersection model, [33, 72]. SCHEINERMAN [68] presents research that is exclusively dedicated to the characterization of classes of intersection graphs, also providing necessary and sufficient conditions for the existence of intersection representations for some specific graph classes.

Many important graph families can be described as intersection graphs. We can cite Interval, Circular-arc, Permutation, Trapezoid, Chordal, Disk, Circle graphs

which are among the most important or at least the most studied classes in the literature in general.

Interval graphs are the intersection graph class of a collection of segments on a line, and the class of Chordal graphs corresponds to the graphs where each cycle $C_n, n \geq 3$ has a chord. Interval graphs have been extensively studied by [54]. About Chordal graphs, GAVRIL [38] shows that this class corresponds exactly to the intersection graph of subtrees on a tree. In this thesis, we will study intersection graphs of paths on a grid and on trees.

GOLUMBIC *et al.* [46] defined the edge intersection graphs of paths on a grid (EPG graphs). Similarly, [7, 9] defined the vertex intersection graphs of paths on a grid (VPG graphs). Both intersection models have some practical importance since they can be used to generalize naturally the context of circuit layout problems and layout optimization [69] where a layout is modeled as paths (wires) on a grid. Thus, they are problems that arise directly from this modeling: reducing the number of times that each path can bend in order to minimize the cost or difficulty of production of a microchip or electronic board [10, 58]; or other times layouts may consist of several layers where the paths on each layer are not allowed to intersect, this can be understood as a coloring problem. These are the main applications that instigate research on the EPG and VPG representations of some graph families. Other applications and details on circuit layout problems can be found in [10, 58, 69].

Some particular questions related to intersection graphs aroused our research interest. Among these, we can mention: “What is the complexity of recognizing a class of path intersection graphs on a grid if we restrict the number of bends in each path individually and considering the fact of each set of intersections have a common element?”; “Will it be possible to solve the problem of calculating some parameters in the class of paths intersection graphs on a grid even when the entire paths bend k times?”; “Is there any relationship among the classes of intersection graphs when we change the tree host to a grid host?”. The answers to these and other questions are considered in the next chapters of this thesis.

The text of this thesis is distributed over the next 5 chapters as follows.

Chapter 2 contains the definitions and concepts needed to fully understand this work. In addition, we provide a short overview of the problems studied and a brief literature review on the main subjects covered in the text.

Chapter 3 will be dedicated to the study of the Helly property and EPG graphs. In particular, the chapter presents an analysis of some basic EPG representations, a comparison of L -shaped paths and B_1 -EPG graph classes, as well as a proof of the NP -completeness of the Helly- B_1 -EPG graph recognition problem [17].

In Chapter 4, the parameters Helly number and strong Helly number will be studied for B_k -EPG and B_k -VPG graphs. We used the strategy of determining tight

lower and upper bounds to show the value of the Helly and strong Helly number parameters in each class and for each value of k .

Chapter 5 presents relationship among Chordal B_1 -EPG, VPT and EPT graphs. We show that if a graph G is a B_1 -EPG graph that is $\{S_3, S'_3, S''_3, C_4\}$ -free then G is Helly- B_1 EPG. We also show some non-trivial graph classes that are Helly- B_1 EPG, namely Bipartite, Blocks, Cactus, and Line of Bipartite. The main result of this chapter is proof that every Chordal B_1 -EPG graph is simultaneously in the VPT and EPT classes. The manuscript of this chapter and corresponding research was done while the author of this doctoral thesis was a doctoral research fellow at the National University of La Plata - UNLP, Math Department.

Chapter 5 contains other paper that has been submitted to the journal *Discussiones Mathematicae Graph Theory* (DMGT).

Chapter 6 is dedicated to discussing the results of this research and it includes the concluding remarks of this thesis with suggestions for future work.

The following are the manuscripts produced during this thesis:

1. BORNSTEIN, C. F.; GOLUBIC, M.C.; SANTOS, T. D.; SOUZA, U. S.; SZWARCFITER, J. L. The Complexity of Helly- B_1 -EPG graph Recognition. In: *Discrete Mathematics & Theoretical Computer Science (DMTCS)*, Source: oai:arXiv.org:1906.11185, June 4, 2020, vol. 22 no. 1.
2. BORNSTEIN, C. F.; MORGENSTERN, G.; SANTOS, T. D.; SOUZA, U. S.; SZWARCFITER, J. L. Helly and Strong Helly Numbers of B_k -EPG and B_k -VPG Graphs. To be submitted to a journal.
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2. BORNSTEIN, C. F.; SANTOS, T. D.; SOUZA, U. S.; SZWARCFITER, J. L. Sobre a Dificuldade de Reconhecimento de Grafos B_1 -EPG-Helly. In: XXXVIII Congresso da Sociedade Brasileira de Computação, 2018, Natal - RN. *Computação e Sustentabilidade*, 2018. p. 113-116.

3. BORNSTEIN, C. F.; SANTOS, T. D.; SOUZA, U. S.; SZWARCFITER, J. L. The complexity of B_1 -EPG-Helly graph recognition. In: VIII Latin American Workshop On Cliques in Graphs (LAWCG), ICM 2018 Satellite Event, 2018, Rio de Janeiro. Program and Abstracts, 2018. p. 69.
4. ALCON, L.; MAZZOLENI, M. P.; SANTOS, T. D. Identifying Subclasses of Helly- B_1 -EPG Graphs. 52nd Brazilian Operational Research Symposium (SBPO), 2020.
5. ALCON, L.; MAZZOLENI, M. P.; SANTOS, T. D. On Subclasses of Helly- B_1 -EPG Graphs. Reunión Anual de la Unión Matemática Argentina (virtUMA), 2020.
6. ALCON, L.; MAZZOLENI, M. P.; SANTOS, T. D. Paths on Hosts: B_1 -EPG, EPT and VPT Graphs. Submitted to: Latin American Workshop on Cliques in Graphs (LAWCG), 2020.

The results obtained in our research can be found in the set of manuscripts previously cited and in this doctoral thesis. For each one of the Chapters 3, 4 and 5 there is a brief introduction and a related paper.

Next, we present the basic concepts.

Chapter 2

Intersection graphs of paths on grid and trees

If you know the enemy and know yourself, you need not fear the result of a hundred battles. If you know yourself but not the enemy, for every victory gained you will also suffer a defeat. If you know neither the enemy nor yourself, you will succumb in every battle.

Sun Tzu, The Art of War

In this chapter, we will present some concepts that will facilitate the understanding of the studied problems. In particular, we describe the notations and we will illustrate with examples only those concepts and definitions that are outside the basic scope of graph theory. As a basic bibliography on graphs, algorithms, and NP-completeness we suggest reading [14] and [73] .

In this thesis, we will consider finite graphs, connected and simple, i.e. graphs without loops (edge connecting a vertex in itself) or more than one edge connecting two vertices. Thus, when we talk about graphs we will consider a simple, finite and connected graph unless something different is explicitly said.

Next, we describe the terminology and notation used in this work.

A *graph* G is a structure composed of two finite sets: $V(G)$ is a non-empty set whose elements are called *vertices*, and $E(G)$ is a set of unordered pairs of distinct elements taken from $V(G)$, which are called *edges*. An edge $e = (u, v) \in E(G)$ is formed by the pair of vertices $u, v \in V(G)$, in this case u and v are said to be *adjacent* vertices . We also say that e is an *incident edge* to u and v . We denote the *cardinality* of $|V(G)| = n$ and $|E(G)| = m$.

Given a vertex $v \in V(G)$, $N(v)$ and $N[v]$ represent the *open* and the *closed neighborhood* of v in G , respectively. For a subset $S \subseteq V(G)$, $G[S]$ is the subgraph of G induced by S . If \mathcal{F} is any family of graphs, we say that G is \mathcal{F} -free if G has no induced subgraph isomorphic to a member of \mathcal{F} .

Let u, v be vertices of G , if $N(u) = N(v)$ then u and v are said to be *false twins*, on the other hand, if $N[u] = N[v]$, then u and v are said *true twins*. The *degree* of a vertex v is denoted by $d(v)$ and corresponds to the number of vertices adjacent to v , i.e., the cardinality of $|N(v)|$. The *maximum degree* of a graph G is denoted by $\Delta(G) = \max\{d(v) \mid v \in V(G)\}$. Similarly, the *minimum degree* is denoted by $\delta(G) = \min\{d(v) \mid v \in V(G)\}$.

Given a graph G , and a vertex $v \in V(G)$, the graph $G \setminus \{v\}$ is obtained from G by removing the vertex v from its vertex set, and also removing all edges of $E(G)$ incident to v . Similarly, given an edge $e \in E(G)$, the graph $G \setminus \{e\}$ is obtained from G removing the edge e from $E(G)$.

We say that $G' = (V', E')$ is a *subgraph* of a graph $G = (V, E)$ when $V' \subseteq V$ and $E' \subseteq E$. When the subgraph G' contains all edges of E whose ends are contained in V' , then G' is the *induced subgraph* of G by V' .

A graph G is a *cycle*, denoted by C_n , if it is a sequence of vertices v_1, \dots, v_n, v_1 , where $v_i \neq v_j$ for $i \neq j$ and $(v_i, v_{i+1}) \in E(G)$, such that $n \geq 3$. For a cycle C_k , we say that it is an *even cycle* if k is even and an *odd cycle*, otherwise. We say that an edge e_{ij} is *between* two vertices v_i and v_j when e_{ij} is incident edge to v_i and v_j . A *chord* is an edge that is between two non-consecutive vertices in the sequence of vertices of a cycle. An *induced cycle* or *chordless cycle* is a cycle that has no chord. A graph that has no cycles is called *acyclic*. A graph G is *connected* if there is a path between any pair of vertices of G . A graph is a *tree* when it is acyclic and connected. A connected subgraph of a tree is called *subtree*.

Chordal graphs are the graphs where each induced cycle $C_n, n \geq 3$ has a chord.

A graph G formed by an induced cycle H plus a single universal vertex v connected to all vertices of H is called *wheel graph*. If the wheel has n vertices, it is denoted by n -wheel.

A *clique* is a set of pairwise adjacent vertices and an *independent set* is a set of pairwise non adjacent vertices.

The *k-sun graph* $S_k, k \geq 3$, consists of $2k$ vertices, an independent set $X = \{x_1, \dots, x_k\}$ and a clique $Y = \{y_1, \dots, y_k\}$, and edges set $E_1 \cup E_2$, where $E_1 = \{(x_1, y_1); (y_1, x_2); (x_2, y_2); (y_2, x_3); \dots, (x_k, y_k); (y_k, x_1)\}$ forms the outer cycle and $E_2 = \{(y_i, y_j) \mid i \neq j\}$ forms the inner clique.

A set \mathcal{S} is *maximal* in relation to a particular property P if \mathcal{S} satisfies P , and each set \mathcal{S}' containing properly \mathcal{S} does not satisfy P . In a similar way, a set \mathcal{S} is *minimal* in relation to a particular property P if \mathcal{S} satisfies P , and each subset \mathcal{S}'

that is properly contained in \mathcal{S} does not satisfy P .

A graph G is an *intersection graph* of a family of subsets of a set \mathcal{S} , when it is possible to associate each vertex $v \in V(G)$ to a subset $S_v \subseteq \mathcal{S}$, such that $S_u \cap S_v \neq \emptyset$ if and only if $(u, v) \in E(G)$. In this thesis, in particular, we will study four families of intersection graphs: the VPG, EPG, VPT and EPT graphs.

The term *grid* is used to denote the Euclidean space of integers orthogonal coordinates. Each pair of integers *coordinates* corresponds to a point or *vertex of the grid* (which by the context is not to be confused with the vertex of the graph). The term *grid edge* (which is also not to be confused with the edge of the graph), will be used to denote a pair of vertices that are at distance one in the grid. Two edges e_1 and e_2 are *consecutive edges* when they share exactly one point on the grid. A grid is the *host* on which we accommodate the VPG and EPG representations. When we refer to the VPT and EPT graphs, we implicitly know that the host of their representations is a tree.

A *path in the grid* is distinguished by two contexts, in the first we study families of subsets \mathcal{F} of edge of the grid. In this context a path in the grid is defined as a finite sequence of consecutive edges $e_1 = (v_1, v_2), e_2 = (v_2, v_3), \dots, e_i = (v_i, v_{i+1}), \dots, e_m = (v_m, v_{m+1})$, where $v_i \neq v_j$ for $i \neq j$. We call a collection of such paths an *EPG representation*, i.e., a collection of paths that represent a graph via its intersection graph (considering edge intersections). *EPG graphs* are the class of graphs that admit an EPG representation. In the second context, for vertex paths, we study families of subsets \mathcal{F} of vertex of the grid, and a path consists of a sequence of consecutive vertices of the grid v_1, v_2, \dots, v_k such that (v_i, v_{i+1}) is an edge of the grid, for all $i \in 1, \dots, k - 1$, where $v_i \neq v_j$ for $i \neq j$, and a collection of these paths forms a *VPG representation* and corresponds to a *VPG graph*.

The first and last edges of a path are called *extremity edges*. The *direction of an edge* is *vertical* when the first coordinate of its vertices is equal, and is *horizontal* when the second coordinate is equal. A *bend* in a path is a pair of consecutive edges e_1, e_2 of the path, such that the directions of e_1 and e_2 are different. When two edges e_1 and e_2 form a bend, they are called *bend edges*. A *segment* is a path without bend.

In the context of EPG graphs, we say that two paths are *edge-intersecting*, or simply *intersecting*, if these share at least one edge (of the grid).

EPG graphs are a class of intersection graphs of paths on a grid [46]. Shortly after came the VPG graphs, this class was introduced in 2011 [9] and [7]. These classes consist of graphs whose vertices can be represented by paths of a grid Q , such that two vertices of G are adjacent if and only if the corresponding paths intersect (in edges, if EPG graphs or in vertex, if VPG graphs). If every path in a representation can be represented with a maximum of k bends, we say that this

graph G has a B_k -EPG (resp. B_k -VPG) representation. When $k = 1$ we say that this is a *single bend* representation.

Let P be a family of paths on a host tree T . Two types of intersection graphs from the pair $\langle P, T \rangle$ are defined, namely VPT and EPT graphs. The *edge intersection graph* of P , $EPT(P)$, has vertices which correspond to the members of P , and two vertices are adjacent in $EPT(P)$ if and only if the corresponding paths in P share at least one edge in T . Similarly, the *vertex intersection graph* of P , $VPT(P)$, has vertices which correspond to the members of P , and two vertices are adjacent in $VPT(P)$ if and only if the corresponding paths in P share at least one vertex in T . VPT and EPT graphs are incomparable families of graphs. However, when the maximum degree of the host tree is restricted to three the family of VPT graphs coincides with the family of EPT graphs [41]. Also, it is known that any Chordal EPT graph is VPT (see [71]). Recall that it was shown that Chordal graphs are the vertex intersection graphs of subtrees of a tree [38].

Let \mathcal{F} be a family of subsets of some universal set U , and h an integer ≥ 1 . Say that \mathcal{F} is *h -intersecting* when every group of h sets of \mathcal{F} intersect. The *core* of \mathcal{F} is the intersection of all sets of \mathcal{F} , denoted $core(\mathcal{F})$.

The family \mathcal{F} is *h -Helly* when every h -intersecting subfamily \mathcal{F}' of it satisfies $core(\mathcal{F}') \neq \emptyset$, see e.g. [31]. On the other hand, if for every subfamily \mathcal{F}' of \mathcal{F} , there are h subsets whose core equals the core of \mathcal{F}' , then \mathcal{F} is said to be *strong h -Helly*. Clearly, if \mathcal{F} is h -Helly then it is h' -Helly, for $h' \geq h$. Similarly, if \mathcal{F} is strong h -Helly then it is strong h' -Helly, for $h' \geq h$.

Finally, the *Helly number* of the family \mathcal{F} is the least integer h , such that \mathcal{F} is h -Helly. Similarly, the *strong Helly number* of \mathcal{F} is the least h , for which \mathcal{F} is strong h -Helly. It also follows that the strong Helly number of \mathcal{F} is at least equal to its Helly number.

A *class* \mathcal{C} of families \mathcal{F} of subsets of some universal set U is a subcollection of the families \mathcal{F} of U . Say that \mathcal{C} is a *hereditary* class when it closed under inclusion. The *Helly number* of a class \mathcal{C} of families \mathcal{F} of subsets is the largest Helly number among the families \mathcal{F} . Similarly, the *strong Helly number* of a class \mathcal{C} is the largest strong Helly number of the families of \mathcal{C} .

If \mathcal{F} is a family of subsets and \mathcal{C} a class of families, denote by $H(\mathcal{F})$ and $H(\mathcal{C})$, the Helly numbers of \mathcal{F} and \mathcal{C} , respectively, while $sH(\mathcal{F})$ and $sH(\mathcal{C})$ represent the strong Helly numbers of \mathcal{F} and \mathcal{C} .

We say that a family of sets is *pairwise intersecting*, i.e. two by two intersecting if any two sets in the family intersect. A collection C of non-empty sets satisfies the Helly property, i.e. it is 2-Helly, when every subcollection pairwise intersecting S of C has at least one element that is in every subset of S .

For simplicity of notation, in this thesis when we refer to a family of sets as a

Helly family it is understood that this family is 2-Helly.

We say that a path P_i is a B_k -path if it contains at most k bends. Say that \mathcal{F} is a B_k -paths family, or simply a B_k -family, if each path of \mathcal{F} is a B_k -path.

In Boolean algebra, a *clause* is a disjunction or conjunction of literals. We say that a *formula* F is in the *Conjunctive Normal Form* (CNF) if F is a conjunction of clauses, where a clause is a disjunction of literals.

2.1 Related Works

In this section, we will present the main known results on the related study topics in this work, namely Helly property, EPG, VPG, EPT, and VPT graphs.

2.1.1 On the Helly property

The Helly property is named in honor of the Austrian mathematician Eduard Helly, who in 1923 proposed a famous theorem about the relationship of intersecting sets. Such a theorem motivates the so-called *Helly property* which can be stated as follows: given a collection of sets C , not empty, we say that this collection satisfies the Helly property when every subcollection of C that is pairwise intersecting has at least one element in common.

We can note that the Helly property is a topic that has instigated scientific research since it appeared, moreover, we can also mention recent works in the area of Graph Theory, see [11, 12, 28, 30, 47, 51, 64]. The study of the Helly property proves to be useful in the most diverse areas of science, of which one can enumerate applications in semantics, code theory, computational biology, database, image processing, graph theory, optimization, in problems of location and linear programming, [51]. In particular, in the area of Graph Theory, the Helly property has motivated the study of several graph classes, for example, we can cite the Clique-Helly graphs [30], Helly Circular-arc [66], Helly EPT [6], Disk-Helly [56] and Helly Hypergraphs [60].

In addition to the applications mentioned above, the Helly property can be studied on B_k -EPG representations, where each path is considered as a set of edges. A graph G has a Helly- B_k -EPG representation if there is a B_k -EPG representation of G where each path has at most k bends and the representation satisfies the Helly property. We will use the notation P_{v_i} to indicate the path corresponding to the vertex v_i . Figure 2.1(a) depicts two representations B_1 -EPG of a graph with 5 vertices. Figure 2.1(b) depicts pairwise intersecting paths $(P_{v_1}, P_{v_2}, P_{v_5})$, containing a common edge, so this is a Helly- B_1 -EPG representation. In Figure 2.1(c), although the 3 paths are pairwise intersecting, there is no edge common to the 3 paths simultaneously, and thus they do not satisfy the Helly property.

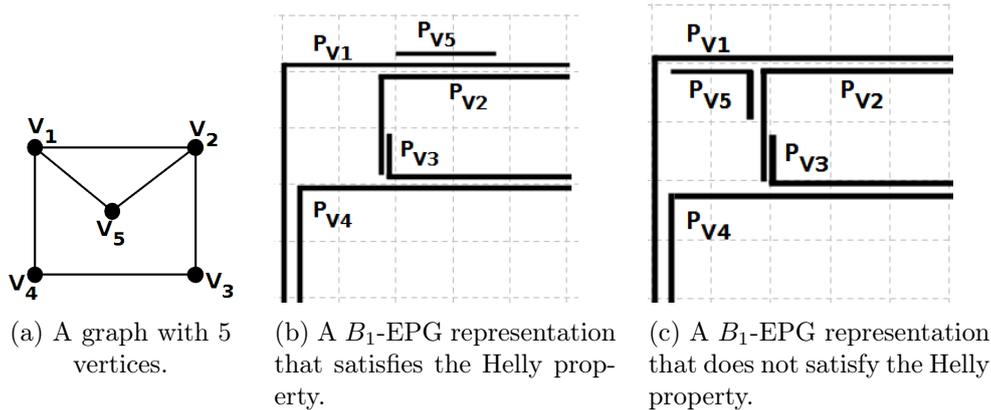


Figure 2.1: A graph with 5 vertices in (a) and some single bend representations: Helly in (b) and not Helly in (c).

In this thesis, we are interested in EPG representations of graphs that satisfy the Helly property. In particular, for the B_1 -EPG graphs, this directly implies that each clique has a special format, and the paths that compose it always share an edge of the representation in the grid, i.e. an edge-clique. Using this premise we were able to present Helly subfamilies for B_1 -EPG graphs and we also presented a hardness proof in recognizing this class of graphs. We will also study within the scope of this research the parameters Helly number and strong Helly number in paths on a grid.

2.1.2 On EPG graphs

A problem related to the study of EPG graphs is the problem of edge-intersection graphs of paths in a tree, well known in the literature as EPT (Edge-intersection Graphs of Paths in a Tree), see for instance [38, 43]. For EPT graphs, in particular, the value of the parameters Helly number, which is 2, and the strong Helly number, which is 3, are known results, also in [43]. The parameters Helly number and strong Helly number had been studied in EPT graphs when the set of paths satisfies the Helly property, see [62] and [63].

Regarding the complexity of the B_k -EPG graph recognition, only the hardness recognition of a few of these graph subclasses was determined. B_0 -EPG can be recognized in polynomial time, since these correspond to the interval graphs, see [16]. In contrast, the B_1 -EPG and B_2 -EPG graphs recognition are NP -complete problems, see [48, 61], and the B_1 -EPG graph recognition problem remains NP -complete even for L -shaped paths on a grid, see [21]. Moreover, in this doctoral thesis you will also find an NP -completeness proof for the Helly- B_1 -EPG graphs recognition in Chapter 3, and the same chapter we further studied the subsets of L -shapes and its relationship with B_1 -EPG and Helly- B_1 -EPG graphs.

In this work, we are going to study graphs that have a Helly-EPG representation

and related subjects. The Helly property related to EPG graph representations was studied by [46] and [47]. In particular, they determined the parameter strong Helly number of graphs B_1 -EPG. We determine two parameters to every class of EPG graphs, the Helly number and strong Helly number, these results are presents in Chapter 4.

The *bend number* of a graph G is the smallest k for which G is a B_k -EPG graph. Analogously, the bend number of a class of graphs is the smallest k for which all graphs in the class have a B_k -EPG representation. Interval graphs have bend number 0, trees have bend number 1, see [46], and outerplanar graphs have bend number 2, see [49]. The bend number for the class of planar graphs is still open, but according to [49], it is either 3 or 4.

Research about graphs of edge-intersection of paths on a grid is a relatively new topic in the area of Graph Theory. The first formal definitions of problems and applications were presented by Golubic in 2009 [46]. Since then, several branches of researches have been conducted by the scientific community. These questions often discuss the path representations, restrictions on the bend number in a representation, among others. A survey that summarizes the state-of-the-art for the topic of EPG graphs can be found at [25].

Next, we present some results regarding the *bend number* for some classes of graphs, among others.

In their study, ALCÓN *et al.* [4], the authors show that 3 bends are enough to represent all graphs in the class of circular-arc graphs, i.e. they are in B_3 -EPG. Additionally, they also show that there are circular-arc graphs that cannot be represented with 2 bends. Using the fact that we can to represent any circular-arc graph using only a rectangle of a grid of any size, the work defines the class of EPR graphs and classifies the normal circular-arc graphs as being B_2 -EPR, they also show that there are normal circular-arc graphs that are not B_1 -EPR. Finally, the work gives a characterization of B_1 -EPR graphs by a minimal family of forbidden induced subgraphs and shows that this subfamily corresponds to a subclass of normal Helly Circular-arc graphs.

In the paper of BIEDL and STERN [13], the authors show that 5 bends are enough to represent all planar graphs and that 3 bends are enough to represent all outerplanar graphs. These results are further improved by [49]. In addition to these results, the work shows that every Bipartite Planar graph has a B_2 -EPG representation and that every Line graph has a B_2 -EPG representation. In this thesis, we demonstrate that every Line of Bipartite graph is in Helly- B_1 EPG, these results are in Chapter 5.

HELDT *et al.* in [49] showed that 4 bends are enough to represent all planar graphs and present a linear algorithm to find this representation with 4 bends.

However, the authors still comment that for some planar graphs, 3 bends are often enough to construct the representation. In fact, it is not that simple the majority of planar graphs could be constructed with 4 bends, in fact, there are no known planar graphs that cannot be drawn using 3 bends. This leaves the question: if 4 bends are always enough to represent any planar graph, then are 4 bends really needed to represent any planar graph? That question is still open. The authors still conjecture that there is a graph where for any of its EPG representations there is always at least one path that needs to use the 4 bends.

The Table 2.1 presents the main known bounds for the *bend number*, denoted by $b(G)$, of some graph classes.

Table 2.1: Some graph classes and known bounds to their *bend number*.

Graph Class	$b(G)$	Reference
Interval graphs	0	[46]
Forests, Cycles	1	[47]
Outerplanar	2	[49]
Planar	$\in [3, 4]$	[49]
Bipartite Planar	2	[13]
Line Graph	2	[13]
$\text{dgn}(G) \stackrel{1}{\leq} k$	$2k - 1$	[49]
$\text{tw}(G) \stackrel{2}{\leq} k$	$2k - 2$	[49]
Degree $\leq \Delta$	$\in [\lceil \frac{\Delta}{2} \rceil, \Delta]$	[49]
Circular-arc	3	[4]
Normal Circular-arc	2	[4]
Halin graphs	2	[35]

In addition to the results cited for bounds on the bend number of some classes of graphs, there are many works that characterize other types of graphs not mentioned in this table, such that the work of RIES in [65] that characterizes the Chordal graphs claw-free, bull-free and diamond-free that have a B_1 -EPG representation. In that same article, there is also a characterization of some Split graphs, with a restriction on the size of the independent set or clique, by forbidden subgraphs. The work still has an interesting result that shows that the neighborhood of every vertex of a graph B_1 -EPG induces a graph that is Weakly Chordal. Implicitly this paper delimits a set of Helly- B_1 -EPG graphs, the bull-free graphs. Based on this fact in this thesis, we extend the results to delimit another Helly- B_1 -EPG subfamily, the diamond-free subfamily. This result can be found in Chapter 5.

Although it is possible to find several lines of researches on EPG graphs inves-

¹Degeneracy

²Treewidth

tigating the bend number, the interests of studies in this class of graphs extend to other classic problems, which we can mention to follow.

In COHEN *et al.* [26] a linear time recognition algorithm is presented for B_1 -EPG Cographs. The paper characterizes B_1 -EPG Cographs and B_0 -VPG Cographs by a family of forbidden induced subgraphs. The algorithm that the paper presents uses the Cotree of the Cograph in the recognition process.

Approximation Algorithms for coloring B_1 -EPG graphs were studied in [32]. The work cited shows that the coloring problem and the maximum independent set problem are both NP -complete for graphs B_1 -EPG even when the EPG representation is given. The authors present a 4-approximate algorithm that solves both problems, assuming that the EPG representation is given. The work still shows that the maximum clique can be found efficiently in graphs B_1 -EPG even when the representation is not given.

Clique coloring problems in B_1 -EPG graphs were studied by [15]. The authors consider the clique coloring problem and show that B_1 -EPG graphs are 4-clique-colorable and present a linear time algorithm to solve the problem. Moreover, given a B_1 -EPG representation of a graph, the paper provides a linear time algorithm that constructs a 4-clique coloring of it.

We can also mention as an often research with respect to EPG graphs the study of NP -hardness [49, 61], area of the grid necessary to represent a graph whose maximum degree is $\Delta(G)$ [8], and many others. The hardness of recognizing few classes of EPG graphs is known, and even for small k values only. Research with EPG graphs whose representations satisfy the Helly property is sparse. Thus, these topics and other similar topics prove to be interesting branches of research from a scientific point of view.

Finally, we mention that the B_k -EPG hierarchy is proper, i.e.,

$$B_0\text{-EPG} \subset B_1\text{-EPG} \subset B_2\text{-EPG} \subset \dots \subset B_{k-1}\text{-EPG} \subset B_k\text{-EPG} \subset B_{k+1}\text{-EPG}$$

this result is demonstrated by BIEDL and STERN [13] for even k and HELDT *et al.* [48] complete the result for all k . A correlated result is presented by ASINOWSKI and SUK [8] that proved that for any k , only a small fraction of all labeled graphs on n vertices are B_k -EPG.

2.1.3 On VPG graphs

VPG representations arise naturally when studying circuit layout problems and layout optimization where layouts are modeled as paths (wires) on grids. One approach to minimize the cost or difficulty of production involves minimizing the number of times that each path bend, see [10, 58, 69]. Other times layout may consist of several layers where the paths on each layer are not allowed to intersect. This is

naturally modeled as the coloring problem on the corresponding intersection graph, see [5].

A graph is a VPG if it is the vertex intersection graph of paths in a grid. A graph is called B_k -VPG if it has a B_k -VPG representation, i.e. if there is a representation where each path in this representation has at most k bends. VPG graphs were introduced in 2011 by ASINOWSKI *et al.* [9] and ASINOWSKI *et al.* [7]. They prove that VPG and String are the same graph class. However, it is known that recognizing String graphs is an NP -complete problem, by the results of [52, 67].

ASINOWSKI *et al.* [7] study B_0 -VPG graphs and observe that horizontal and vertical segments have strong Helly number 2 and that the clique problem has polynomial-time complexity, given the path representation. Among other results, they present proof that the recognition and coloring problems for B_0 -VPG graphs are NP -complete. Moreover, they give a 2-approximation algorithm for coloring B_0 -VPG graphs. Furthermore, they prove that triangle-free B_0 -VPG graphs are 4-colorable, and this is the best possible. In addition, they present a hierarchy of VPG graphs relating them to other known families of graphs, see Figure 2.2. The grid intersection graphs are shown to be equivalent to the bipartite B_0 -VPG graphs and the circle graphs are strictly contained in B_1 -VPG. They still prove the strict containment of B_0 -VPG into B_1 -VPG, and conjecture that, in general, this strict containment continues for all values of k . Finally, they present a graph that is not in B_1 -VPG.

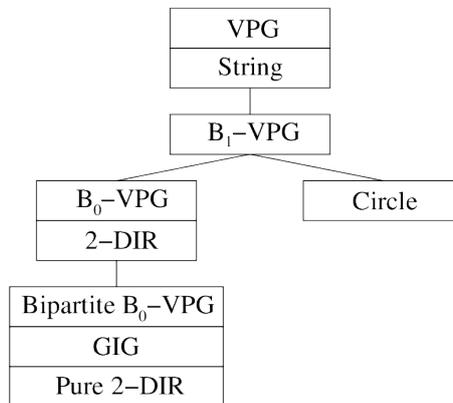


Figure 2.2: Relations between B_k -VPG graphs and well known graph classes [7].

It is known that all planar graphs are B_2 -VPG, see [22]. This paper also shows that the 4-connected planar graphs constitute a subclass of the intersection graphs of Z -shapes (i.e., a special case of B_2 -VPG). Additionally, they demonstrate that a B_2 -VPG representation of a planar graph can be constructed in polynomial time. They further show that the triangle-free planar graphs are contact graphs of L-shapes, Γ -shapes, vertical segments, and horizontal segments (i.e., a special case of contact B_1 -VPG).

Approximation algorithms for the maximum independent set problem over the class of B_1 -VPG graphs are presented by LAHIRI *et al.* [53]. Also, the NP-completeness of the decision version restricted to unit length equilateral B_1 -VPG graphs was established by them.

COHEN *et al.* [27] investigate the VPG graphs, and specifically the relationship between the bend number of a Cocomparability graph and the poset dimension of its complement. They show that the bend number of a Cocomparability graph G is at most the poset dimension of the complement of G minus one. Then, via Ramsey type arguments, they show that their upper bound is best possible.

In FELSNER *et al.* [34], the authors research the L-shapes representations for B_k -VPG graphs. The paper investigates several known subclasses of segment graphs (SEG-graphs), motivated mainly by research [57] that states that every $[\perp, \sqsupset]$ -shape is an SEG-graph. They show that these subclasses of SEG-graphs belong to $[\perp]$ -shapes, also that all Planar 3-trees, all Line graphs of Planar graphs, and all full subdivisions of Planar graphs are $[\perp]$ -shapes. Furthermore, FELSNER *et al.* [34] showed that the complement of Planar graphs is B_{17} -VPG graphs and complements of full subdivisions of the latter class are B_2 -VPG graphs.

In the paper of GOLUMBIC and RIES [42] certain subclasses of B_0 -VPG graphs have been characterized and showed to admit polynomial-time recognition. We can list these classes as Split, Chordal claw-free, and Chordal bull-free B_0 -VPG graphs. The B_0 -VPG Split graphs were characterized by a set of forbidden induced subgraphs.

In CHAPLICK *et al.* [23], they investigate B_0 -VPG graphs. Their paper describes a polynomial time algorithms for recognizing Chordal B_0 -VPG graphs, and for recognizing B_0 -VPG graphs that have representation on a grid with 2 rows and an arbitrary number of columns.

CHAPLICK *et al.* [24] show that for every fixed k , B_k -VPG \subsetneq B_{k+1} -VPG and that recognition of graphs from B_k -VPG is NP-complete even when the input graph is given by a B_{k+1} -VPG representation.

B_0 -VPG graphs restricted to Block graphs were studied by ALCÓN *et al.* [5]. Their research has given a characterization by an infinite family of minimal forbidden induced subgraph for B_0 -VPG Block graphs. Furthermore, the work provides an alternative recognition and representation algorithm for B_0 -VPG graphs also in the class of Block graphs.

In Chapter 4 we study the parameters Helly number and strong Helly number for B_k -VPG graphs. We determine the value of these parameters to $k = 0, 1, 2, 3$ and verify that they are unbounded for $k \geq 4$.

2.1.4 On EPT and VPT graphs

Models based on paths intersection may consider intersections by vertices or intersections by edges. Cases where the paths are hosted on a tree appear in [36, 39, 41]. Representations using paths on a grid were considered in [42, 46, 47].

EPT and VPT graphs have applications in communication networks, see [18] in [20]. Assume that we model a communication network as a tree T and the message routes to be delivered in this communication network as paths on T . Two paths conflict if they both require to use the same link (vertex). This conflict model is equivalent to an EPT (a VPT) graph. Suppose we try to find a schedule for the messages such that no two messages sharing a link (vertex) are scheduled in the same time interval. Then a vertex coloring of the EPT (VPT) graph corresponds to a feasible schedule on this network, [18] and [20].

Let P be a family of paths on a host tree T . Two types of intersection graphs from the pair $\langle P, T \rangle$ are defined, namely VPT and EPT graphs. The *edge intersection graph* of P , $EPT(P)$, has vertices which correspond to the members of P , and two vertices are adjacent in $EPT(P)$ if and only if the corresponding paths in P share at least one edge in T . Similarly, the *vertex intersection graph* of P , $VPT(P)$, has vertices which correspond to the members of P , and two vertices are adjacent in $VPT(P)$ if and only if the corresponding paths in P share at least one vertex in T .

VPT and EPT graphs are incomparable families of graphs. However, when the maximum degree of the host tree is restricted to three the family of VPT graphs coincide with the family of EPT graphs [41]. Also, it is known that any Chordal EPT graph is VPT, see [71]. Recall that it was shown that Chordal graphs are the vertex intersection graphs of subtrees of a tree [38].

Next, we list some research involving EPT and VPT graphs.

Although VPT graphs can be characterized by a fixed number of forbidden subgraphs, see [55], it is shown that EPT graphs recognition is an NP-complete problem, see [39]. Main optimization and decision problems such as recognition [36], the maximum clique [37], the minimum vertex coloring [40] and the maximum stable set problems [70] are polynomial-time solvable in VPT whereas recognition and minimum vertex coloring problems remain NP-complete in EPT graphs [41]. In contrast, we can solve in polynomial time the maximum clique, see [39], and the maximum stable set, see [74], problems in EPT graphs.

In ALCÓN *et al.* [1] we find a short paper that deals with EPT graphs. The paper defines the concept of satellite of a clique and we give us a necessary condition for the structure of cliques in EPT graphs based on satellites of cliques. In addition, the paper presents a finite family of minimal forbidden subgraphs for the EPT class.

Next, we will present the notation $[h, s, t]$ so that we can talk about some equiv-

alences known in the literature.

The class of graphs that have an $[h, s, t]$ -representation is denoted by $[h, s, t]$. A graph G has an $[h, s, t]$ -representation when h, s , and t are positive integers such that $h \geq s$, there is a host tree T with maximum degree $\Delta(T) \leq h$, there is a family of subtrees $S = \{S_u \subseteq T/u \in V(G)\}$ with $\Delta(S_u) \leq s$, and there is an edge $uv \in E(G)$ if and only if $|S_u \cap S_v| \geq t$.

In ALCÓN *et al.* [3] was studied a set of minimal forbidden induced subgraphs from VPT and their $[h, s, t]$ -representations. When there is no restriction on the maximum degree of T or on the maximum degree of the subtrees is used the notation $h = \infty$ and $s = \infty$, respectively. Therefore, $[\infty, \infty, 1]$ is the class of Chordal graphs and $[2, 2, 1]$ is the class of interval graphs. The classes $[\infty, 2, 1]$ and $[\infty, 2, 2]$ correspond to VPT and EPT respectively in [41]; and UV and UE, respectively in [59]. By taking $h = 3$ they obtain a characterization by minimal forbidden induced subgraphs of the class $\text{VPT} \cap \text{EPT} = \text{EPT} \cap \text{Chordal} = [3, 2, 2] = [3, 2, 1]$, see GOLUMBIC and JAMISON [41]. The paper also proved that the problem of deciding whether a given VPT graph belongs to $[h, 2, 1]$ is NP-complete even when restricted to the class $\text{VPT} \cap \text{Split}$ without dominated stable vertices, among other minor results.

Priscila Petito in her master thesis [62] researched UE graphs, UV graphs, and the Helly property. In particular, when it considers the UE family with Helly property its study leads to a new graph class denoted by UEH graph class. The master thesis also presents results to directed and rooted trees. Furthermore, the master thesis also considers the relationship among these classes in addition to others. In time, the work still considers the parameter strong Helly number in its scope. This doctoral thesis approaches a similar branch of research since we studied EPG and Helly graphs, the parameters Helly number and Strong Helly number, and also VPT and EPT (UV and UE respectively) graphs.

In Priscila Petito's doctoral thesis [63] UEH graphs were studied. The work presents a characterization by forbidden subgraphs that are simultaneously UEH and Split. Among the main problems addressed in the research are also the clique coloring problem in UEH graphs, the study of the complexity of the sandwich problem for the Clique-Helly class. In addition, the work also studies the inclusion relations among UE, UEH, and Clique-Helly classes.

Returning to $[h, s, t]$ notation, it is known that when the EPT graphs are restricted to host trees of vertex degree 3 this class corresponds precisely to the Chordal EPT graphs. In GOLUMBIC *et al.* [45] was proved an analogous result that Weakly Chordal EPT graphs are precisely the EPT graphs whose host tree restricted to degree 4. Moreover, they provide an algorithm to reduce a given EPT representation of a Weakly Chordal EPT graph to an EPT representation on a degree 4 tree. In

short, their proof state that $[4, 2, 2]$ graphs are equivalent to Weakly Chordal $[\infty, 2, 2]$ graphs. In addition, we know that when the maximum degree of the host tree T is 3, the coloring problem is polynomial, by [39]. The paper of [45] also shows the analogous polynomial result for a degree 4 host tree, thus the coloring problem on EPT graphs restricted to a host tree of vertex degree 4 is polynomial.

In GOLUMBIC *et al.* [44], the research presents equivalences and the complete hierarchy of intersection graphs of paths in a tree, this including VPT and EPT graphs, in particular orthodox- $[h, s, t]$ graphs with $s = 2$ and considering variations of h, t . For more information about orthodox- $[h, s, t]$ graphs we recommend reading JAMISON and MULDER [50] and PINTO [64].

Other researches still focus on variations of the EPT representations, such as [18] and [19]. These two articles represent the same research divided into two parts. Given a set of paths P , they define the graph $\text{ENPT}(P)$ of edge intersecting non-splitting paths of a tree, denoted by ENPT graph, as the graph having a vertex for each path in P , and an edge between every pair of vertices representing two paths that are both edge-intersecting and non-splitting. A graph G is an ENPT graph if there is a tree T and a set of paths P of T such that $G = \text{ENPT}(P)$. The papers investigate the basic properties of this class and proof that some graph classes belong to ENPT, such that Trees, Holes, Complete graphs, etc. Among the results, they show that the problem of finding such a representation is *NP*-Hard in general also for this class.

As we can see, EPT and VPT graphs have been extensively studied in the literature. With approaches that study from classic problems in these classes of graphs to variations of constructions and representations in those same classes. In this thesis, in particular, we will study the relationship of the VPT and EPT graphs with the EPG graphs.

In Chapter 5 we consider relationship between classes VPT, EPT and Chordal B_1 -EPG graphs.

In the next section, we present a table with the main notations used in the text.

2.2 Terminology

Table 2.2 describes the basic symbols and their meanings about graph theory. More specific definitions will be given in the next chapters as necessary.

In the following chapters, we will dedicate ourselves to expose the main results obtained by researching this thesis.

Table 2.2: Terms and basic symbols of Graph Theory used in this thesis.

Symbol	Description
$G = (V, E)$	Graph G with vertex set $V(G)$ and edge set $E(G)$.
$V(G)$	Vertex set of G .
$E(G)$	Edge set of G .
$n(G)$	Number of vertices in G .
$m(G)$	Number of edges in G .
v_i	Vertex v_i .
P_{v_i}	Path corresponding to the vertex v_i .
$e = (v_i, v_j)$	Edge e with endpoints v_i and v_j .
$d(v)$	Degree of vertex v .
$\delta(G)$	Minimum degree of a vertex in G .
$\Delta(G)$	Maximum degree of a vertex in G .
$N(v)$	Opened neighborhood of the vertex v .
$N[v]$	Closed neighborhood of the vertex v .
$G[S]$	Induced subgraph in G by subset of vertices S .
$ S $	Cardinality of set S .
$G \setminus \{v\}$	Subgraph obtained of G by removing the vertex v .
C_n	Induced Cycle with n vertices.
W_n	Wheel graph with n vertices.
$K_{r,s}$	Complete Bipartite graph with parts os size r and s .
K_n	Complete graph or clique with n vertices.
B_k -representation	Representation where each path has at most k bends.
$\langle P, T \rangle$	Set of paths P on a tree T .
$[h, s, t]$ -representation	Representation on a host tree of degree at most h of subtrees of degree at most s and intersection of lenght at least t .

Chapter 3

The Helly property and EPG graphs

*Genius is one percent inspiration,
ninety nine percent perspiration.*

Thomas Edison

In this chapter, after a brief introduction, the reader can find a complete version of the paper published in the journal DMTCS. We will examine the hierarchical relationships among some EPG and Helly-EPG classes. Besides, we will approach B_1 -EPG representations of some graphs that will be used later. First, let us focus our attention to understand how the classes B_0 -EPG, B_1 -EPG, Helly- B_1 EPG, and L -shaped paths are related, then we consider the B_1 -EPG representations of graphs C_4 and the Octahedral graph. Finally, we will present the proof of NP -completeness for the Helly- B_1 -EPG graph recognition problem.

3.1 Introduction

An EPG graph G is a graph that admits a representation in which its vertices are represented by paths of a grid Q , such that two vertices of G are adjacent if and only if the corresponding paths have at least one common edge.

The study of EPG graphs has motivation related to the problem of VLSI design that combines the notion of edge intersection graphs of paths in a tree with a VLSI grid layout model, see [46]. The number of bends in an integrated circuit may increase the layout area, and consequently, increase the cost of chip manufacturing. This is one of the main applications that instigate research on the EPG representations of some graph families when there are constraints on the number of bends in the paths used in the representation. Other applications and details on circuit layout problems can be found in [10, 58].

In this chapter, we study the Helly- B_k -EPG graphs. First, we show that every graph admits an EPG representation that is Helly, and present a characterization of Helly- B_1 -EPG representations. Besides, we relate Helly- B_1 -EPG graphs with L-shaped graphs, a natural family of subclasses of B_1 -EPG. Finally, we prove that recognizing Helly- B_k -EPG graphs is in NP, for every fixed k . Besides, we show that recognizing Helly- B_1 -EPG graphs is NP-complete, and it remains NP-complete even when restricted to 2-apex and 3-degenerate graphs. Other results found in the chapter are as follows: we show that every graph admits a Helly-EPG representation, and $\frac{\mu}{2n} - 1 \leq b_H(G) \leq \mu - 1$; and that Helly- B_k -EPG $\subsetneq B_k$ -EPG for each $k > 0$.

Next, we present the main paper that gave rise to this chapter.

3.2 Article published in the Discrete Mathematics & Theoretical Computer Science (DMTCS) journal.

The Complexity of Helly- B_1 -EPG graph Recognition*

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Golumbic, Lipshteyn, and Stern defined in 2009 the class of EPG graphs, the intersection graph class of edge paths on a grid. An EPG graph G is a graph that admits a representation where its vertices correspond to paths in a grid Q , such that two vertices of G are adjacent if and only if their corresponding paths in Q have a common edge. If the paths in the representation have at most k bends, we say that it is a B_k -EPG representation. A collection C of sets satisfies the Helly property when every sub-collection of C that is pairwise intersecting has at least one common element. In this paper, we show that given a graph G and an integer k , the problem of determining whether G admits a B_k -EPG representation whose edge-intersections of paths satisfy the Helly property, so-called Helly- B_k -EPG representation, is in NP, for every k bounded by a polynomial function of $|V(G)|$. Moreover, we show that the problem of recognizing Helly- B_1 -EPG graphs is NP-complete, and it remains NP-complete even when restricted to 2-apex and 3-degenerate graphs.

Keywords: paths, grid, EPG, Helly, intersection graphs, NP-completeness, single bend.

1 Introduction

An EPG graph G is a graph that admits a representation in which its vertices are represented by paths of a grid Q , such that two vertices of G are adjacent if and only if the corresponding paths have at least one common edge.

The study of EPG graphs has motivation related to the problem of VLSI design that combines the notion of edge intersection graphs of paths in a tree with a VLSI grid layout model, see Golumbic et al. (2009). The number of bends in an integrated circuit may increase the layout area, and consequently,

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increase the cost of chip manufacturing. This is one of the main applications that instigate research on the EPG representations of some graph families when there are constraints on the number of bends in the paths used in the representation. Other applications and details on circuit layout problems can be found in Bandy and Sarrafzadeh (1990); Molitor (1991).

A graph is a B_k -EPG graph if it admits a representation in which each path has at most k bends. As an example, Figure 1(a) shows a C_3 , Figure 1(b) shows an EPG representation where the paths have no bends and Figure 1(c) shows a representation with at most one bend per path. Consequently, C_3 is a B_0 -EPG graph. More generally, B_0 -EPG graphs coincide with interval graphs.

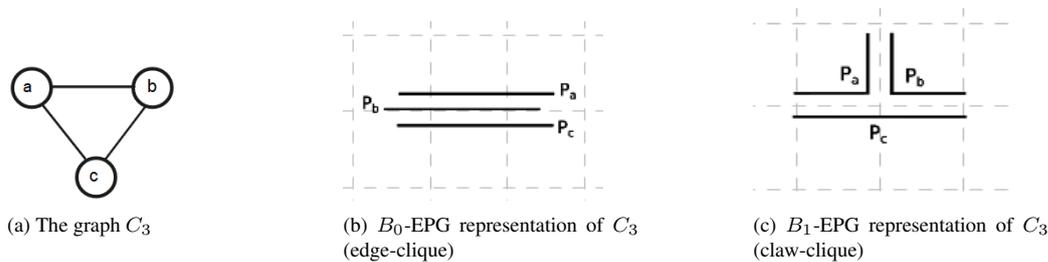


Fig. 1: The graph C_3 and representations without bends and with 1 bend

The *bend number* of a graph G is the smallest k for which G is a B_k -EPG graph. Analogously, the bend number of a class of graphs is the smallest k for which all graphs in the class have a B_k -EPG representation. Interval graphs have bend number 0, trees have bend number 1, see Golumbic et al. (2009), and outerplanar graphs have bend number 2, see Heldt et al. (2014a). The bend number for the class of planar graphs is still open, but according to Heldt et al. (2014a), it is either 3 or 4.

The class of EPG graphs has been studied in several papers, such as Alc3n et al. (2016); Asinowski and Suk (2009); Cohen et al. (2014); Golumbic et al. (2009); Heldt et al. (2014b); Pergel and Rzażewski (2017); Golumbic and Morgenstern (2019), among others. The investigations regarding EPG graphs frequently approach characterizations concerning the number of bends of the graph representations. Regarding the complexity of recognizing B_k -EPG graphs, only the complexity of recognizing a few of these sub-classes of EPG graphs have been determined: B_0 -EPG graphs can be recognized in polynomial time, since it corresponds to the class of interval graphs, see Booth and Lueker (1976); in contrast, recognizing B_1 -EPG and B_2 -EPG graphs are NP-complete problems, see Heldt et al. (2014b) and Pergel and Rzażewski (2017), respectively. Also, note that the paths in a B_1 -EPG representation have one of the following shapes: \perp , \lrcorner , \ulcorner and \llcorner . Cameron et al. (2016) showed that for each $S \subset \{\perp, \lrcorner, \ulcorner, \llcorner\}$, it is NP-complete to determine if a given graph G has a B_1 -EPG representation using only paths with shape in S .

A collection C of sets satisfies the Helly property when every sub-collection of C that is pairwise intersecting has at least one common element. The study of the Helly property is useful in diverse areas of science. We can enumerate applications in semantics, code theory, computational biology, database, image processing, graph theory, optimization, and linear programming, see Dourado et al. (2009).

The Helly property can also be applied to the B_k -EPG representation problem, where each path is considered a set of edges. A graph G has a Helly- B_k -EPG representation if there is a B_k -EPG representation of G where each path has at most k bends, and this representation satisfies the Helly property. Figure 2(a)

presents two B_1 -EPG representations of a graph with five vertices. Figure 2(b) illustrates 3 pairwise intersecting paths ($P_{v_1}, P_{v_2}, P_{v_5}$), containing a common edge, so it is a Helly- B_1 -EPG representation. In Figure 2(c), although the three paths are pairwise intersecting, there is no common edge in all three paths, and therefore they do not satisfy the Helly property.

The Helly property related to EPG representations of graphs has been studied in Golubic et al. (2009) and Golubic et al. (2013).

Let \mathcal{F} be a family of subsets of some universal set U , and $h \geq 2$ be an integer. Say that \mathcal{F} is h -*intersecting* when every group of h sets of \mathcal{F} intersect. The *core* of \mathcal{F} , denoted by $\text{core}(\mathcal{F})$, is the intersection of all sets of \mathcal{F} . The family \mathcal{F} is h -*Helly* when every h -intersecting subfamily \mathcal{F}' of \mathcal{F} satisfies $\text{core}(\mathcal{F}') \neq \emptyset$, see e.g. Duchet (1976). On the other hand, if for every subfamily \mathcal{F}' of \mathcal{F} , there are h subsets whose core equals the core of \mathcal{F}' , then \mathcal{F} is said to be *strong h -Helly*. Note that the Helly property that we will consider in this paper is precisely the property of being 2-Helly.

The *Helly number* of the family \mathcal{F} is the least integer h , such that \mathcal{F} is h -Helly. Similarly, the *strong Helly number* of \mathcal{F} is the least h , for which \mathcal{F} is strong h -Helly. It also follows that the strong Helly number of \mathcal{F} is at least equal to its Helly number. In Golubic et al. (2009) and Golubic et al. (2013), they have determined the strong Helly number of B_1 -EPG graphs.

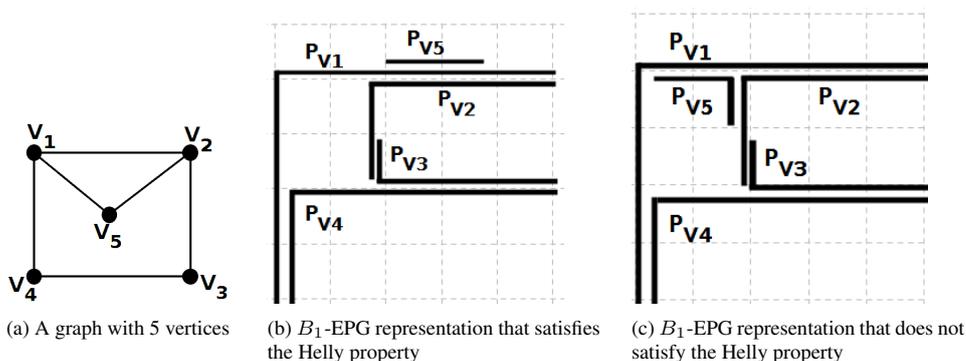


Fig. 2: A graph with 5 vertices in (a) and some single bend representations: Helly in (b) and not Helly in (c)

Next, we describe some terminology and notation.

The term *grid* is used to denote the Euclidean space of integer orthogonal coordinates. Each pair of integer coordinates corresponds to a *point* (or vertex) of the grid. The *size* of a grid is its number of points. The term *edge of the grid* will be used to denote a pair of vertices that are at a distance one in the grid. Two edges e_1 and e_2 are *consecutive edges* when they share exactly one point of the grid. A (simple) path in the grid is a sequence of distinct edges e_1, e_2, \dots, e_m , where consecutive edges are adjacent, i.e., contain a common vertex, whereas non-consecutive edges are not adjacent. In this context, two paths only intersect if they have at least a common edge. The first and last edges of a path are called *extremity edges*.

The *direction of an edge* is vertical when the first coordinates of its vertices are equal, and is horizontal when the second coordinates are equal. A *bend* in a path is a pair of consecutive edges e_1, e_2 of that path, such that the directions of e_1 and e_2 are different. When two edges e_1 and e_2 form a bend, they are called *bend edges*. A *segment* is a set of consecutive edges with no bends. Two paths are said to be *edge-intersecting*, or simply *intersecting* if they share at least one edge. Throughout the paper, any time

we say that two paths intersect, we mean that they edge-intersect. If every path in a representation of a graph G has at most k bends, we say that this graph G has a B_k -EPG representation. When $k = 1$ we say that this is a *single bend* representation.

In this paper, we study the Helly- B_k -EPG graphs. First, we show that every graph admits an EPG representation that is Helly, and present a characterization of Helly- B_1 -EPG representations. Besides, we relate Helly- B_1 -EPG graphs with L-shaped graphs, a natural family of subclasses of B_1 -EPG. Finally, we prove that recognizing Helly- B_k -EPG graphs is in NP, for every fixed k . Besides, we show that recognizing Helly- B_1 -EPG graphs is NP-complete, and it remains NP-complete even when restricted to 2-apex and 3-degenerate graphs.

The rest of the paper is organized as follows. In Section 2, we present some preliminary results, we show that every graph is a Helly-EPG graph, present a characterization of Helly- B_1 -EPG representations, and relate Helly- B_1 EPG with L-shaped graphs. In Section 3, we discuss the NP-membership of HELLY- B_k EPG RECOGNITION. In Section 4, we present the NP-completeness of recognizing Helly- B_1 -EPG graphs.

2 Preliminaries

The study starts with the following lemma.

Lemma 1 (Golumbic et al. (2009)). *Every graph is an EPG graph.*

We show that this result extends to Helly-EPG graphs.

Lemma 2. *Every graph is a Helly-EPG graph.*

Proof: Let G be a graph with n vertices v_1, v_2, \dots, v_n and μ maximal cliques C_1, C_2, \dots, C_μ . We construct a Helly-EPG representation of G using a $\mu + 1 \times \mu + 1$ grid Q . Each maximal clique C_i of G is mapped to an edge of Q as follow:

- if i is even then the maximal clique C_i is mapped to the edge in column i between rows i and $i + 1$;
- if i is odd then the maximal clique C_i is mapped to the edge in row i between columns i and $i + 1$.

The following describes a descendant-stair-shaped construction for the paths.

Let $v_l \in V(G)$ and C_i be the first maximal clique containing v_l according to the increasing order of their indices. If i is even (resp. odd) the path P_l starts in column i (resp. in row i), in the point (i, i) . Then P_l extends to at least the point $(i + 1, i)$ (resp. $(i, i + 1)$) proceeding to the until the row (resp. column) corresponding to next maximal clique of the sequence containing v_l , we say C_j . At this point, we bend P_l , which goes to the point (j, j) and repeat the process previously described. Figure 3 shows the Helly-EPG representation of the octahedral graph O_3 , according to the construction previously described.

By construction, each path travels only rows and columns corresponding with maximal cliques containing its respective vertex. And, every path crosses the edges of the grid to which your maximal cliques were mapped. Thus, the previously described construction results in an EPG representation of G , which is Helly since every set \mathcal{P} of paths representing a maximal clique has at least one edge in its core. \square

Definition 3. *The Helly-bend number of a graph G , denoted by $b_H(G)$, is the smallest k for which G is a Helly- B_k -EPG graph. Also, the bend number of a graph class \mathcal{C} is the smallest k for which all graphs in \mathcal{C} have a B_k -EPG representation.*

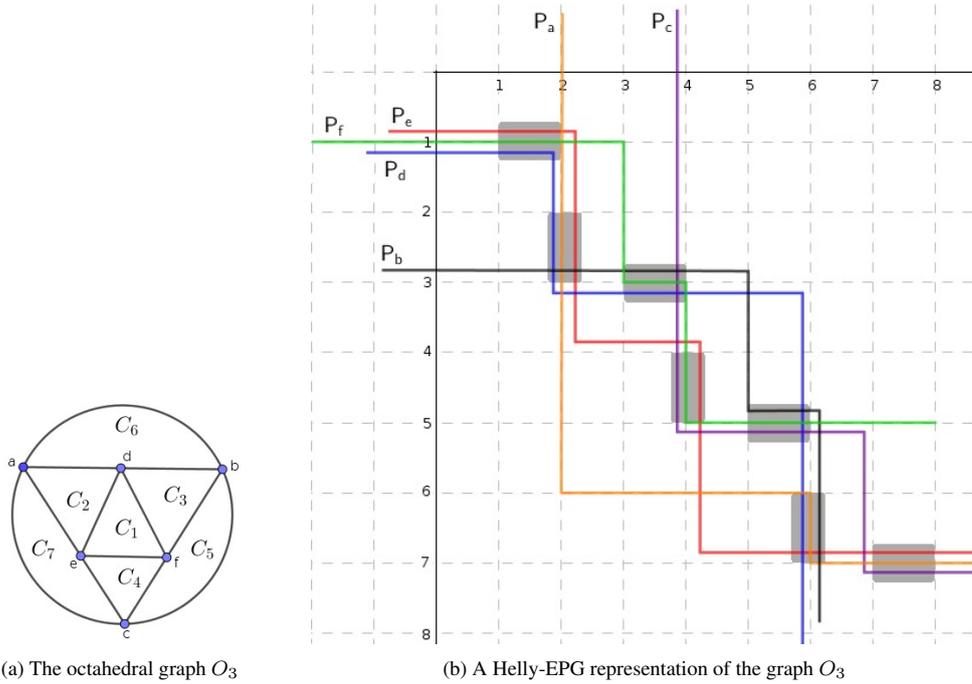


Fig. 3: Helly-EPG representation of the graph O_3 according to the construction of Lemma 2. The paths have been extended to the first/last row or column to improve the presentation.

Corollary 4. For every graph G containing μ maximal cliques, it holds that $b_H(G) \leq \mu - 1$.

Proof: From the construction presented in Lemma 2, it follows that any graph admits a Helly-EPG representation where its paths have a descendant-stair shape. Since the number of bends in such a stair-shaped path is the number of maximal cliques containing the represented vertex minus one, it holds that $b_H(G) \leq \mu - 1$ for any graph G . \square

Next, we examine the B_1 -EPG representations of a few graphs that we employ in our constructions.

Given an EPG representation of a graph G , for any grid edge e , the set of paths containing e is a clique in G ; such a clique is called an edge-clique. A claw in a grid consists of three grid edges meeting at a grid point. The set of paths that contain two of the three edges of a claw is a clique; such a clique is called a claw-clique, see Golubic et al. (2009). Fig. 1 illustrates an edge-clique and a claw-clique.

Lemma 5 (Golubic et al. (2009)). Consider a B_1 -EPG representation of a graph G . Every clique in G corresponds to either an edge-clique or a claw-clique.

Next, we present a characterization of Helly- B_1 -EPG representations.

Lemma 6. A B_1 -EPG representation of a graph G is Helly if and only if each clique of G is represented by an edge-clique, i.e., it does not contain any claw-clique.

Proof: Let R be a B_1 -EPG representation of a graph G . It is easy to see that if R has a claw-clique, it does not satisfy the Helly property. Now, suppose that R does not satisfy the Helly property. Thus it has a set \mathcal{P} of pairwise intersecting paths having no common edge. Note that the set \mathcal{P} represents a clique of G , and by Lemma 5, every clique in G corresponds to either an edge-clique or a claw-clique. Since \mathcal{P} represents a clique, but its paths have no common edge, then it has a claw-clique. \square

Now, we consider EPG representations of C_4 .

Definition 7. Let Q be a grid and let $(a_1, b), (a_2, b), (a_3, b), (a_4, b)$ be a 4-star as depicted in Figure 4(a). Let $\mathcal{P} = \{P_1, \dots, P_4\}$ be a collection of distinct paths each containing exactly two edges of the 4-star.

- A true pie is a representation where each P_i of \mathcal{P} forms a bend in b .
- A false pie is a representation where two of the paths P_i do not contain bends, while the remaining two do not share an edge.

Fig. 4 illustrates true pie and false pie representations of a C_4 .

Definition 8. Consider a rectangle of any size with 4 corners at points $(x_1, y_1); (x_2, y_1); (x_2, y_2); (x_1, y_2)$, positioned as in Fig. 5(a).

- A frame is a representation containing 4 paths $\mathcal{P} = \{P_1, \dots, P_4\}$, each having a bend in a different corner of a rectangle, and such that the sub-paths $P_1 \cap P_2, P_1 \cap P_3, P_2 \cap P_4, P_3 \cap P_4$ share at least one edge. While $P_1 \cap P_4$ and $P_2 \cap P_3$ are empty sets.
- A square-frame is a frame where P_1, P_2, P_3 and P_4 have respectively point of bend $(x_1, y_1), (x_2, y_1), (x_1, y_2)$ and (x_2, y_2) , and are of the shape \perp, \dashv, \lrcorner and \ulcorner . (see Fig.5)

Fig. 5 illustrates some frame representations of a C_4 .

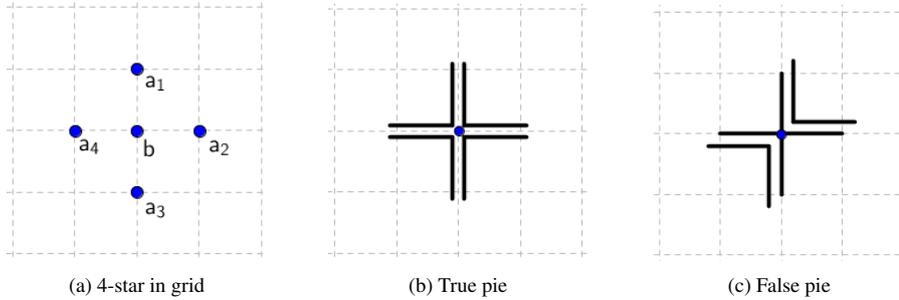


Fig. 4: B_1 -EPG representation of the induced cycle of size 4 as pies with emphasis in center b

Lemma 9 (Golumbic et al. (2009)). Every C_4 that is an induced subgraph of a graph G corresponds, in any representation, to a true pie, a false pie, or a frame.

The following is a claim of Heldt et al. (2014b) which a reasoning can be found in Asinowski and Suk (2009).

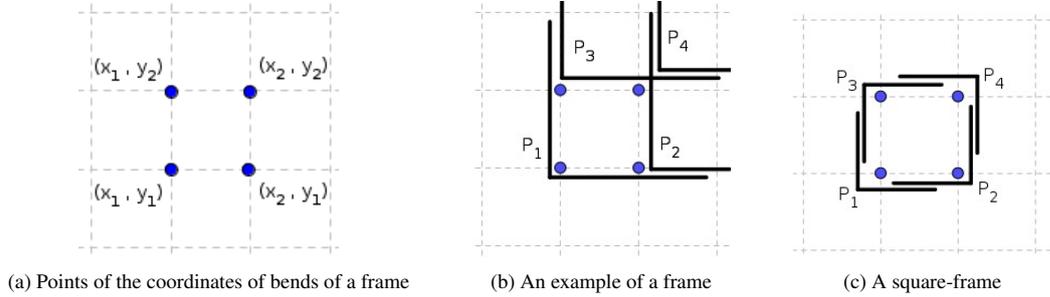


Fig. 5: B_1 -EPG representation of the induced cycle of size 4 as frame

Lemma 10 (Heldt et al. (2014a) and Asinowski and Suk (2009)). *In every single bend representation of a $K_{2,4}$, the path representing each vertex of the largest part has its bend in a false pie.*

By creating four $K_{2,4}$ and identifying a vertex of the largest part of each one to a distinct vertex of a C_4 , we construct the graph called bat graph (see Fig 6). Regarding to such a graph, the following holds.

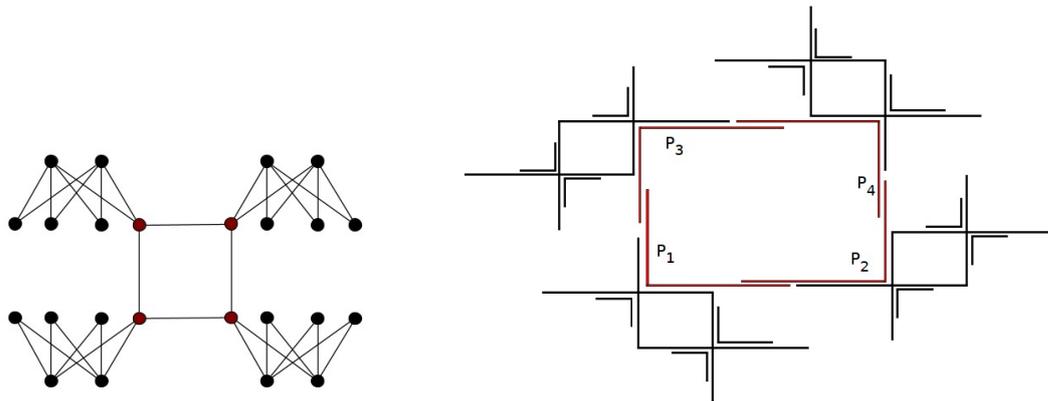


Fig. 6: A bat graph G and a Helly- B_1 -EPG representation of G .

Corollary 11. *In every single bend representation of the bat graph, G presented in Fig. 6, the C_4 that is a transversal of all $K_{2,4}$ is represented by a square-frame.*

Proof: By Lemma 10, it follows that in every single bend representation of the bat graph, each path representing a vertex of the C_4 (transversal to all $K_{2,4}$) has its bend in a false pie in which paths represent vertices of a $K_{2,4}$ (Fig. 7 illustrates a B_1 -EPG representation of a $K_{2,4}$). Thus, the intersection of two paths representing vertices of this C_4 does not contain any edge incident to a bend point of such paths, which implies that such a C_4 must be represented by a frame (see Lemma 9). Note that for each path of the frame, we have four possible shapes (\perp , \lrcorner , \ulcorner , and \top). Let P_1 be the path having the bottom-left bend point, P_2 be the path having the bottom-right bend point, P_3 be the path having the top-left bend point

and P_4 be the path having the top-right bend point. Note that to prevent P_2 and P_3 from containing edges incident at the bend point of P_1 , the only shape allowed for P_1 is \perp . Similarly, the only shape allowed for P_2 is \lrcorner as well as for P_3 is \ulcorner and for P_4 is \llcorner . Thus, the C_4 is represented by a square-frame. \square

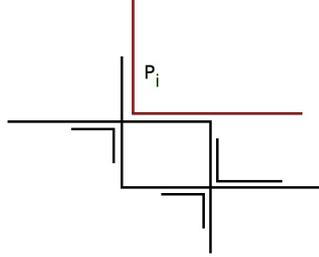


Fig. 7: Helly- B_1 -EPG representation of a $K_{2,4}$.

Definition 12. A B_k -EPG representation is minimal when its set of edges does not properly contain another B_k -EPG representation.

The octahedral graph is the graph containing 6 vertices and 12 edges, depicted in Figure 8(a). Next, we consider representations of the octahedral graph.

The next lemma follows directly from the discussion presented in Heldt et al. (2014b).

Lemma 13. Every minimal B_1 -EPG representation of the octahedral graph O_3 has the same shape.

Proof: Note that the octahedral graph O_3 has an induced C_4 such that the two vertices of the octahedral graph that are not in such a cycle are false twins whose neighborhood contains the vertices of the induced C_4 .

If in an EPG representation of the graph O_3 such a C_4 is represented as a frame, then no single bend path can simultaneously intersect the four paths representing the vertices of the induced C_4 . Therefore, we conclude that the frame structure cannot be used to represent such a C_4 in a B_1 -EPG representation of the O_3 . Now, take a B_1 -EPG representation of such a C_4 shaped as a true pie or false pie. By adding the paths representing the false twin vertices, which are neighbors of all vertices of the C_4 , in both cases (from a true or false pie), we obtain representations with the shape represented in Fig. 8(b). \square

2.1 Subclasses of B_1 -EPG graphs

By Lemma 13, every minimal B_1 -EPG representation of the octahedral graph O_3 has the same shape, as depicted in Fig. 8(b). Since in any representation of the graph O_3 there is always a triple of paths that do not satisfy the Helly property, paths P_a, P_b and P_c in the case of Fig. 8(b), it holds that $O_3 \notin$ Helly- B_1 EPG, which implies that the class of Helly- B_1 -EPG graphs is a proper subclass of B_1 -EPG.

Also, B_0 -EPG and Helly- B_0 -EPG graphs coincide. Hence, Helly- B_0 EPG can be recognized in polynomial time, see Booth and Lueker (1976).

In a B_1 -EPG representation of a graph, the paths can be of the following four shapes: \perp , \lrcorner , \ulcorner and \llcorner . Cameron et al. (2016) studied B_1 -EPG graphs whose paths on the grid belong to a proper subset of the

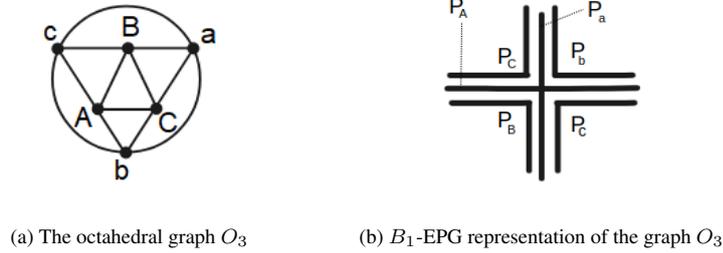


Fig. 8: The octahedral graph O_3 graph and its B_1 -EPG representation

four shapes. If S is a subset of $\{\lrcorner, \llcorner, \ulcorner, \urcorner\}$, then $[S]$ denotes the class of graphs that can be represented by paths whose shapes belong to S , where zero-bend paths are considered to be degenerate \lrcorner 's. They consider the natural subclasses of B_1 -EPG: $[\lrcorner]$, $[\lrcorner, \ulcorner]$, $[\lrcorner, \urcorner]$ and $[\lrcorner, \ulcorner, \urcorner]$, all other subsets are isomorphic to these up to 90 degree rotation. Cameron et al. (2016) showed that recognizing each of these classes is NP-complete.

The following shows how these classes relate to the class of Helly- B_1 -EPG graphs.

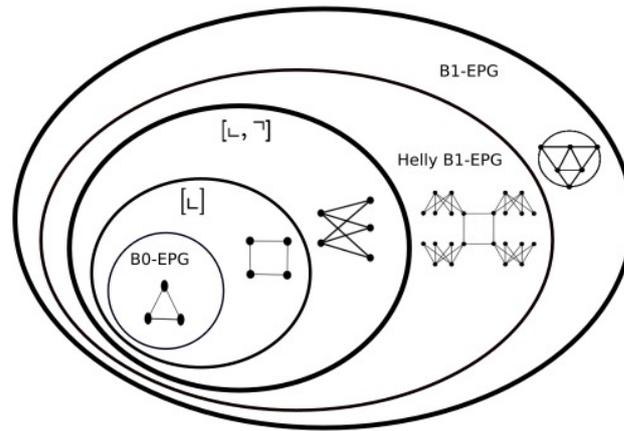


Fig. 9: Hierarchical diagram of some EPG classes

Theorem 14. $[\lrcorner] \subsetneq [\lrcorner, \urcorner] \subsetneq \text{Helly-}B_1 \text{ EPG}$, and $\text{Helly-}B_1 \text{ EPG}$ is incomparable with $[\lrcorner, \ulcorner]$ and $[\lrcorner, \ulcorner, \urcorner]$.

Proof: Cameron et al. (2016) showed that $[\lrcorner] \subsetneq [\lrcorner, \urcorner]$. Also, it is easy to see that \lrcorner 's and \urcorner 's cannot form a claw-clique, thus, by Lemma 6, it follows that $[\lrcorner, \urcorner] \subseteq \text{Helly-}B_1 \text{ EPG}$. In order to observe that $[\lrcorner, \urcorner]$ is a proper subclass of $\text{Helly-}B_1 \text{ EPG}$, it is enough to analyze the bat graph (see Fig. 6): by Corollary 11 follows that any B_1 -EPG representation of a bat graph contains a square-frame, thus it is not in $[\lrcorner, \urcorner]$. In addition, the bat graph is bipartite which implies that any B_1 -EPG representation of that graph does not contain claw-cliques and therefore is Helly.

Now, it remains to show that Helly- B_1 EPG is incomparable with $[\sqcup, \sqcap]$ and $[\sqcup, \sqcap, \sqsupset]$. Again, since any B_1 -EPG representation of a bat graph contains a square-frame, bat graph is a Helly- B_1 -EPG graph that is not in $[\sqcup, \sqcap, \sqsupset]$. On the other hand, the S_3 (3-sun) is a graph in $[\sqcup, \sqcap]$ such that any of its B_1 -EPG representations have a claw-clique, see Observation 7 in Cameron et al. (2016). Therefore, S_3 is a graph in $[\sqcup, \sqcap]$ that is not Helly- B_1 EPG. \square

Figure 9 depicts example of graphs of the classes B_0 -EPG, $[\sqcup]$, $[\sqcup, \sqsupset]$, Helly- B_1 EPG, and B_1 -EPG that distinguish these classes.

It is known that recognizing $[\sqcup]$, $[\sqcup, \sqsupset]$, and B_1 -EPG are NP-complete while recognizing B_0 -EPG and EPG graphs can be done in polynomial time (c.f. Booth and Lueker (1976), Heldt et al. (2014b), and Cameron et al. (2016)).

In this paper, we show that it is NP-complete to recognize Helly- B_1 -EPG graphs.

3 Membership in NP

The HELLY- B_k EPG RECOGNITION problem can be formally described as follows.

HELLY- B_k EPG RECOGNITION	
<i>Input:</i>	A graph G and an integer $k \leq V(G) ^c$, for some fixed c .
	Determine if there is a set of k -bend paths $\mathcal{P} = \{P_1, P_2, \dots, P_n\}$ in a grid Q such that:
<i>Goal:</i>	<ul style="list-style-type: none"> • $u, v \in V(G)$ are adjacent in G if and only if P_u, P_v share an edge in Q; and • \mathcal{P} satisfies the Helly property.

A (positive) certificate for the HELLY- B_k EPG RECOGNITION consists of a grid Q , a set \mathcal{P} of k -bend paths of Q , which is in one-to-one correspondence with the vertex set $V(G)$ of G , such that, for each pair of distinct paths $P_i, P_j \in \mathcal{P}$, $P_i \cap P_j \neq \emptyset$ if and only if the corresponding vertices are adjacent in G . Furthermore, \mathcal{P} satisfies the Helly property.

The following are key concepts that make it easier to control the size of an EPG representation. A *relevant edge* of a path in a B_k -EPG representation is either an extremity edge or a bend edge of the path. Note that each path with at most k bends can have up to $2(k+1)$ relevant edges, and any B_k -EPG representation contains at most $2|\mathcal{P}|(k+1)$ distinct relevant edges.

To show that there is a non-deterministic polynomial-time algorithm for HELLY- B_k EPG RECOGNITION, it is enough to consider as certificate a B_k -EPG representation R containing a collection \mathcal{P} of paths, $|\mathcal{P}| = |V(G)|$, such that each path $P_i \in \mathcal{P}$ is given by its set of relevant edges along with the relevant edges, that intersects P_i , of each path P_j intersecting P_i , where $P_j \in \mathcal{P}$. The relevant edges for each path are given in the order that they appear in the path, to make straightforward checking that the edges correspond to a unique path with at most k bends. This representation is also handy for checking that the paths form an intersection model for G .

To verify in polynomial time that the input is a positive certificate for the problem, we must assert the following:

- (i) The sequence of relevant edges of a path $P_i \in \mathcal{P}$ determines P_i in polynomial time;

- (ii) Two paths $P_i, P_j \in \mathcal{P}$ intersect if and only if they intersect in some relevant edge;
- (iii) The set \mathcal{P} of relevant edges satisfies the Helly property.

The following lemma states that condition (i) holds.

Lemma 15. *Each path P_i can be uniquely determined in polynomial time by the sequence of its relevant edges.*

Proof: Consider the sequence of relevant edges of some path $P_i \in \mathcal{P}$. Start from an extremity edge of P_i . Let t be the row (column) containing the last considered relevant edge. The next relevant edge e' in the sequence, must be also contained in row (column) t . If e' is an extremity edge, the process is finished, and the path has been determined. It contains all edges between the considered relevant edges in the sequence. Otherwise, if e' is a bend edge, the next relevant edge is the second bend edge e'' of this same bend, which is contained in some column (row) t' . The process continues until the second extremity edge of P_i is located.

With the above procedure, we can determine in $\mathcal{O}(k \cdot |V(G)|)$ time, whether path P_i contains any given edge of the grid Q . Therefore, the sequence of relevant edges of P_i uniquely determines P_i . \square

Next, we assert property (ii).

Lemma 16. *Let \mathcal{P} be the set of paths in a B_k -EPG representation of G , and let $P_1, P_2 \in \mathcal{P}$. Then P_1, P_2 are intersecting paths if and only if their intersection contains at least one relevant edge.*

Proof: Assume that P_1, P_2 are intersecting, and we show they contain a common relevant edge. Without loss of generality, suppose P_1, P_2 intersect at row i of the grid, in the B_k -EPG representation R . The following are the possible cases that may occur:

- **Case 1:** Neither P_1 nor P_2 contain bends in row i .
Then P_1 and P_2 are entirely contained in row i . Since they intersect, either P_1, P_2 overlap, or one of the paths contains the other. In any of these situations, they intersect in a common extremity edge, which is a relevant edge.
- **Case 2:** P_1 does not contain bends in i , but P_2 does.
If some bend edge of P_2 also belongs to P_1 , then P_1, P_2 intersect in a relevant edge. Otherwise, since P_1, P_2 intersect, the only possibility is that the intersection contains an extremity edge of P_1 or P_2 . Hence the paths intersect in a relevant edge.
- **Case 3:** Both P_1, P_2 contain bends in i
Again, if the intersection occurs in some bend edge of P_1 or P_2 , the lemma follows. Otherwise, the same situation as above must occur: P_1, P_2 must intersect in an extremity edge.

In any of the cases, P_1 and P_2 intersect in some relevant edge. \square

The two previous lemmas let us check that a certificate is an actual B_k -EPG representation of a given graph G . The next lemma says we can also verify in polynomial time that the representation encoded in the certificate is a Helly representation. Fortunately, we do not need to check every subset of intersecting paths of the representation to make sure they have a common intersection.

Lemma 17. *Let \mathcal{P} be a collection of paths encoded as a sequence of relevant edges that constitute a B_k -EPG representation of a graph G . We can verify in polynomial time if \mathcal{P} has the Helly property.*

Proof: Let T be the set of relevant edges of \mathcal{P} . Consider each triple T_i of edges of T . Let P_i be the set of paths of \mathcal{P} containing at least two of the edges in the triple T_i . By Gilmore's Theorem, see Berge and Duchet (1975), \mathcal{P} has the Helly property if and only if the subset of paths P_i corresponding to each triple T_i has a non-empty intersection. By Lemma 16, it suffices to examine the intersections on relevant edges. Therefore a polynomial algorithm for checking if \mathcal{P} has the Helly property could examine each of the subsets P_i , and for each relevant edge e of a path in P_i , to compute the number of paths in P_i that contain e . Then \mathcal{P} has the Helly property if and only if for every P_i , there exists some relevant edge that is present in all paths in P_i , yielding a non-empty intersection. \square

Corollary 18. *Let \mathcal{P}' be a set of pairwise intersecting paths in a Helly- B_k -EPG representation of a graph G . Then the intersection of all paths of \mathcal{P}' contains at least one relevant edge.*

Note that the property described in Corollary 18 is a consequence of Gilmore's Theorem, see Berge and Duchet (1975), and it applies only to representations that satisfy Helly's property.

From Corollary 18, the following theorem concerning the Helly-bend number of a graph holds.

Theorem 19. *For every graph G containing n vertices and μ maximal cliques, it holds that*

$$\frac{\mu}{2n} - 1 \leq b_H(G) \leq \mu - 1.$$

Proof: The upper bound follows from Corollary 4. For the lower bound first notice that each path with at most k bends can have up to $2(k+1)$ relevant edges, and any B_k -EPG representation with a set of paths \mathcal{P} contains at most $2|\mathcal{P}|(k+1)$ distinct relevant edges. Now, let G be a graph with n vertices, μ maximal cliques, and $b_H(G) = k$. From Corollary 18, it follows that in a Helly- B_k -EPG representation of G every maximal clique of G contains at least one relevant edge. By maximality, two distinct maximal cliques cannot share the same edge-clique. Thus, in a Helly- B_k -EPG representation of G every maximal clique of G contains at least one distinct relevant edge, which implies that $\mu \leq 2n(k+1)$, so $\frac{\mu}{2n} - 1 \leq b_H(G)$. \square

Lemma 20. *Let G be a (Helly-) B_k -EPG graph. Then G admits a (Helly-) B_k -EPG representation on a grid of size at most $4n(k+1) \times 4n(k+1)$.*

Proof: Let R be a B_k -EPG representation of a graph G on a grid Q with the smallest possible size. Let \mathcal{P} be the set of paths of R . Note that $|\mathcal{P}| = n$. A counting argument shows that there are at most $2|\mathcal{P}|(k+1)$ relevant edges in R . If Q has a pair of consecutive columns c_i, c_{i+1} neither of which contains relevant edges of R , and such that there is no relevant edge crossing from c_i to c_{i+1} , then we can contract each edge crossing from c_i to c_{i+1} into single vertices so as to obtain a new B_k -EPG representation of G on a smaller grid, which is a contradiction. An analogous argument can be applied to pairs of consecutive rows of the grid. Therefore the grid Q is such that each pair of consecutive columns and consecutive rows of Q has at least one relevant edge of R or contains a relevant edge crossing it. Since Q is the smallest possible grid for representing G , then the first row and the first column of Q must contain at least one point belonging to some relevant edge of R . Thus, if G is B_k -EPG then it admits a B_k -EPG representation on a grid of size at most $4|\mathcal{P}|(k+1) \times 4|\mathcal{P}|(k+1)$. Besides, by Corollary 18, it holds that the contraction operation previously described preserves the Helly property, if any. Hence, letting R be a Helly- B_k -EPG

representation of a graph G on a grid Q with the smallest possible size it holds that Q has size at most $4|\mathcal{P}|(k+1) \times 4|\mathcal{P}|(k+1)$. \square

Given a graph G with n vertices and an EPG representation R , it is easy to check in polynomial time with respect to $n + |R|$ whether R is a B_k -EPG representation of G . By Lemma 20, if G is a B_k -EPG graph then there is a positive certificate (an EPG representation) R of polynomial size with respect to $k + n$ to the question “ $G \in B_k$ -EPG?”. Therefore, Corollary 21 holds.

Corollary 21. *Given a graph G and an integer $k \geq 0$, the problem of determining whether G is a B_k -EPG graph is in NP, whenever k is bounded by a polynomial function of $|V(G)|$.*

At this point, we are ready to demonstrate the NP-membership of HELLY- B_k EPG RECOGNITION.

Theorem 22. HELLY- B_k EPG RECOGNITION is in NP.

Proof: By Lemma 20 and the fact that k is bounded by a polynomial function of $|V(G)|$, it follows that the collection \mathcal{P} can be encoded through its relevant edges with $n^{\mathcal{O}(1)}$ bits.

Finally, by Lemmas 15, 16 and 17, it follows that one can verify in polynomial-time in the size of G whether \mathcal{P} is a family of paths encoded as a sequence of relevant edges that constitute a Helly- B_k -EPG representation of a graph G . \square

4 NP-hardness

Now we will prove that HELLY- B_1 EPG RECOGNITION is NP-complete. For this proof, we follow the basic strategy described in the prior hardness proof of Heldt et al. (2014b). We set up a reduction from POSITIVE (1 IN 3)-3SAT defined as follows:

POSITIVE (1 IN 3)-3SAT	
<i>Input:</i>	A set X of positive variables; a collection C of clauses on X such that for each $c \in C$, $ c = 3$.
<i>Goal:</i>	Determine if there is an assignment of values to the variables in X so that every clause in C has exactly one true literal.

POSITIVE (1 IN 3)-3SAT is a well-known NP-complete problem (see Garey and Johnson (1979), problem [L04], page 259). Also, it remains NP-complete when the incidence graph of the input CNF (Conjunctive Normal Form) formula is planar, see Mulzer and Rote (2008).

Given a formula F that is an instance of POSITIVE (1 IN 3)-3SAT we will present a polynomial-time construction of a graph G_F such that $G_F \in \text{Helly-}B_1$ EPG if and only if F is satisfiable. This graph will contain an induced subgraph G_{C_i} with 12 vertices (called *clause gadget*) for every clause $C_i \in C$, and an induced subgraph (*variable gadget*) for each variable x_j , containing a special vertex v_j , plus a *base gadget* with 55 additional vertices.

We will use a graph H isomorphic to the graph presented in Figure 10, as a gadget to perform the proof. For each clause C_i of F of the target problem, we will have a *clause gadget* isomorphic to H , denoted by G_{C_i} .

The reduction of a formula F from POSITIVE (1 IN 3)-3SAT to a particular graph G_F (where G_F has a Helly- B_1 -EPG representation if only if F is satisfiable) is given below.

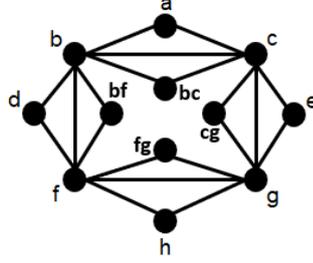


Fig. 10: The partial gadget graph H

Definition 23. Let F be a CNF-formula with variable set \mathcal{X} and clause set \mathcal{C} with no negative literals, in which every clause has exactly three literals. The graph G_F is constructed as follows:

1. For each clause $C_i \in \mathcal{C}$ create a clause gadget G_{C_i} , isomorphic to graph H ;
2. For each variable $x_j \in \mathcal{X}$ create a variable vertex v_j that is adjacent to the vertex a , e , or h of G_{C_i} , when x_j is the first, second or third variable in C_i , respectively;
3. For each variable vertex v_j , construct a variable gadget formed by adding two copies of H , H_1 and H_2 , and making v_j adjacent to the vertices of the triangles (a, b, c) in H_1 and H_2 .
4. Create a vertex V , that will be used as a vertical reference of the construction, and add an edge from V to each vertex d of a clause gadget;
5. Create a bipartite graph $K_{2,4}$ with a particular vertex T in the largest stable set. This vertex is nominated true vertex. Vertex T is adjacent to all v_j and also to V ;
6. Create two graphs isomorphic to H , G_{B_1} and G_{B_2} . The vertex T is connected to each vertex of the triangle (a, b, c) in G_{B_1} and G_{B_2} ;
7. Create two graphs isomorphic to H , G_{B_3} and G_{B_4} . The vertex V is connected to each vertex of the triangle (a, b, c) in G_{B_3} and G_{B_4} ;
8. The subgraph induced by the set of vertices $\{V(K_{2,4}) \cup \{T, V\} \cup V(G_{B_1}) \cup V(G_{B_2}) \cup V(G_{B_3}) \cup V(G_{B_4})\}$ will be referred to as the base gadget.

Figure 11 illustrates how this construction works on a small formula.

Lemma 24. Given a satisfiable instance F of POSITIVE (1 IN 3)-3SAT, the graph G_F constructed from F according to Definition 23 admits a Helly- B_1 -EPG representation.

Proof: We will use the true pie and false pie structures to represent the clause gadgets G_C (see Figure 12), but the construction could also be done with the frame structure without loss of generality.

The variable gadgets will be represented by structures as of Figure 13.

The base gadget will be represented by the structure of Figure 14.

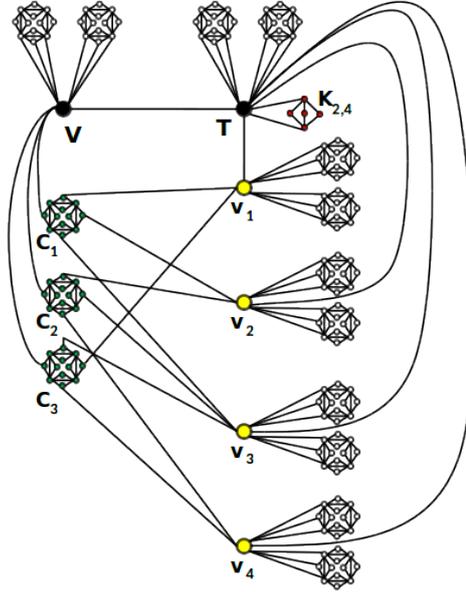


Fig. 11: The G_F graph corresponding to formula $F = (x_1 + x_2 + x_3) \cdot (x_2 + x_3 + x_4) \cdot (x_3 + x_1 + x_4)$

It is easy to see that the representations of the clause gadgets, variable gadgets, and base gadgets are all Helly- B_1 EPG. Now, we need to describe how these representations can be combined to construct a single bend representation R_{G_F} .

Given an assignment A that satisfies F , we can construct a Helly- B_1 -EPG representation R_{G_F} . First we will fix the representation structure of the base gadget in the grid to guide the single bend representation, see Figure 14. Next we will insert the variable gadgets with the following rule: if the variable x_i related to the path P_{v_i} had assignment *True*, then the adjacency between the path P_{v_i} with P_T is horizontal, and vertical otherwise. For example, for an assignment $A = \{x_1 = \text{False}; x_2 = \text{False}; x_3 = \text{True}; x_4 = \text{False}\}$ to variables of the formula F that generated the gadget G_F of Figure 11, it will give us a single bend representation (base gadget + variables gadget) according to the Figure 15(a).

When a formula F of POSITIVE (1-IN-3)-3SAT has clauses whose format of the assignment is $(\text{False}, \text{True}, \text{False})$ or $(\text{False}, \text{False}, \text{True})$ then we will use false pie to represent these clauses. When the clause has format $(\text{True}, \text{False}, \text{False})$, we will use true pie to represent this clause (the use of true pie in the last case is only to illustrate that the shape of the pie does not matter in the construction). To insert a *clause gadget* G_C , we introduce a horizontal line l_h in the grid between the horizontal rows used by the paths for the two false variables in C . Then we connect the path $P_{d_{c_i}}$ of G_{C_i} to P_V vertically using the bend of $P_{d_{c_i}}$. We introduce a vertical line l_v in the grid, between the vertical line of the grid used by P_V and the path to the true variable in C_i , i.e. between P_V and the path of the true variable $x_j \in C_i$. At the point where l_h and l_v cross, to insert the center of the *clause gadget* as can be seen in Figure 15(b). The complete construction of this single bend representation for the G_F can be seen in Figure 16.

Note that when we join all these representations of gadgets that form R_{G_F} , we do not increase the

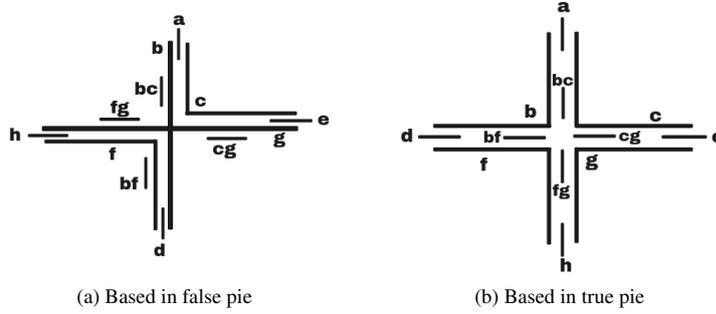


Fig. 12: Single bend representations of a clause gadget isomorphic to graph H



Fig. 13: Single bend representation of a variable gadget

number of bends. Then the representation necessarily is B_1 -EPG. Let us show that it satisfies the Helly property.

A simple way to check that R_{G_F} satisfies the Helly property is to note that the particular graph G_F never forms triangles between variable, clause, and base gadgets. Thus, any triangle of G_F is inside a variable, clause, or base gadget. As we only use Helly- B_1 -EPG representations of such gadgets, R_{G_F} is a Helly- B_1 -EPG representation of G_F . \square

Now, we consider the converse. Let R be a Helly- B_1 -EPG representation of G_F .

Definition 25. Let H be the graph shown in Figure 10, such that the 4-cycle $H[\{b, c, f, g\}]$ corresponds

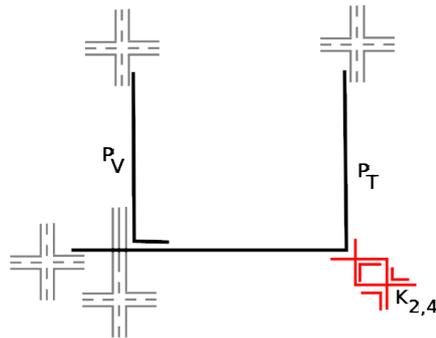


Fig. 14: Single bend representation of the base gadget

in R to a false pie or true pie, then:

- the center is the unique grid-point of this representation which is contained in every path representing 4-cycle $\{b, c, f, g\}$;
- a central ray is an edge-intersection between two of the paths corresponding to vertices b, c, f, g , respectively.

Note that every B_1 -EPG representation of a C_4 satisfies the Helly property, see Lemma 9, and triangles have B_1 -EPG representations that satisfy the Helly property, e.g. the one shown in Figure 1(b). The graph H is composed by a 4-cycle $C_4^H = H[b, c, f, g]$ and eight cycles of size 3.

As C_4^H has well known representations (see in Lemma 9), then we can start drawing the Helly- B_1 -EPG representation of H from these structures. Figure 17 shows possible representations for H .

If C_4^H is represented by a pie, then the paths P_b, P_c, P_f, P_g share the center of the representation. On the other hand, if C_4^H is represented by a frame, then the bends of the four paths correspond to the four distinct corners of a rectangle, i.e. all paths representing the vertices of C_4^H have distinct bend points, see Golubic et al. (2009).

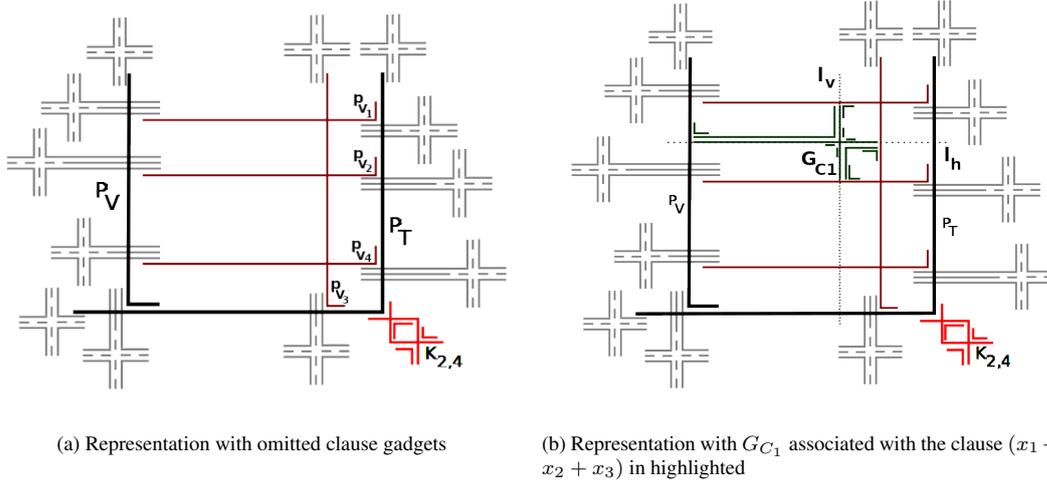


Fig. 15: Single bend representation of the base and variables gadgets associated with the assignment $x_1 = False, x_2 = False, x_3 = True, x_4 = False$

Next, we examine the use of the frame structure.

Proposition 26. *In a frame-shaped B_1 -EPG representation of a C_4 , every path P_i that represents a vertex of the C_4 intersects exactly two other paths P_{i-1} and P_{i+1} of the frame so that one of the intersections is horizontal and the other is vertical.*

Proposition 27. *Given a Helly- B_1 -EPG representation of a graph G that has an induced C_4 whose representation is frame-shaped. If there is a vertex v of G , outside the C_4 , that is adjacent to exactly two*

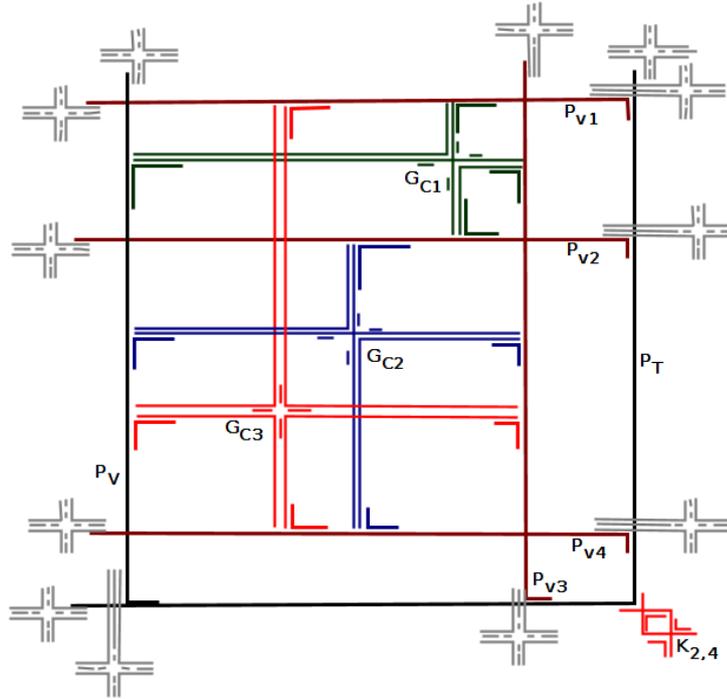


Fig. 16: Single bend representation of G_F

consecutive vertices of this C_4 , then the path representing v shares at least one common edge-intersection with the paths representing both of these vertices.

Proof: By assumption, G has a triangle containing v and two vertices of a C_4 . Therefore the path representing v shares at least one common edge intersecting with the paths representing these neighbors, otherwise the representation does not satisfy the Helly property. \square

By Proposition 26 and Proposition 27 we can conclude that for every vertex $v_i \in V(H)$ such that $v_i \neq V(C_4^H)$, when we use a frame to represent the C_4^H , P_{v_i} will have at least one common edge-intersection with the pair of paths representing its neighbors in H . Figure 17(c) presents a possible Helly- B_1 -EPG representation of H . Note that we can apply rotations and mirroring operations while maintaining it as a Helly- B_1 -EPG representation of H .

Definition 28. In a frame-shaped single bend representation of a C_4 graph, the paths that represent consecutive vertices in the C_4 are called consecutive paths and the segment that corresponds to the intersection between two consecutive paths is called side intersection.

Lemma 29. In any minimal single bend representation of a graph isomorphic to H , there are two paths in $\{P_a, P_e, P_d, P_h\}$ that have horizontal directions and the other two paths have vertical directions.

Proof: If the $C_4^H = [b, c, f, g]$ is represented by a true pie or false pie, then each path of C_4^H shares two central rays with two other paths of C_4^H , where each central ray corresponds to one pair of consecutive vertices in C_4^H .

As the vertices a, e, d and h are adjacent to pairs of consecutive vertices in C_4^H so the paths P_a, P_e, P_d and P_h have to be positioned in each one of the different central rays, 2 are horizontal and 2 are vertical.

If the C_4^H is represented by a frame, then each path of the C_4^H has a bend positioned in the corners of the frame. In the frame, the adjacency relationship of pairs of consecutive vertices in the C_4^H is represented by the edge-intersection of the paths that constitute the frame. Thus, since a frame has two parts in the vertical direction and two parts in the horizontal direction, then there are two paths in $\{P_a, P_e, P_d, P_h\}$ that have horizontal direction and two that have vertical direction.

Note that no additional edge is needed on the different paths by the minimality of the representation. \square

Corollary 30. *In any minimal single bend representation of a graph isomorphic to H , the following paths are on the same central ray or side intersection: P_a and P_{bc} ; P_e and P_{cg} ; P_h and P_{fg} ; P_d and P_{bf} .*

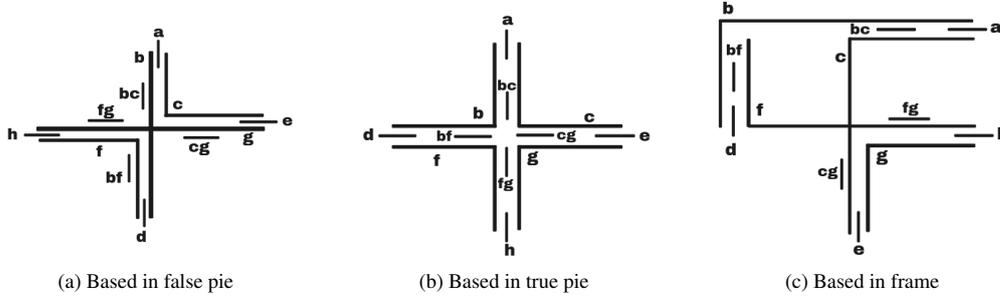


Fig. 17: Different single bend representations of the graph H using a false pie (a), a true pie (b) and a frame (c) for representing C_4^H

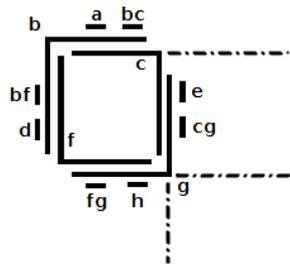


Fig. 18: A frame representation where the bend of dashed paths change directions

The following proposition helps us in the understanding of the NP-hardness proof.

Proposition 31. *In any Helly- B_1 representation of the graph G' , presented in Figure 19(a), the path P_x has obstructed extremities and bends.*

Proof: Consider G' consisting of a vertex x together with two graphs, H_1 and H_2 , isomorphic to H and a bipartite graph $K_{2,4}$, such that: x is a vertex of the largest stable set of the $K_{2,4}$; x is adjacent to an induced cycle of size 3 of H_1 , $C_3^{H_1}$ and to an induced cycle of size 3 of H_2 , $C_3^{H_2}$, see Figure 19(a).

We know that the paths belonging to the largest stable set of a $K_{2,4}$ always will bend into a false pie, see Fact 10. Since P_x is part of the largest stable set of the $K_{2,4}$, then P_x has an *obstructed bend*, see Figure 19(b).

The vertex x is adjacent to $C_3^{H_1}$ and $C_3^{H_2}$, so that its path P_x intersects the paths representing them. But in a single bend representations of a graph isomorphic to H there are pairs of paths that always are on some segment of a central ray or a side intersection, see Corollary 30, and the representation of $C_3^{H_1}$ (similarly $C_3^{H_2}$) has one these paths. Therefore, there is an edge in the set of paths that represent H_1 (similarly in H_2) that has a intersection of 3 paths representing $C_3^{H_1}$ (and $C_3^{H_2}$), otherwise the representation would not be Helly. There is another different edge in the same central ray or side intersection that contains three other paths and one of them is not in the set of paths $C_3^{H_1}$ (similarly $C_3^{H_2}$). Thus in a single bend representation of G' , the paths that represent $C_3^{H_1}$ (similarly $C_3^{H_2}$) must intersect in a bend edge or an extremity edge of P_x , because P_x intersects only one of the paths that are on some central ray or side intersection where $C_3^{H_1}$ (similarly $C_3^{H_2}$) is. As the bend of G' is already obstructed by structure of $K_{2,4}$, then H_1 (similarly in H_2) must be positioned at an extremity edge of P_x . This implies that P_x has a condition of *obstructed extremities*, see Figure 19(b). \square

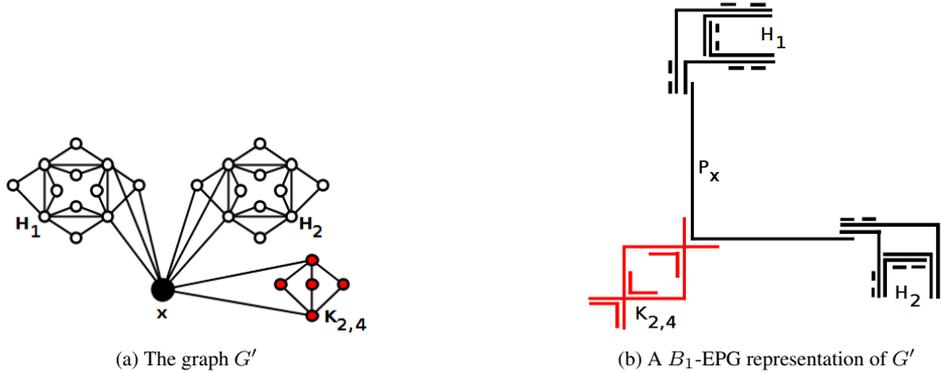


Fig. 19: The sample of obstructed extremities and bend.

Definition 32. We say that a segment s is internally contained in a path P_x if s is contained in P_x , and it does not intersect a relevant edge of P_x .

Some of the vertices of G_F have highly constrained B_1 -EPG representations. Vertex T has its bend and both extremities obstructed by its neighbors in G_{B1} , G_{B2} and in the $K_{2,4}$ subgraphs. Vertex V and each variable vertex v_i must have one of its segments internally contained in T , and also have its extremities and bends obstructed. Therefore, vertex V and each variable vertex has only one segment each that can be used in an EPG representation to make them adjacent to the clause gadget. The direction of this segment, being either horizontal or vertical, can be used to represent the true or false value for the variable. The clause gadgets, on the other hand, are such that exactly two of its adjacencies to the variable vertices and

V can be realized with a horizontal intersection, whereas the other two must be realized with a vertical intersection. If we consider the direction used by V as a truth assignment, we get that exactly one of the variables in each clause will be true in any possible representation of G_F . Conversely, it is fairly straightforward to obtain a B_1 -EPG representation for G_F when given a truth assignment for the formula F . Therefore, Lemma 33 holds.

Lemma 33. *If a graph G_F , constructed according to Definition 23, admits a Helly- B_1 -EPG representation, then the associated CNF-formula F is a yes-instance of POSITIVE (1 IN 3)-3SAT.*

Proof: Suppose that G_F has a Helly- B_1 -EPG representation, R_{G_F} . From R_{G_F} we will construct an assignment that satisfies F .

First, note that in every single bend representation of a $K_{2,4}$, the path of each vertex of the largest stable set, in particular, P_T (in R_{G_F}), has bends contained in a false pie (see Lemma 10).

The vertex T is adjacent to the vertices of a triangle of G_{B_1} and G_{B_2} . As the $K_{2,4}$ is positioned in the bend of P_T , then in R_{G_F} the representations of G_{B_1} and G_{B_2} are positioned at the extremities of P_T , see Proposition 4.3.

Without loss of generality assume that $P_V \cap P_T$ is a horizontal segment in R_{G_F} .

We can note in R_{G_F} that: the number of paths P_d with segment internally contained in P_V is the number of clauses in F ; the intersection between each P_a, P_e, P_h in the gadget clause and each path P_{v_j} indicates the variables composing the clause. Thus, we can assign to each variable x_j the value *True* if the edge intersecting P_{v_j} and P_T is horizontal, and *False* otherwise.

In Lemma 29 it was shown that any minimal B_1 -EPG representation of a clause gadget has two paths in $\{P_a, P_d, P_e, P_h\}$ with vertical direction and the other two paths have horizontal direction. Since P_d intersects P_V , it follows that in a single bend representation of G_F , we must connect two of these to represent a false assignment, and exactly one will represent a true assignment. Thus, from R_{G_F} , we construct an assignment to F such that every clause has exactly one variable with a true value. \square

Recall that a B_1 -EPG representation is Helly if and only if each clique is represented by an edge-clique (and not by a claw-clique). Thus, an alternative way to check whether a representation is Helly is to note that all cliques are represented as edge-cliques.

Theorem 34. HELLY- B_1 EPG RECOGNITION is NP-complete.

Proof: By Theorem 22, Lemma 24, Lemma 33. \square

We say that a k -apex graph is a graph that can be made planar by the removal of k vertices. A d -degenerate graph is a graph in which every subgraph has a vertex of degree at most d . Recall that POSITIVE (1 IN 3)-3SAT remains NP-complete when the incidence graph of the input formula is planar, see Mulzer and Rote (2008). Thus, the following corollary holds.

Corollary 35. HELLY- B_1 EPG RECOGNITION is NP-complete on 2-apex and 3-degenerate graphs.

Proof: To prove that G_F is 3-degenerate, we apply the d -degenerate graphs recognition algorithm, consisting of repeatedly removing the vertices of a minimum degree from the graph. Note that each vertex to be removed at each iteration of the algorithm always has a degree at most three, and therefore the graphs G_F constructed according to Definition 23 is 3-degenerate.

Now, recall that POSITIVE (1 IN 3)-3SAT remains NP-complete when the incidence graph of F is planar, see Mulzer and Rote (2008). Let F be an instance of PLANAR POSITIVE (1 IN 3)-3SAT, we

know that the incidence graph of the formula F is planar. By using the planar embedding of the incidence graph, we can appropriately replace the vertices representing variables and clauses by variables gadgets and clauses gadgets. As each variable gadget, clause gadget, and base gadget are planar, then something not planar may have arisen only from the intersection that was made between them. As the incidence graph assures that there is a planar arrangement between the intersections of the variable gadgets and clause gadgets, then from that one can construct a graph G_F such that the removal of V and T results into a planar graph, see Figura 20. Thus G_F is 2-apex. \square

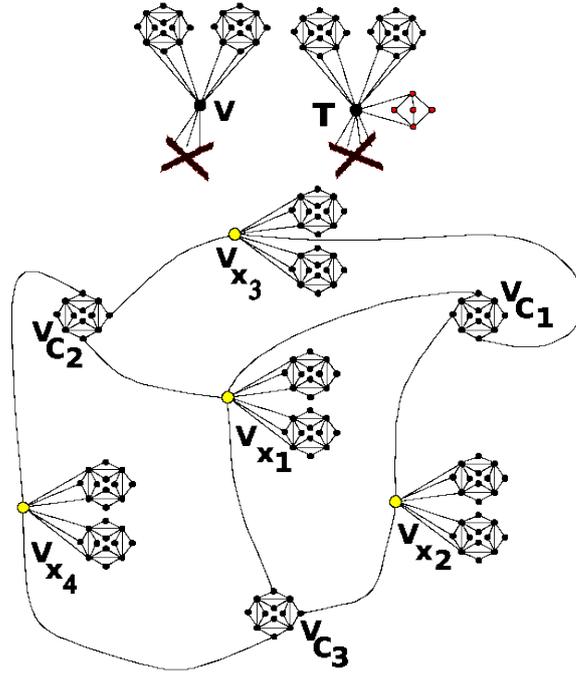


Fig. 20: Planar graph built from $F = (x_1 + x_2 + x_3) \cdot (x_1 + x_3 + x_4) \cdot (x_1 + x_2 + x_4)$, after removing V and T .

5 Concluding Remarks

In this paper, we show that every graph admits a Helly-EPG representation, and $\frac{\mu}{2r} - 1 \leq b_H(G) \leq \mu - 1$. Besides, we relate Helly- B_1 -EPG graphs with L-shaped graphs, a natural family of subclasses of B_1 -EPG. Also, we prove that recognizing (Helly-) B_k -EPG graphs is in NP, for every fixed k . Finally, we show that recognizing Helly- B_1 -EPG graphs is NP-complete, and it remains NP-complete even when restricted to 2-apex and 3-degenerate graphs.

Now, let r be a positive integer and let K_{2r}^- be the cocktail-party graph, i.e., a complete graph on $2r$ vertices with a perfect matching removed. Since K_{2r}^- has 2^r maximal cliques, by Theorem 19 follows that $\frac{2^r}{4r} - 1 \leq b_H(K_{2r}^-)$. This implies that, for each k , the graph $K_{2(k+5)}^-$ is not a Helly- B_k -EPG graph.

Therefore, as Pergel and Rzażewski (2017) showed that every cocktail-party graph is in B_2 -EPG, we conclude the following.

Lemma 36. *Helly- B_k -EPG $\subsetneq B_k$ -EPG for each $k > 0$.*

The previous lemma suggests asking about the complexity of recognizing Helly- B_k -EPG graphs for each $k > 1$. Also, it seems interesting to present characterizations for Helly- B_k -EPG representations similar to Lemma 6 (especially for $k = 2$) as well as considering the h -Helly- B_k EPG graphs. Regarding L-shaped graphs, it also seems interesting to analyse the classes Helly- $[\perp, \sqcap]$ and Helly- $[\perp, \sqsupset]$ (recall Theorem 14).

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Chapter 4

The Helly and Strong Helly numbers for B_k -EPG and B_k -VPG graphs

*Il y a quelque chose à compléter dans
cette démonstration. Je n'ai pas le
tems.*

Évariste Galois

In this chapter, we investigate two parameters in EPG and VPG graph classes. The parameters that will be studied are namely the Helly number and the strong Helly number. The parameter strong Helly number generalizes the parameter Helly number. Thus, by definition, the Helly number is a natural lower bound for the strong Helly number in any family of sets studied. In this chapter, we solve the problem of determining both the Helly and strong Helly numbers, for B_k -EPG, and B_k -VPG graphs, for each value k .

4.1 Introduction

EPG graphs were introduced by Golumbic, Lypshteyn, and Stern (2009) and consist of the intersection graphs of sets of paths on the orthogonal grid, whose intersections are taken considering the edges of the paths. If the intersections of the paths consider the vertices and not the edges, the resulting graph class is called VPG graphs. Such a class was introduced in 2011 [9] and [7]. In the present chapter, we study two graph parameters of both EPG and VPG graphs, namely the Helly number and the strong Helly number.

In this chapter, we study families of subsets \mathcal{F} of edge and vertex paths in a grid. For EPG graphs, the Helly number of B_0 -families is well known and is equal to 2, since B_0 -EPG graphs coincide with interval graphs. It is also simple to conclude

that the strong Helly number of B_0 -EPG graphs are also equal to 2. For $k = 1$, we prove that both the Helly number and the strong Helly number of the class of B_1 -families are equal to 3. For the class of B_2 -families, we prove that these two parameters are equal to 4. The Helly and strong Helly number for B_3 -families equal 8, and finally, these parameters are unbounded for $k \geq 4$.

As for VPG graphs, it is simple to verify that the Helly number of B_0 -VPG graphs equals 2, and we prove that B_1 -VPG graphs have Helly number 4, B_2 -VPG graphs have Helly number 6, B_3 -VPG graphs have Helly number 12, while the Helly number for B_4 -VPG graphs is again unbounded.

Finally, the strong Helly number equals the Helly number of B_k -EPG graphs, for each k . Similarly, for B_k -VPG graphs.

Following, we present all the results previously mentioned.

4.2 Manuscript on the Helly and Strong Helly numbers for B_k -EPG and B_k -VPG graphs

1 **HELLY AND STRONG HELLY NUMBERS OF B_K -EPG AND**
2 **B_K -VPG GRAPHS**

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19 **Abstract**

20 EPG graphs were introduced by Golumbic, Lypshteyn, and Stern (2009)
21 and consist of the intersection graphs of sets of paths on the orthogonal grid,
22 whose intersections are taken considering the edges of the paths. If the in-
23 tersections of the paths consider the vertices and not the edges, the resulting
24 graph class is called VPG graphs. A path P is a B_k -path if it contains at
25 most k bends. B_k -EPG and B_k -VPG graphs are the intersection graphs of
26 B_k -paths on the orthogonal grid, considering the intersection of edges and
27 vertices, respectively. A family \mathcal{F} is h -Helly when every h -intersecting sub-
28 family \mathcal{F}' of it satisfies $\text{core}(\mathcal{F}') \neq \emptyset$. If for every subfamily \mathcal{F}' of \mathcal{F} , there
29 are h subsets whose core equals the core of \mathcal{F}' , then \mathcal{F} is said to be strong
30 h -Helly. The Helly number of the family \mathcal{F} is the least integer h , such that

31 \mathcal{F} is h -Helly. Similarly, the strong Helly number of \mathcal{F} is the least h , for which
 32 \mathcal{F} is strong h -Helly. In this paper, we solve the problem of determining both
 33 the Helly and strong Helly numbers, for B_k -EPG, and B_k -VPG graphs, for
 34 each value k .

35 **Keywords:** EPG, VPG, path, grid, bend, Helly number, strong Helly.

36 **2010 Mathematics Subject Classification:** 05C62 - Graph representa-
 37 tions.

38 1. INTRODUCTION

39 EPG graphs were introduced by Golumbic, Lypshteyn, and Stern (2009) and
 40 consist of the intersection graphs of sets of paths on the orthogonal grid, whose
 41 intersections are taken considering the edges of the paths. If the intersections
 42 of the paths consider the vertices and not the edges, the resulting graph class
 43 is called VPG graphs. Such a class was introduced in 2011 [1] and [2]. In the
 44 present paper, we study two graph parameters of both EPG and VPG graphs,
 45 namely the Helly number and the strong Helly number.

46 Let \mathcal{F} be a family of subsets of some universal set U , and h an integer ≥ 1 .
 47 Say that \mathcal{F} is h -intersecting when every group of h sets of \mathcal{F} intersect. The *core*
 48 of \mathcal{F} is the intersection of all sets of \mathcal{F} , denoted $core(\mathcal{F})$.

49 The family \mathcal{F} is h -Helly when every h -intersecting subfamily \mathcal{F}' of it satisfies
 50 $core(\mathcal{F}') \neq \emptyset$, see e.g. [4]. On the other hand, if for every subfamily \mathcal{F}' of \mathcal{F} ,
 51 there are h subsets whose core equals the core of \mathcal{F}' , then \mathcal{F} is said to be *strong*
 52 h -Helly. Clearly, if \mathcal{F} is h -Helly then it is h' -Helly, for $h' \geq h$. Similarly, if \mathcal{F} is
 53 strong h -Helly then it is strong h' -Helly, for $h' \geq h$.

54 Finally, the *Helly number* of the family \mathcal{F} is the least integer h , such that \mathcal{F}
 55 is h -Helly. Similarly, the *strong Helly number* of \mathcal{F} is the least h , for which \mathcal{F} is
 56 strong h -Helly. It also follows that the strong Helly number of \mathcal{F} is at least equal
 57 to its Helly number.

58 A *class* \mathcal{C} of families \mathcal{F} of subsets of some universal set U is a subcollection
 59 of the families \mathcal{F} of U . Say that \mathcal{C} is a *hereditary* class when it closed under
 60 inclusion. The *Helly number* of a class \mathcal{C} of families \mathcal{F} of subsets is the largest
 61 Helly number among the families \mathcal{F} . Similarly, the *strong Helly number* of a class
 62 \mathcal{C} is the largest strong Helly number of the families of \mathcal{C} .

63 If \mathcal{F} is a family of subsets and \mathcal{C} a class of families, denote by $H(\mathcal{F})$ and $H(\mathcal{C})$,
 64 the Helly numbers of \mathcal{F} and \mathcal{C} , respectively, while $sH(\mathcal{F})$ and $sH(\mathcal{C})$ represent
 65 the strong Helly numbers of \mathcal{F} and \mathcal{C} .

66 In this work, we study families of subsets \mathcal{F} of edge and vertex paths in a
 67 grid. In the context of edge paths, a path consists of a sequence of consecutive

68 edges in the orthogonal grid. We call a collection of such paths an *EPG representation*,
 69 i.e., a collection of paths that represent a graph via its intersection graph
 70 (considering edge intersections). *EPG graphs* are the class of graphs that admit
 71 an EPG representation. Similarly, for vertex paths, a path consists of a sequence
 72 of consecutive vertices of the orthogonal grid and a collection of these paths form
 73 a *VPG representation* and correspond to a *VPG graph*.

74 Each edge has an associated direction in the grid, which can be either hor-
 75 izontal or vertical. A *bend* in a path is a pair of consecutive edges that have
 76 different directions. A *segment* of a path is a sequence of consecutive edges of
 77 the path, with no bends. Say that a path P_i is a B_k -*path* if it contains at most k
 78 bends. Say that \mathcal{F} is a B_k -*paths family*, or simply a B_k -*family*, if each path of \mathcal{F}
 79 is a B_k -*path*.

80 In this paper, we solve the problem for determining the Helly and strong
 81 Helly numbers, for both B_k -EPG and B_k -VPG graphs, for each value k .

82 For EPG graphs, the Helly number of B_0 -families is well known and is equal
 83 to 2, since B_0 -EPG graphs coincide with interval graphs. It is also simple to
 84 conclude that the strong Helly number of B_0 -EPG graphs are also equal to 2.
 85 For $k = 1$, we prove that both the Helly number and the strong Helly number
 86 of the class of B_1 -families are equal to 3. For the class of B_2 -families, we prove
 87 that these two parameters are equal to 4. The Helly and strong Helly number
 88 for B_3 -families equal 8, and finally, these parameters are unbounded for $k \geq 4$.

89 As for VPG graphs, it is simple to verify that the Helly number of B_0 -VPG
 90 graphs equals 2, and we prove that B_1 -VPG have Helly number 4, B_2 -VPG graphs
 91 have Helly number 6, B_3 -VPG has Helly number 12, while the Helly number for
 92 B_4 -VPG graphs is again unbounded.

93 Finally, the strong Helly number equals the Helly number of B_k -EPG graphs,
 94 for each k . Similarly, for B_k -VPG graphs.

95 As for existing results, Golumbic, Lipshteyn, and Stern [9] have already
 96 shown that the strong Helly number for B_1 -EPG graphs equal 3, and for B_1 -VPG
 97 graphs is equal to 4. employing a different proof technique. See [11], Theorem
 98 11.13, below:

99 **Theorem 1.** [11] *Let P be a collection of single bend paths on a grid. If every*
 100 *two paths in P share at least one grid-edge, then P has strong Helly number 3.*
 101 *Otherwise, P has strong Helly number 4.*

102 No other results concerning the strong Helly number, or no results for the
 103 Helly number of B_k -EPG graphs seem to have been reported in the literature.
 104 As for other classes, Golumbic and Jamison have determined the strong Helly
 105 number of the intersection of edge paths of a tree [8]. Finally, Asinowski, Cohen,
 106 Golumbic, Limouzy, Lipshteyn, and Stern have reported that the strong Helly
 107 number of B_0 -VPG graphs equals two [1].

108 Deciding whether a given hypergraph is k -Helly can be done in polynomial
 109 time for fixed k , employing the characterization by Berge and Duchet [3]. For
 110 arbitrary k , the problem is co-NP-complete [7]. For the corresponding problems
 111 for strong k -Helly see [6, 7].

112 The paper is organized as follows. Section 2 contains some preliminary propo-
 113 sitions and further notation. Section 3 describes the results for the Helly number
 114 of B_k -EPG graphs, while Section 4 contains the results of this parameter for B_k -
 115 VPG graphs. The strong Helly number is considered in Section 5. Final remarks
 116 are presented in the last section.

117 2. PRELIMINARIES

118 The following theorem characterizes h -Helly families of subsets.

119 **Theorem 2.** ([3]): *A family \mathcal{F} of subsets of the universal set U is h -Helly if
 120 and only if for every subset $U' \subseteq U$, $|U'| = h + 1$, the subfamily \mathcal{F}' of \mathcal{F} , formed
 121 by the subsets containing at least h of the $h + 1$ elements of U' , has a non-empty
 122 core.*

123 The next theorem is central to our results.

124 **Theorem 3.** *Let \mathcal{C} be a hereditary class of families \mathcal{F} of subsets of the universal
 125 set U , whose Helly number $H(\mathcal{C})$ equals h . Then there exists a family $\mathcal{F}' \in \mathcal{C}$
 126 with exactly h subsets, satisfying the following condition:*

*For each subset $P_i \in \mathcal{F}'$, there is exactly one distinct element $u_i \in U$, such
 that*

$$u_i \notin P_i,$$

but u_i is contained in all subsets

$$P_j \in \mathcal{F}' \setminus P_i.$$

127 **Proof:** Let \mathcal{C} be a class of families \mathcal{F} of subsets P , each subset formed by
 128 elements $u \in U$, such that the Helly number $H(\mathcal{C})$ equals h . Then each family
 129 $\mathcal{F} \in \mathcal{C}$ satisfies $H(\mathcal{F}) \leq h$. Consider a family $\mathcal{F}' \in \mathcal{C}$ whose Helly number
 130 is exactly h , and containing exactly h subsets. Such a family must exist since
 131 \mathcal{C} is hereditary. Since $H(\mathcal{F}') = h$, \mathcal{F}' is h -intersecting, and therefore $(h - 1)$ -
 132 intersecting. Furthermore, \mathcal{F}' is not $(h - 1)$ -Helly. Applying Theorem 2, we
 133 conclude that there are h elements $U' = \{u_1, \dots, u_h\} \subset U$, such that each set of
 134 \mathcal{F}' contains at least $h - 1$ elements of U' . Since $H(\mathcal{F}') > h - 1$, $core(\mathcal{F}') = \emptyset$ and
 135 therefore there is no common element among the sets of \mathcal{F}' . In particular, since
 136 each set $P_i \in \mathcal{F}'$ contains at least $h - 1$ elements of U' , and $core(\mathcal{F}') = \emptyset$, we

137 can choose h subsets P_i , in which each of them misses a distinct element $u_i \in U'$.
 138 Then for each subset $P_i \in \mathcal{F}$, there exists some element $u_i \notin P_i$, but $u_i \in P_j$, for
 139 all $P_j \in \mathcal{F}'$, $j \neq i$. \square

140 Let \mathcal{F}' be as in the previous theorem. It is simple to conclude that the
 141 removal of any subset from \mathcal{F}' makes it an $(h - 1)$ -Helly family. Therefore we call
 142 \mathcal{F}' a *minimal non- $(h - 1)$ -Helly family*. Moreover, the element $u_i \notin P_i$, contained
 143 in all subsets $P_j \in \mathcal{F}' \setminus P_i$, except P_i , is the *h -non-representative* of P_i .

144 We can apply this notion of minimal families of subsets for the B_k -EPG and
 145 B_k -VPG representations. Recall that B_k -EPG and B_k -VPG graphs are heredi-
 146 tary classes.

147 3. THE HELLY NUMBER OF B_k -EPG GRAPHS

148 In this section, we determine the Helly number of the classes of B_1 -EPG, B_2 -EPG
 149 and B_3 -EPG graphs, and show that for B_k -EPG graphs, $k \geq 4$, the Helly number
 150 is unbounded. We prove the following result.

151 **Theorem 4.** *The Helly number of B_k -EPG graphs satisfy:*

- 152 (i) $H(B_1\text{-EPG}) = 3$
- 153 (ii) $H(B_2\text{-EPG}) = 4$
- 154 (iii) $H(B_3\text{-EPG}) = 8$
- 155 (iv) $H(B_k\text{-EPG})$ is unbounded, for $k \geq 4$.

156 The proof consists in determining tight lower and upper bounds, as shown
 157 in the next two subsections.

158 3.1. Lower Bounds

159 We present lower bounds for the Helly number, as a function of the number
 160 k of bends.

161 **Claim 5.** *The following are lower bounds for B_k -EPG graphs.*

- 162 (i) $H(B_1\text{-EPG}) \geq 3$
- 163 (ii) $H(B_2\text{-EPG}) \geq 4$
- 164 (iii) $H(B_3\text{-EPG}) \geq 8$
- 165 (iv) $H(B_k\text{-EPG})$ is unbounded for $k \geq 4$.

166 **Proof.** For each value of k , we exhibit a B_k -family of edge paths whose Helly
 167 number is the corresponding stated value. We refer to the pair of coordinates of
 168 grid points, to describe the paths.

169 For $k = 1$, let \mathcal{F} be a family of three 1-bend paths that pairwise intersect
 170 but which have no common edge, as depicted in Figure 1(a). Then \mathcal{F} is a 2-
 171 intersecting B_1 -EPG family of three paths, having an empty core. Furthermore,

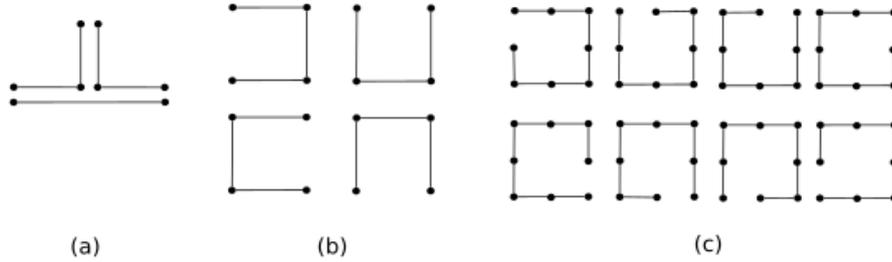


Figure 1. Minimal non-Helly sub-families for the B_1 , B_2 and B_3 -families.

172 removing any of the paths from \mathcal{F} makes its core become non-empty. Therefore
 173 \mathcal{F} is a minimal non-2-Helly family and $H(B_1\text{-EPG}) \geq 3$.

174 Let S be the 4-cycle formed by the four edge segments, with bends at the
 175 grid points $(0, 0)$, $(0, 2)$, $(2, 2)$, $(2, 0)$, respectively. For $k = 2$, consider \mathcal{F} to be the
 176 family of four 2-bend paths formed when we remove exactly one of the two-edge
 177 segments that form the 4-cycle, as depicted in Figure 1(b). It follows that \mathcal{F}
 178 is 3-intersecting and there is no common edge to all four paths. Hence $H(B_2\text{-}$
 179 $\text{EPG}) \geq 4$.

180 For $k = 3$, consider again the same cycle S as above. Note that S contains 8
 181 grid edges. Let \mathcal{F} consist of the 8 paths P_i , $1 \leq i \leq 8$, obtained by removing from
 182 S , exactly one of these distinct 8 edges, as depicted in Figure 1(c). Consequently,
 183 \mathcal{F} is 7-intersecting, but $\text{core}(\mathcal{F}) = \emptyset$. Therefore, $H(B_3\text{-EPG}) \geq 8$.

184 Finally, for $k = 4$, let \mathcal{F} be the family of n paths P_i , described as follows:

- 185 • P_1 is formed by the segments connecting:
 186 $(0, 0), (0, 1), (1, 1), (1, 0), (n, 0)$;
- 187 • for $2 \leq i \leq n - 1$, P_i contains the segments connecting:
 188 $(0, 0), (0, i - 1), (i - 1, 1), (i, 1), (i, 0), (n, 0)$;
- 189 • P_n is formed by the segments connecting:
 190 $(0, 0), (n - 1, 0), (n - 1, 1), (n - 1, 0)$.

191 Observe that \mathcal{F} is $(n - 1)$ -intersecting, while $\text{core}(\mathcal{F}) = \emptyset$ (see Figure 2).
 192 Therefore $H(B_4\text{-EPG})$ is unbounded. Clearly the same holds for $k > 4$. \square

193 Next, we consider upper bounds for the Helly number B_k -EPG graphs.

194 3.2. Upper Bounds

195 In order to obtain tight upper bounds for the Helly number, in terms of the
 196 number of bends, we introduce below more notation and lemmas.

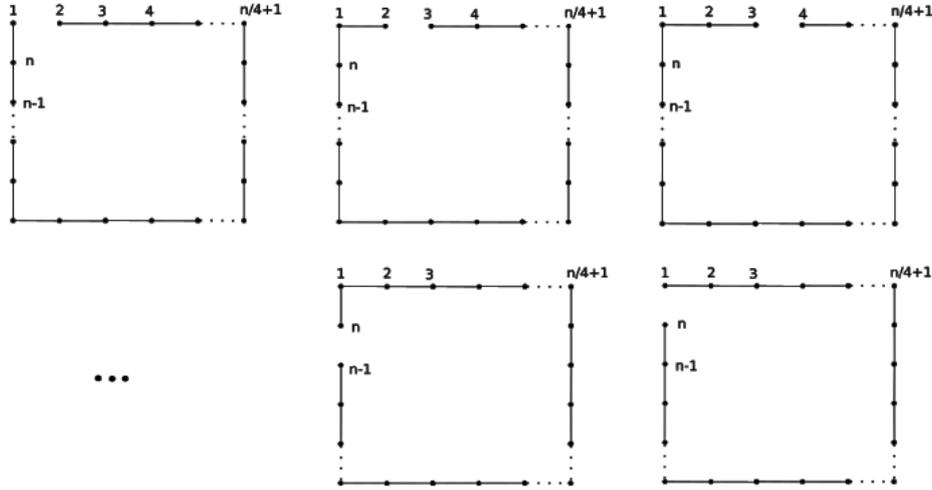


Figure 2. B_4 has an unlimited Helly number.

197 Say that a set of edges of a grid is *co-linear* if all edges of the set belong to
 198 the same line of the grid, horizontal or vertical. The set of edges is called *parallel*
 199 if all its edges lie on parallel lines of the grid, but no two of them are co-linear.

200 **Lemma 6.** *Let \mathcal{F} be a minimal non- $(h - 1)$ -Helly family of paths on a grid*
 201 *containing three co-linear non-representative edges. Then \mathcal{F} must contain paths*
 202 *with at least four bends.*

203 **Proof.** Let u_i be the middle one of the three co-linear non-representative edges.
 204 It corresponds to the path P_i of \mathcal{F} , not containing u_i . Then P_i must go through
 205 the other two non-representative edges, but it cannot include the middle edge.
 206 Therefore path P_i must leave the common line of the grid, containing those three
 207 representative edges, and return to that same line, thus requiring at least four
 208 bends. \square

209 **Lemma 7.** *Let \mathcal{F} be a minimal non- $(h - 1)$ -Helly family of paths on a grid,*
 210 *containing three parallel edges, and having Helly number $H(\mathcal{F}) \geq 4$. Then \mathcal{F}*
 211 *must contain paths with at least four bends.*

212 **Proof.** Since $H(\mathcal{F}) \geq 4$ and \mathcal{F} is a minimal $(h - 1)$ -family, it follows that \mathcal{F}
 213 must contain at least four paths, P_1, P_2, P_3, P_4 . Without loss of generality, let
 214 u_1, u_2, u_3 be non-representative edges which are parallel and correspond to the
 215 paths P_1, P_2 and P_3 respectively. Then P_4 must go through all the three parallel
 216 non-representative edges u_1, u_2, u_3 , thus requiring at least four bends. \square

217 **Lemma 8.** *Let \mathcal{F} be a minimal non- $(h - 1)$ -Helly family of paths on a grid with*
 218 *Helly number $H(\mathcal{F}) \geq 4$. If \mathcal{F} contains three non-representative edges that lie on*
 219 *a common B_1 -subpath P_i , then \mathcal{F} must have some path with at least three bends.*

220 **Proof.** Since \mathcal{F} is a minimal $(h - 1)$ -family having Helly number ≥ 4 , it contains
 221 at least four paths. Without loss of generality, let u_1, u_2, u_3 be the three non-
 222 representative edges contained in P_4 and such that u_2 lies between u_1 and u_3 in
 223 P_4 . Then path P_2 must contain u_1 and u_3 , but avoid u_2 , thus requiring at least
 224 three bends. \square

225 The following are tight upper bounds for the Helly numbers of B_k -EPG paths,
 226 for $k = 1, 2, 3$.

227 **Claim 9.** $H(B_1\text{-EPG}) \leq 3$.

228 **Proof.** Assume by contradiction that the Helly number of B_1 -EPG paths is
 229 $h > 3$. In this case, consider a minimal non- $(h - 1)$ -Helly family of \mathcal{F} of B_1 -EPG
 230 paths. Then \mathcal{F} contains at least h paths. Any path $P_1 \in \mathcal{F}$ must contain $h - 1$
 231 non-representative edges corresponding to the $h - 1$ distinct paths of \mathcal{F} other
 232 than P_1 . Since $h - 1 \geq 3$, P_1 contains at least three distinct non-representative
 233 edges $u_2, u_3, u_4 \in P_i$, with u_3 lying between u_2 and u_4 in the path.

234 If u_2, u_3 and u_4 are co-linear then by Lemma 6 $P_3 \in \mathcal{F}$ must contain at least
 235 four bends. Otherwise, the edges must lie on P_1 which has a single bend. Thus, it
 236 follows from Lemma 8 that P_3 has three bends. In any situation, a contradiction
 237 arises, implying that $H(\mathcal{F}) \leq 3$. \square

238 **Claim 10.** $H(B_2\text{-EPG}) \leq 4$.

239 **Proof.** Assume by contradiction that the Helly number of B_2 -EPG families of
 240 paths is $h > 4$. Consider a minimal non- $(h - 1)$ -Helly family \mathcal{F} of B_2 -EPG
 241 paths. The family \mathcal{F} must contain at least $h \geq 5$ distinct paths, each of them
 242 corresponding to a distinct non-representative edge. Choose arbitrarily 5 of these
 243 non-representative edges.

244 By Lemmas 6 and 7 any three of these chosen edges can neither be co-linear
 245 nor parallel. Therefore, at least one of the five chosen non-representative edges
 246 must be in a different direction from the majority of the chosen edges. Call the
 247 direction of this edge vertical and the direction of the majority of the chosen
 248 edges horizontal. Consider a path P_1 from the family \mathcal{F} that goes through this
 249 vertical edge. The path P_1 contains at least four of the chosen non-representative
 250 edges, at least one of which is vertical. Since P_1 has at most two bends, then it
 251 must have at most three segments. Since we have three segments and four non-
 252 representative edges which P_1 must contain, by the pigeon hole principle, one of
 253 these segments must have two non-representative edges. If this pair of edges are
 254 in a horizontal segment of P_1 , then such pair of edges, along with the vertical

255 edge are in two consecutive path segments, forming a B_1 -subpath in \mathcal{F} . Then
 256 Lemma 8 implies that some path of \mathcal{F} must have at least three bends. Otherwise,
 257 the two edges are vertical. But the others must be horizontal, and again we have
 258 at least three edges in a pair of consecutive segments forming a subpath in \mathcal{F}
 259 having one bend. Again, Lemma 8 implies that some path has at least three
 260 bends. \square

261 **Claim 11.** $H(B_3\text{-EPG}) \leq 8$.

262 **Proof.** Assume by contradiction that the Helly number of B_3 -EPG paths is $h >$
 263 8. In this case, consider a minimal non- $(h - 1)$ -Helly family \mathcal{F} of B_3 -EPG paths.
 264 Then \mathcal{F} contains at least h distinct non-representative edges, corresponding to
 265 h distinct paths. By Lemma 7, since we can have at most three bends in any
 266 path, then these h non-representative edges must lie in at most two vertical and
 267 two horizontal lines of the grid. Therefore one of these four possible lines must
 268 contain at least three distinct non-representative edges. By Lemma 6, that would
 269 imply the existence of a path with four bends. \square

270 This completes the proof of Theorem 4.

271 4. HELLY NUMBER OF B_k -VPG GRAPHS

272 In this section, we determine the Helly number of B_k -VPG graphs. We prove the
 273 following results.

274 **Theorem 12.** *The Helly numbers for B_k -VPG graphs satisfy:*

- 275 1. $H(B_1\text{-VPG}) = 4$
- 276 2. $H(B_2\text{-VPG}) = 6$
- 277 3. $H(B_3\text{-VPG}) = 12$
- 278 4. $H(B_4\text{-VPG})$ is unbounded.

279 Again, we prove the theorem by showing tight lower and upper bounds.

280 4.1. Lower Bounds

281 We start by describing some sets of paths that achieve our lower bounds.
 282 Figure 3 shows a set of 4 B_1 -paths of a graph G , in a 2×2 grid, such that each
 283 path covers three vertices of the grid, and avoids exactly one of the vertices.

284 Figure 4 shows a set of 6 B_2 -paths of a graph G , in a 2×3 grid, such that
 285 each path covers five vertices of the grid, and avoids exactly one.

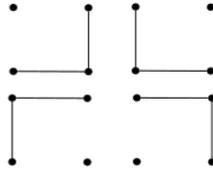


Figure 3. Lower bound for B_1 -VPG graphs

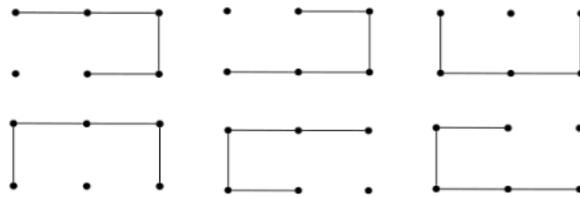


Figure 4. Lower bound for B_2 -VPG graphs

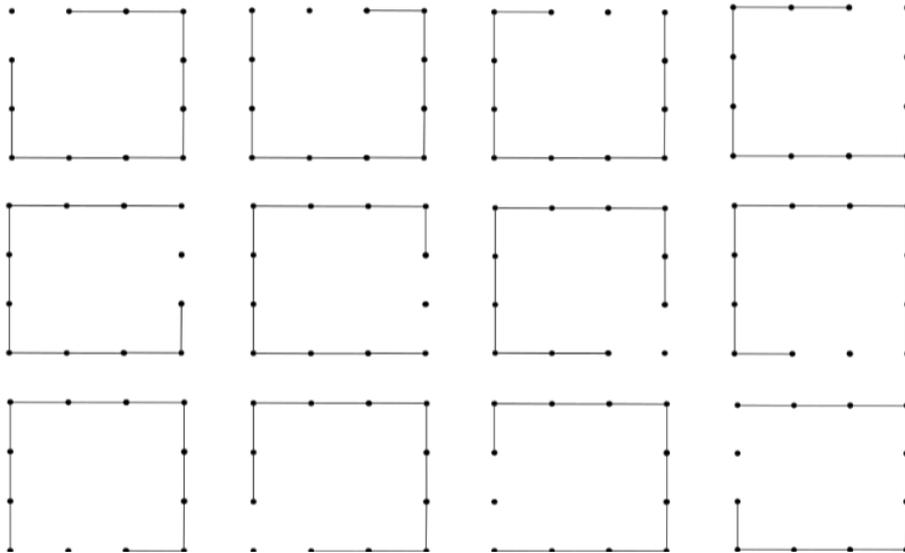


Figure 5. Lower bound for B_3 -VPG graphs

286 Figure 5 shows 12 B_3 -paths of a graph G , in a grid, of perimeter 12, such
 287 that each path covers 11 vertices of the grid, avoiding one of them.

288 Figure 6 shows a set of n B_4 -paths of a n -vertex graph G , in a grid having
 289 perimeter n , such that each path covers $n - 1$ vertices of G , avoiding one of them.

290 Applying Theorem 3, we can then conclude that the number of vertices of
 291 each of the above-described graphs is lower bound for the corresponding class.

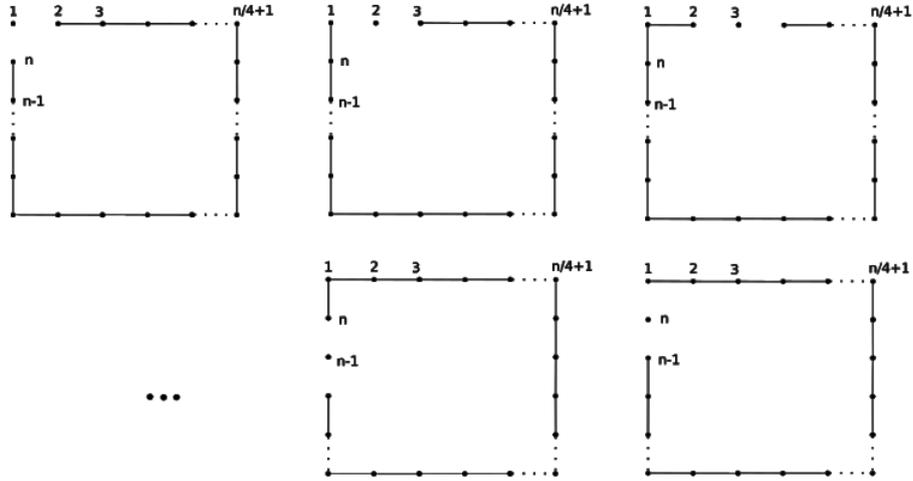


Figure 6. Lower bound for B_4 -VPG graphs

292 Then, we can claim the following bounds.

293 **Claim 13.** *The following are lower bounds for the Helly numbers of B_k -VPG*
 294 *graphs.*

- 295 1. $H(B_1\text{-VPG}) \geq 4$
- 296 2. $H(B_2\text{-VPG}) \geq 6$
- 297 3. $H(B_3\text{-VPG}) \geq 12$
- 298 4. $H(B_4\text{-VPG})$ is unbounded.

299 **4.2. Upper Bounds**

300 Next, we provide upper bounds for the Helly number of B_k -VPG graphs.
 301 The following lemmas are employed.

302 **Lemma 14.** *Let \mathcal{F} be a minimal non- $(h - 1)$ -Helly family of paths, for some h ,*
 303 *containing $k \in \{3, 4, 5\}$ distinct co-linear non-representative points of the grid.*
 304 *Then \mathcal{F} contains a path having at least $k - 1$ bends.*

305 **Proof.** For $k \in \{3, 5\}$, the path avoiding the middle point has at least $k - 1$
 306 bends, while for $k = 4$, the path avoiding one of the middle points also has this
 307 same property. □

308 **Lemma 15.** *Let \mathcal{F} be a minimal non- $(h - 1)$ -Helly family of paths, on a grid*
 309 *containing $k < h$ distinct pairwise non-co-linear non-representative points. Then*
 310 *\mathcal{F} must contain a path with at least $k - 1$ bends.*

311 **Proof.** Since $k < h$, \mathcal{F} must contain a path that visits all such k pairwise non-
 312 co-linear points. Such a path requires at least one bend, between two consecutive
 313 non-co-linear points. Therefore \mathcal{F} contains a path with at least $k - 1$ bends. \square

314

We also employ some additional concepts and notation, below described.

315

316 Let \mathcal{F} be a minimal non- $(h - 1)$ -Helly family of B_{k-1} -paths on a grid Q . By
 317 Theorem 3, we can choose h paths $P_i \in \mathcal{F}$, each of them associated to a distinct
 318 non-representative grid point p_i , such that P_i avoids p_i , but contains all the other
 319 $h - 1$ distinct non-representative points $p_j \in P_j$, for each $j \neq i$. Denote by P_N ,
 320 $|P_N| = h$, the subset of grid points of Q , restricted to the chosen set of distinct
 321 non-representative points p_i . By Lemmas 14 and 15, the grid points of P_N are
 322 contained in at most k columns (lines), and each column (line) contains at most
 323 k points of P_N . Consequently, the cardinalities of the points of P_N , contained in
 324 the columns (lines) of Q , form a partition of the integer h , into at most k parts,
 325 such that each part is at most k . Call such a partition as a *feasible partition of*
 326 *h , relative to P_N* . Therefore, each non-representative point $p_i \in P_N$ contributes
 327 with one unit to some part of the partition, which is then referred to, as the part
 328 of the partition *corresponding to p_i* .

329

The following lemma describes sufficient conditions for an integer h to be an
 330 upper bound for the Helly number.

331

Lemma 16. *Let \mathcal{F} be a minimal non- $(h - 1)$ -Helly family of B_{k-1} -paths on a
 332 grid Q , and P_N the set of non-representative points of Q . Let k, h be integers,
 333 $1 \leq k \leq 3$ and $k < h$. The following conditions imply $H(B_k\text{-VPG}) \leq h$*

334

(i) *there is no feasible partition of $h + 1$, relative to P_N , or*

335

(ii) *for any possible feasible partition, and for any arrangement of the grid points
 336 of P_N in Q , there is some non-representative point $p_i \in P_N$, such that no
 337 path exists in Q , having at most k bends, containing all points of P_N , except
 338 p_i .*

339

Proof: The proof of (i) follows from Lemmas 14 and 15, while the proof of
 340 (ii) is a consequence of Theorem 3. \square

341

The following are upper bounds for the Helly number of B_k -VPG graphs, for
 342 each k , $1 \leq k \leq 3$, obtained by applying Lemma 16.

343

Claim 17. $H(B_1\text{-VPG}) \leq 4$.

344

Proof. There is no partition of the integer 5, into two parts, in which each part
 345 is at most 2. Consequently, the result follows from Lemma 16 (i). \square

346

Claim 18. $H(B_2\text{-VPG}) \leq 6$.

347

348 **Proof.** Assume the contrary. Then $H(B_2\text{-VPG}) \geq 7$, let \mathcal{F} be a minimal non-
 349 6-Helly family of B_2 -paths, and P_N be the set of non-representative points of
 350 \mathcal{F} in Q . There are two possible partitions of the integer 7, in three parts, each
 351 of them of size at most 3, namely $(3, 3, 1)$ and $(3, 2, 2)$. In any of these cases,
 352 it is always possible to choose some point $p_i \in P_N$, belonging to a part of the
 353 partition of size 3, such that a path in \mathcal{F} which avoids p_i and covers the other six
 354 non-representative points, must contain at least three bends. Then by Lemma
 355 16, indeed $H(B_2\text{-VPG}) \leq 6$. \square

356 **Claim 19.** $H(B_3\text{-VPG}) \leq 12$.

357 **Proof.** Assume the contrary, $H(B_3\text{-VPG}) \geq 12$. Let \mathcal{F} be a minimal non-12-
 358 Helly family of B_3 -paths, and P_N be the set of non-representative points of \mathcal{F}
 359 in Q . There are three possible partitions of the integer 13, into four parts, each
 360 of them of size at most 4, namely $(4, 4, 4, 1)$, $(4, 4, 3, 2)$ and $(4, 3, 3, 3)$. In this
 361 case, choose $p_i \in P_N$ to be a non-representative point, corresponding to a part
 362 of size 4 of the partition. The path of \mathcal{F} , which avoids p_i , must cover the other
 363 12 non-representative points. These points are located in 4 distinct columns, of
 364 cardinalities 4,4,3,1, 4,3,3,2, or 3,3,3,3, considering the three possible partitions,
 365 respectively. Such a path must contain at least four bends, a contradiction. Then
 366 by Lemma 16, $H(B_3\text{-VPG}) \leq 12$. \square

367 From the lower and upper bounds described in the previous subsections, we
 368 obtain the results for the Helly numbers of B_k -VPG graphs, completing the proof
 369 of Theorem 12.

370 5. STRONG HELLY NUMBER

371 In this section, we first consider determining the strong Helly number of B_k -EPG
 372 graphs.

373 We start by describing a theorem similar to Theorem 3.

374 **Theorem 20.** *Let \mathcal{C} be a hereditary class of families \mathcal{F} of subsets of the universal
 375 set U , whose strong Helly number $sH(\mathcal{C})$ equals h . Then there exists a family
 376 $\mathcal{F}' \in \mathcal{C}$ with exactly h subsets satisfying the following condition:*

*For each subset $P_i \in \mathcal{F}'$, there is exactly one distinct element $u_i \in U$, such
 that*

$$u_i \notin P_i,$$

but u_i is contained in all subsets

$$P_j \in \mathcal{F}' \setminus P_i.$$

k	B_k -EPG	B_k -VPG
0	2	2
1	3	4
2	4	6
3	8	12
≥ 4	unbounded	unbounded

Table 1. Helly and Strong Helly Numbers for B_k -EPG and B_k -VPG Graphs

377 Proof: The strong Helly number of \mathcal{C} is h and not $h - 1$, so that there
 378 must exist some family $\mathcal{F} \in \mathcal{C}$ whose strong Helly number is exactly h , i.e., \mathcal{F}
 379 contains h subsets P_i whose intersection equals $\text{core}(\mathcal{F}')$ but is such that no $h - 1$
 380 of its subsets have the same intersection. In particular, let \mathcal{F}' be the family
 381 containing exactly the h subsets P_i described above. Such a family must exist,
 382 since \mathcal{C} is hereditary. Then each P_i does not contain at least one element u_i in
 383 the intersection of the remaining $h - 1$ subsets $P_j, j \neq i$, since the intersection of
 384 these $h - 1$ subsets must not be equal to the $\text{core}(\mathcal{F}')$. \square

385 Again, if we consider the family \mathcal{F}' described in the theorem above it is simple
 386 to conclude that the removal of any subset from \mathcal{F}' turns it $(h - 1)$ -strong Helly.
 387 Then call \mathcal{F}' a *minimal* non- $(h - 1)$ -strong Helly family. Moreover, the element
 388 $u_i \notin P_i$, contained in all subsets $P_j \in \mathcal{F}' \setminus P_i$, except P_i , is the h *non-representative*
 389 of P_i .

390 As before, we employ the above minimal families of subsets, applied to paths
 391 in a grid.

392 We prove that the strong Helly number of B_k -EPG graphs coincide with the
 393 Helly number, for each corresponding value of k . Similarly, for B_k -VPG graphs.
 394 For $k = 0$, it is simple to show that if a set of intervals \mathcal{I} in a line pairwise intersect,
 395 then there exist two intervals of \mathcal{I} , whose intersection equals the intersection of
 396 all intervals of \mathcal{I} . Consequently, the k -strong Helly number of B_0 -EPG graphs
 397 equals 2. Similarly, for B_0 -VPG graphs. Recall that the strong Helly number is
 398 at least equal to the Helly number of a family so that the lower bounds presented
 399 in Claim 5 also hold for the strong Helly number. The proofs for the strong Helly
 400 numbers for $k \geq 1$ are similar to those described in Section 3.

401 **6. CONCLUDING REMARKS**

402 We have determined the Helly number and strong Helly number of B_k -EPG
 403 graphs and B_k -VPG graphs, for $k \geq 0$.

404 Table 1 summarizes the results obtained.

405 We leave two questions to be investigated concerning the presented results.

- 406 1. Given a *specific* EPG or VPG graph, the question is to formulate an algo-
 407 rithm to determine its Helly and strong Helly numbers. See [5], for instance,
 408 for such algorithms, applied to general graphs.
- 409 2. The values of the Helly and strong Helly numbers, which were determined
 410 in this paper, coincided in all cases. Clearly, in general, this is not the case.
 411 We leave as an open question, to find the conditions for such equality to
 412 occur.

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Chapter 5

Relationship among B_1 -EPG, EPT and VPT graph classes

What we know is a drop, what we don't know is an ocean.

Sir Isaac Newton

This chapter presents as the main result the proof that every Chordal B_1 -EPG graph is simultaneously in the VPT and EPT graph classes. In particular, we describe structures that belong to B_1 -EPG but do not support a Helly- B_1 -EPG representation and thus we define some sets of subgraphs that delimit Helly subfamilies. Besides, this chapter also presents features of some non-trivial graph families that are properly contained in Helly- B_1 EPG, namely these families are composed by Bipartite, Blocks, Cactus, and Line of Bipartite graphs.

5.1 Introduction

Models based on paths intersection may consider intersections by vertices or intersections by edges. Cases where the paths are hosted on a tree have appeared in [36, 39, 41], among others. Representations using paths on a grid were considered later, see [42, 46, 47].

A pertinent question in the context of path intersection graphs is as follows: given two classes of path intersection graphs, the first whose host is a tree and the second whose host is a grid, is there an intersection or containment relationship among these classes? What do we know about it?

In the present chapter we will explore B_1 -EPG graphs, in particular Diamond-free graphs and Chordal graphs. We will work on the question about the containment relation between VPT, EPT and B_1 -EPG graph classes.

We presented an infinite family of forbidden induced subgraphs for the class B_1 -EPG and in particular we proved that $\text{Chordal } B_1\text{-EPG} \subset \text{VPT} \cap \text{EPT}$. In addition, we also propose other questions for future research.

Next, we present the manuscript where the reader can find all the results previously mentioned.

5.2 Manuscript on B_1 -EPG and EPT Graphs

1

ON B_1 -EPG AND EPT GRAPHS

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13

Abstract

14

This research contains as a main result the proof that every Chordal B_1 -EPG graph is simultaneously in the graph classes VPT and EPT. In addition, we describe structures that must be present in any B_1 -EPG graph which does not admit a Helly- B_1 -EPG representation. In particular, this paper presents some features of non-trivial families of graphs properly contained in Helly- B_1 -EPG, namely Bipartite, Block, Cactus and Line of Bipartite graphs.

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Keywords: Edge-intersection of paths on a grid, Edge-intersection graph of paths in a tree, Helly property, Intersection graphs, Single bend paths, Vertex-intersection graph of paths in a tree.

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2010 Mathematics Subject Classification: 05C62 - Graph representations.

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1. INTRODUCTION

Models based on paths intersection may consider intersections by vertices or intersections by edges. Cases where the paths are hosted on a tree appear first in the literature, see for instance [9, 10, 11]. Representations using paths on a grid were considered later, see [12, 13, 15].

31 Let P be a family of paths on a host tree T . Two types of intersection graphs
 32 from the pair $\langle P, T \rangle$ are defined, namely VPT and EPT graphs. The *edge*
 33 *intersection graph* of P , $EPT(P)$, has vertices which correspond to the members
 34 of P , and two vertices are adjacent in $EPT(P)$ if and only if the corresponding
 35 paths in P share at least one edge in T . Similarly, the *vertex intersection graph* of
 36 P , $VPT(P)$, has vertices which correspond to the members of P , and two vertices
 37 are adjacent in $VPT(P)$ if and only if the corresponding paths in P share at least
 38 one vertex in T . VPT and EPT graphs are incomparable families of graphs.
 39 However, when the maximum degree of the host tree is restricted to three the
 40 family of VPT graphs coincides with the family of EPT graphs [10]. Also it is
 41 known that any Chordal EPT graph is VPT (see [19]). Recall that it was shown
 42 that Chordal graphs are the vertex intersection graphs of subtrees of a tree [8].

43 Edge intersection graphs of paths on a grid are called *EPG graphs*.

44 In [12], the authors proved that every graph is EPG, and started the study
 45 of the subclasses defined by bounding the number of times any path used in the
 46 representation can bend. Graphs admitting a representation where paths have
 47 at most k changes of direction (bends) were called B_k -EPG. In particular, when
 48 the paths have at most one bend we have the *B_1 -EPG graphs* or a *single bend*
 49 *EPG graphs*.

50 A pertinent question in the context of path intersection graphs is as follows:
 51 given two classes of path intersection graphs, the first whose host is a tree and the
 52 second whose host is a grid, is there an intersection or containment relationship
 53 among these classes? What do we know about it?

54 In the present paper we will explore B_1 -EPG graphs, in particular diamond-
 55 free graphs and Chordal graphs. We will work on the question about the con-
 56 tainment relation between VPT, EPT and B_1 -EPG graph classes.

57 A collection of sets satisfies the *Helly property* when every pair-wise inter-
 58 secting sub-collection has at least one common element. When this property is
 59 satisfied by the set of vertices (edges) of the paths used in a representation, we
 60 get a Helly representation. Helly- B_1 -EPG graphs were studied in [5]. It is known
 61 that not every B_1 -EPG graph admits a Helly- B_1 -EPG representation. We are
 62 interested in determining the subgraphs that make B_1 -EPG graphs that do not
 63 admit a Helly representation. In the present work, we describe some structures
 64 that will be present in any such subgraph, and, in addition, we present new Helly-
 65 B_1 -EPG subclasses. Moreover, we describe new Helly- B_1 -EPG subclasses and we
 66 give some sets of subgraphs that delimit Helly subfamilies.

67

2. DEFINITIONS AND TECHNICAL RESULTS

68 The *vertex set* and the *edge set* of a graph G are denoted by $V(G)$ and $E(G)$,
 69 respectively. Given a vertex $v \in V(G)$, $N(v)$ represents the *open neighborhood*
 70 of v in G . For a subset $S \subseteq V(G)$, $G[S]$ is the subgraph of G induced by S . If
 71 \mathcal{F} is any family of graphs, we say that G is \mathcal{F} -free if G has no induced subgraph
 72 isomorphic to a member of \mathcal{F} . A *cycle*, denoted by C_n , is a sequence of distinct
 73 vertices v_1, \dots, v_n, v_1 where $v_i \neq v_j$ for $i \neq j$ and $(v_i, v_i + 1) \in E(G)$, such that
 74 $n \geq 3$. A *chord* is an edge that is between two non-consecutive vertices in a
 75 sequence of vertices of a cycle. An *induced cycle* or *chordless cycle* is a cycle that
 76 has no chord, in this paper an induced cycle will simply be called a *cycle*. A graph
 77 G formed by an induced cycle H plus a single universal vertex v connected to all
 78 vertices of H is called a *wheel graph*. If the wheel has n vertices, it is denoted by
 79 n -wheel.

80 The k -sun graph S_k , $k \geq 3$, consists of $2k$ vertices, an independent set
 81 $X = \{x_1, \dots, x_k\}$ and a clique $Y = \{y_1, \dots, y_k\}$, and edge set $E_1 \cup E_2$, where $E_1 =$
 82 $\{(x_1, y_1); (y_1, x_2); (x_2, y_2); (y_2, x_3); \dots, (x_k, y_k); (y_k, x_1)\}$ and $E_2 =$
 83 $\{(y_i, y_j) | i \neq j\}$.

84 A graph is a B_k -EPG graph if it admits an EPG representation in which
 85 each path has at most k bends. When $k = 1$ we say that this is a *single bend*
 86 *EPG* representation or simply a B_1 -EPG representation. A *clique* is a set of
 87 pairwise adjacent vertices and an *independent set* is a set of pairwise non adjacent
 88 vertices. Given an EPG representation of a graph G , we will identify each vertex
 89 v of G with the corresponding path P_v of the grid used in the representation.
 90 Accordingly, for instance, we will say that a vertex of G covers or contains some
 91 edge of the grid (meaning that the corresponding path does), or that a set of paths
 92 of the representation induces a subgraph of G (meaning that the corresponding
 93 set of vertices does).

94 In a B_1 -EPG representation, a clique K is said to be an *edge-clique* if all
 95 the vertices of K share a common edge of the grid (see Figure 1(a)). A *claw of*
 96 *the grid* is a set of three edges of the grid incident into the same point of the
 97 grid, which is called the *center of the claw*. The two edges of the claw that have
 98 the same direction form the *base of the claw*. If K is not an edge-clique, then
 99 there exists a claw of the grid (and only one) such that the vertices of K are
 100 those containing exactly two of the three edges of the claw; such a clique is called
 101 *claw-clique* [12] (see Figure 1(b)).

102 Notice that if three vertices induce a claw-clique, then exactly two of them
 103 turn at the center of the corresponding claw of the grid, and the third one contains
 104 the base of the claw. Furthermore, any other vertex adjacent to the three must
 105 contain two of the edges of that claw, then the following lemma holds.

106 **Lemma 1.** *If three vertices are together in more than one maximal clique of a*

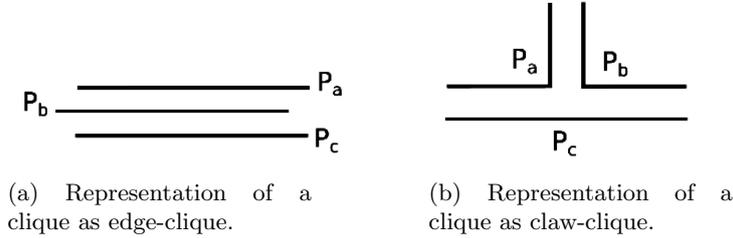


Figure 1. Examples of clique representations.

107 graph G , then in any B_1 -EPG representation of G the three vertices do not form
 108 a claw-clique.

109 In [3] Asinowski et al. proved the following lemma for C_4 -free graphs.

110 **Lemma 2.** [3] Let G be a B_1 -EPG graph. If G is C_4 -free, then there exists a B_1 -
 111 EPG representation of G such that every maximal claw-clique K is represented
 112 on a claw of the grid whose base is covered only by vertices of K .

113 We have obtained the following similar result for diamond-free graphs. A
 114 *diamond* is a graph G with vertex set $V(G) = \{a, b, c, d\}$ and edge set $E(G) =$
 115 $\{ab, ac, bc, bd, cd\}$.

116 **Lemma 3.** Let G be a B_1 -EPG graph. If G is diamond-free, then in any B_1 -
 117 EPG representation of G , every maximal claw-clique K is represented on a claw
 118 of the grid whose edges are covered only by vertices of K .

119 **Proof.** Let K be a maximal clique which is a claw-clique in a given B_1 -EPG
 120 representation of G . Then there exist three vertices of K which induce a claw-
 121 clique K' on the same claw of the grid than K . Assume, in order to derive a
 122 contradiction, that a vertex $v \notin K$ covers some edge of the claw. Clearly, v
 123 must cover only one of such edges. Therefore v and the vertices of K' induce a
 124 diamond, a contradiction. ■

125 Let Q be a grid and let (a_1, b) , (a_2, b) , (a_3, b) , (a_4, b) be a 4-star centered at
 126 b as depicted in Figure 2(a). Let $\mathcal{P} = \{P_1, \dots, P_4\}$ be a collection of four paths
 127 each containing a different pair of edges of the 4-star. Following [12], we say that
 128 the four paths form

- 129 • a *true pie* when each one has a bend at b , Figure 2(b); and
- 130 • a *false pie* when exactly two of the paths bend at b and they do not share
 131 an edge of the 4-star, Figure 2(c).

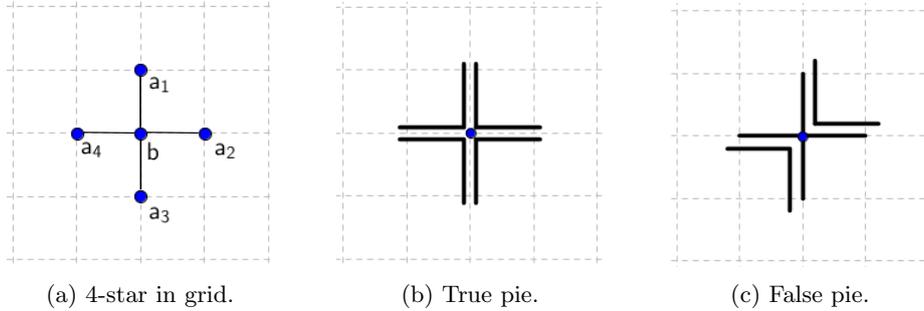


Figure 2. B_1 -EPG representation of the induced cycle of size 4 as pies with emphasis in center b .

132 Clearly if four paths of a B_1 -EPG representation of G form a pie, then the
 133 corresponding vertices induce a 4-cycle in G . The following result can be easily
 134 proved. We say that a set of paths form a claw when each pair of edges of the
 135 claw is covered by some of the paths.

136 **Lemma 4.** *In any B_1 -EPG representation of a graph G , a set of paths forming*
 137 *two different claws centered at the same point of the grid contains four paths*
 138 *forming either a true pie or a false pie. Therefore, in any B_1 -EPG representation*
 139 *of a chordal graph G , no two maximal claw-cliques of G are centered at the same*
 140 *point of the grid.*

141 **Lemma 5.** *Let G be a graph whose vertex set can be partitioned into a non trivial*
 142 *clique K and an independent set $I = \{w_1, w_2, w_3\}$, such that each vertex of K is*
 143 *adjacent to each vertex of I . Then, in any B_1 -EPG representation of G , at least*
 144 *one of the cliques $K_i = K \cup \{w_i\}$, with $1 \leq i \leq 3$, is an edge-clique.*

145 **Proof.** Assume, in order to derive a contradiction, that the three cliques are
 146 claw-cliques. By Lemma 4, they have different centers, say the points q_1, q_2, q_3
 147 of the grid, respectively. Since at least two paths have a bend at the center of
 148 a claw, for each $i \in \{1, 2, 3\}$, there must exist a vertex v_i of K such that the
 149 corresponding path P_{v_i} turns at the point q_i of the grid. Notice that each one of
 150 the three paths P_{v_i} must contain the three grid points q_1, q_2 and q_3 . To prove
 151 that this is not possible, we will consider, without loss of generality, two cases.
 152 First, q_1 is between q_2 and q_3 in P_{v_1} . Then, P_{v_3} cannot turn at q_3 and contain
 153 q_1 and q_2 . And second, q_2 is between q_1 and q_3 in P_{v_1} . In this case, P_{v_2} cannot
 154 turn at q_2 and contain q_1 and q_3 ; thus the proof is completed. ■

155 Three vertices u, v, w of a graph G form an *asteroidal triple* (AT) of G if for
 156 every pair of them there exists a path connecting the two vertices and such that
 157 the path avoids the neighborhood of the remaining vertex [4]. A graph without
 158 an asteroidal triple is called *AT-free*.

159 **Lemma 6** [3]. *Let v be any vertex of a B_1 -EPG graph G . Then $G[N(v)]$ is*
 160 *AT-free.*

161 Let C be any subset of the vertices of a graph G . The *branch graph* $B(G|C)$,
 162 see [12], of G over C has a vertex set, $V(B)$, consisting of all the vertices of G
 163 not in C but adjacent to some member of C , i.e. $V(B) = N(C) - C$. Adjacency
 164 in $B(G|C)$ is defined as follows: we join two vertices x and y by an edge in $E(B)$
 165 if and only if in G occurs:

- 166 1. x and y are not adjacent;
- 167 2. x and y have a common neighbor $u \in C$;
- 168 3. the sets $N(x) \cap C$ and $N(y) \cap C$ are not comparable, i.e. there exist pri-
 169 vate neighbors $w, z \in C$ such that w is adjacent to x but not to y , and
 170 z is adjacent to y but not to x ; we say that x and y are neighborhood
 171 incomparable.

172 We let $\chi(G)$ denote the chromatic number of G .

173 **Lemma 7** [12]. *Let C be any maximal clique of a B_1 -EPG graph G . Then, the*
 174 *branch graph $B(G|C)$ is $\{P_6, C_n \text{ for } n \geq 4\}$ -free, and $\chi(B(G|C)) \leq 3$.*

175 3. SUBCLASSES OF HELLY- B_1 -EPG GRAPHS

176 In this section, we delimit some subclasses of B_1 -EPG graphs that admit a Helly-
 177 B_1 -EPG representation. It is known that B_1 -EPG and Helly- B_1 -EPG are heredi-
 178 tary classes, so they can be characterized by forbidden structures. In both cases,
 179 finding the list of minimal forbidden induced subgraphs are challenging open
 180 problems. Taking a step towards solving those problems, we describe a few
 181 structures at least one of which will necessarily be present in any B_1 -EPG graph
 182 that does not admit a Helly representation. In addition, we show that the well
 183 known families of Block graphs, Cactus and Line of Bipartite graphs are totally
 184 contained in the class Helly- B_1 -EPG.

185 Let $S_3, S_{3'}, S_{3''}$ and C_4 be the graphs depicted in Figure 4.

186 **Theorem 8.** *Let G be a B_1 -EPG graph. If G is $\{S_3, S_{3'}, S_{3''}, C_4\}$ -free then G is*
 187 *a Helly- B_1 -EPG graph.*

188 **Proof.** If G is not a Helly- B_1 -EPG graph, then in each B_1 -EPG representation
 189 of G , there is at least one clique that is represented as claw-clique and not as
 190 edge-clique. Consider any B_1 -EPG representation of G and let K be a maximal
 191 clique which is represented as a claw-clique. Assume, w.l.o.g, K is on a claw of
 192 the grid with base $[x_0, x_2] \times \{y_0\}$ and center $C = (x_1, y_0)$. Denote by \mathcal{P}_K the

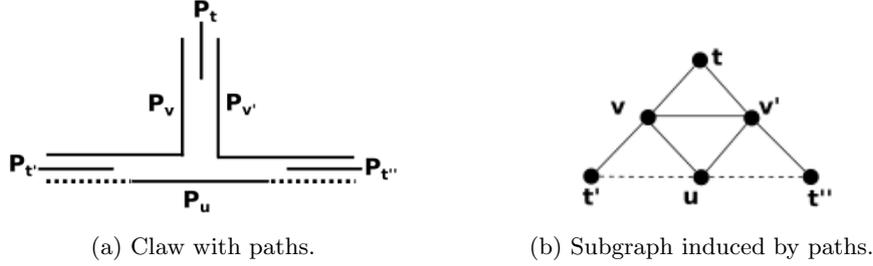


Figure 3. Reconstruction of the intersection model.

193 set of paths corresponding to the vertices of K . By Lemma 2, the grid segment
 194 $[x_0, x_2] \times \{y_0\}$ is covered only by vertices of K .

195 For every \lrcorner -path (resp. \llcorner -path) belonging to \mathcal{P}_K , we do the following: if
 196 the path does not intersect any path $P_t \notin \mathcal{P}_K$ on column x_1 , then we delete its
 197 vertical segment and add the grid segment $[x_1, x_2] \times \{y_0\}$ (resp. $[x_0, x_1] \times \{y_0\}$).
 198 If after this transformation there is no more \lrcorner -paths (resp. \llcorner -paths) in \mathcal{P}_K , then
 199 we are done since we have obtained an edge-clique. So we may assume that
 200 every \lrcorner -path and every \llcorner -path in \mathcal{P}_K intersects some path $P_t \notin \mathcal{P}_K$ on column
 201 x_1 (notice that we can assume is the same path P_t for all the vertices).

202 Now, if none of the \lrcorner -paths belonging to \mathcal{P}_K intersect a path not in \mathcal{P}_K on
 203 the line y_0 , then we can replace the horizontal part of those paths by the segment
 204 $[x_1, x_2] \times \{y_0\}$, getting an edge representation of the clique K . Thus, we can
 205 assume there exists at least one \lrcorner -path $P_v \in \mathcal{P}_K$ intersecting some path $P_{t'} \notin \mathcal{P}_K$
 206 on line y_0 . Analogously, there exists at least one \llcorner -path $P_{v'} \in \mathcal{P}_K$ intersecting
 207 some path $P_{t''} \notin K$ on line y_0 , as depicted in Figure 3. Notice that vertex t'
 208 cannot be adjacent to any of the vertices t , v' or t'' ; and, in addition, vertex t''
 209 cannot be adjacent to t , or v .

210 Finally, since K is claw-clique, there is a path $P_u \in \mathcal{P}_K$ covering the base of
 211 the claw. Depending on the possible adjacencies between u and t' or t'' , one of
 212 the graphs S_3 , $S_{3'}$ or $S_{3''}$ is obtained.

213

214 Notice that any bull-free graph is $\{S_3, S_{3'}, S_{3''}\}$ -free, so our previous result
 215 implies Lemma 5 of [3].

216 Next theorem has as consequence the identification of several graph classes
 217 where the existence of a B_1 -EPG representation ensures the existence of a Helly-
 218 B_1 -EPG representation.

219 **Theorem 9.** *If G is a B_1 -EPG and diamond-free graph then G is a Helly- B_1 -
 220 EPG graph.*

221 **Proof.** If G is not a Helly- B_1 -EPG graph, then in each B_1 -EPG representation

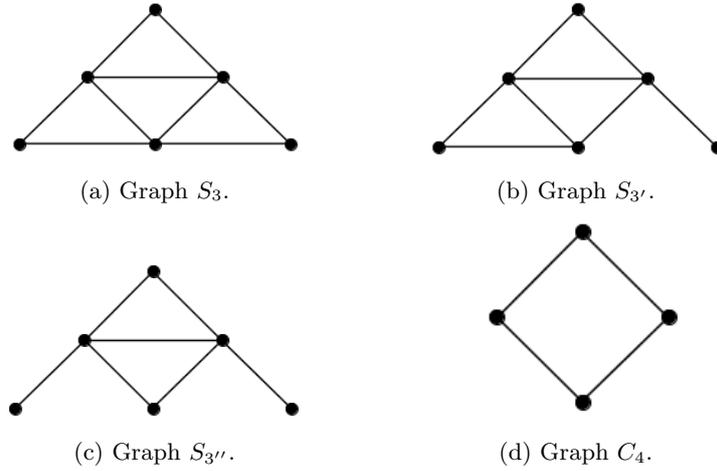


Figure 4. Graphs on the statement of Theorem 8.

222 of G , there is at least one clique that is represented as claw-clique and no as
 223 edge-clique. Consider any B_1 -EPG representation of G and let K be a maximal
 224 clique which is represented as a claw-clique. Assume, w.l.o.g, K is on a claw
 225 of the grid with base $[x_0, x_2] \times \{y_0\}$ and center $C = (x_1, y_0)$. Denote by \mathcal{P}_K
 226 the set of paths corresponding to the vertices of K . By Lemma 3, the grid
 227 segment $[x_0, x_2] \times \{y_0\}$ is covered only by vertices of K . For every \lrcorner -path (resp.
 228 \llcorner -path) belonging to \mathcal{P}_K , we do the following: if the path does not intersect any
 229 path $P_t \notin \mathcal{P}_K$ on column x_1 , then we delete its vertical segment and add the
 230 grid segment $[x_1, x_2] \times \{y_0\}$ (resp. $[x_0, x_1] \times \{y_0\}$). If after this transformation
 231 there is no more \lrcorner -paths (resp. \llcorner -paths) in \mathcal{P}_K , then we are done since we have
 232 obtained an edge-clique. So we may assume that every \lrcorner -path and every \llcorner -path
 233 in \mathcal{P}_K intersects some path $P_t \notin \mathcal{P}_K$ on column x_1 (notice that we can assume
 234 is the same path P_t for all the vertices). Since K is claw-clique, there is a path
 235 $P_u \in \mathcal{P}_K$ covering the base of the claw. Thus, $G[v, v', u, t]$ induces a diamond, a
 236 contradiction. ■

237 An *independent set* of vertices is a set of vertices no two of which are adjacent.
 238 A graph G is said to be *Bipartite* if its set of vertices can be partitioned into two
 239 distinct independent sets. There are Bipartite graphs that are not B_1 -EPG, for
 240 instance $K_{2,5}$ and $K_{3,3}$ (see [7]). Clearly, since bipartite graphs are triangle-
 241 free, any B_1 -EPG representation of a bipartite graph is also a Helly- B_1 -EPG
 242 representation. A similar result (but a bit weaker) is obtained as a corollary of
 243 the previous theorem.

244 **Corollary 10.** *If G is a Bipartite B_1 -EPG graph then G is a Helly- B_1 -EPG*
 245 *graph.*

246 **Proof.** The Bipartite graphs are diamond-free, thus by Theorem 9 these graphs
247 are Helly- B_1 -EPG graphs. ■

248 A *Block graph* or *Clique Tree* is a type of graph in which every biconnected
249 component (block) is a clique.

250 **Corollary 11.** *Block graphs are Helly- B_1 -EPG.*

251 **Proof.** Block graphs are known to be exactly the Chordal diamond-free graphs,
252 so by Theorem 19 of [3], all Block graphs are B_1 -EPG. It follows from Theorem 9
253 that all Block graphs are Helly- B_1 -EPG. ■

254 A *Cactus* (sometimes called a Cactus Tree) graph is a connected graph in
255 which any two cycles have at most one vertex in common. Equivalently, it is
256 a connected graph in which every edge belongs to at most one cycle, or (for
257 nontrivial Cactus) in which every block (maximal subgraph without a cut-vertex)
258 is an edge or a cycle. The family of graphs in which each component is a Cactus
259 is closed under graph minor operations. This graph family may be characterized
260 by a single forbidden minor, the diamond graph.

261 **Corollary 12.** *Cactus graphs are Helly- B_1 -EPG.*

262 **Proof.** In [6], it is proved that every Cactus graph is a monotonic B_1 -EPG
263 graph (there is a B_1 -EPG representation where all paths are ascending in rows
264 and columns). Thus, Cactus graphs are B_1 -EPG graphs.

265 Since Cactus are diamond-free, by Theorem 9, the proof follows. ■

266 Given a graph G , its *Line graph* $L(G)$ is a graph such that each vertex of
267 $L(G)$ represents an edge of G and two vertices of $L(G)$ are adjacent if and only
268 if their corresponding edges share a common endpoint (i.e. “are incident”) in G .
269 A graph G is a *Line graph of a Bipartite graph* (or simply *Line of Bipartite*) if
270 and only if it contains no claw, no odd cycle (with more than 3 vertices), and no
271 diamond as an induced subgraph [16].

272 In [17] was proved that every Line graph has a representation with at most
273 2 bends. We proved in the following corollary that when restricted to the Line
274 of Bipartite we can obtain a representation Helly and one-bended.

275 **Corollary 13.** *Line of Bipartite graphs are Helly- B_1 -EPG.*

276 **Proof.** Line of Bipartite graphs were proved to be B_1 -EPG in [14]. Since they
277 are diamond-free, the proof follows from Theorem 9.

278 ■

279 The diagram of Figure 5 illustrates the containment relationship between
 280 the graph classes studied so far in this work. We list in Figure 6 examples of
 281 graphs in each numbered region of the diagram. The numbers of each item below
 282 correspond to the regions of the same number in the diagram depicted in Figure 5.

- 283 (1) (B_1 -EPG) - (Helly- B_1 -EPG) graphs, depicted in Figure 6(a), graph E_1 ;
- 284 (2) (Line of Bipartite) - (Cactus) - (Block) - (Bipartite) graphs, depicted in
 285 Figure 6(b), graph E_2 ;
- 286 (3) (Helly- B_1 -EPG) - (Line of Bipartite) - (Block) - (Cactus) - (Bipartite)
 287 graphs, depicted in Figure 6(c), graph E_3 ;
- 288 (4) (Block) \cap (Line of Bipartite) - (Cactus) - (Bipartite), depicted in Fig-
 289 ure 6(d), graph E_4 ;
- 290 (5) (Block) \cap (Line of Bipartite) \cap (Cactus) - (Bipartite), depicted in Fig-
 291 ure 6(e), graph E_5 ;
- 292 (6) (Cactus) \cap (Line of Bipartite) - (Block) - (Bipartite). This intersection is
 293 empty. Let G be a graph that is Cactus and Line of Bipartite then G is
 294 {claw, odd cycle, diamond}-free. But G is not a Bipartite graph, then G
 295 has odd cycle, absurd with the hypothesis of G is Line of Bipartite;
- 296 (7) (Bipartite) \cap (Line of Bipartite) - (Cactus) - (Block) graphs, depicted in
 297 Figure 6(f), graph E_7 ;
- 298 (8) (Bipartite) \cap (Line of Bipartite) \cap (Cactus) - (Block) graphs, depicted in
 299 Figure 6(g), graph E_8 ;
- 300 (9) (Bipartite) \cap (Line of Bipartite) \cap (Cactus) \cap (Block) graphs, depicted in
 301 Figure 6(h), graph E_9 ;
- 302 (10) (Bipartite) \cap (Cactus) \cap (Block) - (Line of Bipartite) graphs, depicted in
 303 Figure 6(i), graph E_{10} ;
- 304 (11) (Bipartite) \cap (Cactus) - (Block) - (Line of Bipartite) graphs, depicted in
 305 Figure 6(j), graph E_{11} ;
- 306 (12) (Bipartite) \cap (Helly- B_1 -EPG) - (Cactus) - (Block) - (Line of Bipartite)
 307 graphs, depicted in Figure 6(k), graph E_{12} ;
- 308 (13) (Bipartite) - (B_1 -EPG) graphs, depicted in Figure 6(l), graph E_{13} ;
- 309 (14) (Block) - (Bipartite) - (Line of Bipartite) - (Cactus) graphs, depicted in
 310 Figure 6(m), graph E_{14} ;

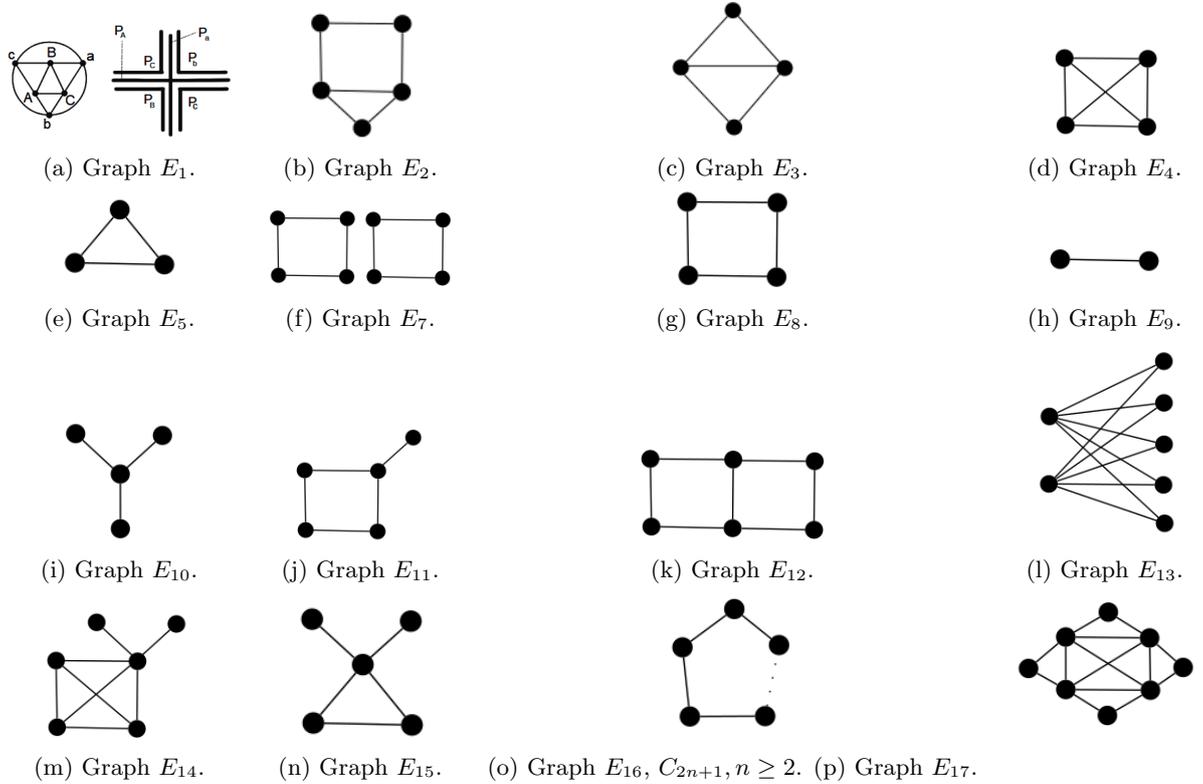


Figure 6. The set of instances for the Venn Diagram on Figure 5.

333 to show that if none of the paths could be modified in order to avoid an edge
 334 of the polygon, then G had some chordless cycle (i.e. G is not chordal). The
 335 surprise was that the only way we found to demonstrate our main Theorem 23
 336 was through VPT graphs. We will prove the following theorem.

337 **Theorem 14.** *Chordal B_1 -EPG \subsetneq VPT.*

338 In Lévêque et al. [18] apud [2], VPT graphs were characterized by a family
 339 of minimal forbidden induced subgraphs, the ones depicted in Figure 7 plus the
 340 induced cycles C_n for $n \geq 4$. Therefore, in order to prove that Chordal B_1 -EPG
 341 graphs are VPT is enough to show that none of the graphs in Figure 7 is B_1 -EPG.

342 First notice that in each one of the graphs F_1, F_2, F_3, F_4 and F_5 (Figures 7(a),
 343 (b), (c), (d), (e), respectively), the neighborhood of the universal vertex (the one
 344 that is a bit bigger than the others, in the respective figures) contains an asteroidal
 345 triple. Therefore, by Lemma 6, these graphs are not B_1 -EPG.

346 Now, in each one of the graphs $F_{11}, F_{12}, F_{13}, F_{14}, F_{15}$ and F_{16} (Figures 7(k),
 347 (l), (m), (n), (o), (p), respectively), let C be the maximal clique in bold. It is

348 easy to check that, in all cases, the branch graph $B(G|C)$ contains an induced
 349 cycle C_n , for some $n \geq 4$, or an induced path P_6 ; thus, by Lemma 7, graphs
 350 $F_{11}, F_{12}, F_{13}, F_{14}, F_{15}$ and F_{16} are not B_1 -EPG.

351 **Observation 15.** *Let e_ℓ, e_m and e_r be three distinct edges of a one-bend path P ,
 352 and assume that e_m is between e_ℓ and e_r on P . If P_ℓ and P_r are one-bend paths
 353 such that: P_ℓ contains e_ℓ , P_r contains e_r , and P_ℓ and P_r intersect in at least one
 354 edge, then P_ℓ or P_r contains e_m .*

355 **Observation 16.** *Let e and q be an edge and a point of a one-bend path P ,
 356 respectively. If a one-bend path P' contains both e and q , then P' contains the
 357 whole segment of P between q and e .*

358 **Lemma 17.** *Let G be a graph whose vertex set can be partitioned into a clique
 359 $K = \{a, b\}$ and an independent set $I = \{x, y, z\}$, such that each vertex of K is
 360 adjacent to each vertex of I . If in a given B_1 -EPG representation of G , $P_a \cap P_y$
 361 is between $P_a \cap P_x$ and $P_a \cap P_z$, then $\{a, b, y\}$ is an edge-clique, and $P_a \cap P_y \subset P_b$.
 362 Even more, any vertex adjacent to both a and y , but not to b (or to b and y , but
 363 not to a) has to be adjacent to x or to z .*

364 **Proof.** Assume in order to obtain a contradiction that $\{a, b, y\}$ is not an edge-
 365 clique. Then, by Lemma 5, we can assume, w.l.o.g., that $\{a, b, x\}$ is an edge-
 366 clique. It implies that there is an edge e_ℓ of $P_a \cap P_x$ covered by P_b . Since every
 367 edge of $P_a \cap P_z$ is covered by P_z , z and b are adjacent, and z and y are non
 368 adjacent, we have by Observation 15, that every edge of $P_a \cap P_y$ is covered by P_b ,
 369 which implies that $\{a, b, y\}$ is an edge-clique, contrary to the assumption.

370 Thus, $\{a, b, y\}$ is an edge-clique. By Observation 16, we have that the whole
 371 interval of P_a between $P_a \cap P_x$ and $P_a \cap P_z$ is contained in P_b , and so, in particular,
 372 $P_a \cap P_y \subset P_b$. Observe that this implies that if q is an end point of the interval
 373 $P_a \cap P_y$, and e is the edge of P_a incident on q that do not belong to P_y , then e
 374 belongs to P_b or to P_x or to P_z .

375 Now, assume there exists a vertex v adjacent to both a and y , but not to
 376 b . Then, the clique $\{a, y, v\}$ has to be a claw-clique. Let q be the center of the
 377 claw, notice that q has to be an end vertex of the interval $P_a \cap P_y$. Since v is not
 378 adjacent to b , it follows from the observation at the end of the paragraph above,
 379 that v has to be adjacent to x or to z .

380 ■

381 **Lemma 18.** *The graph F_6 on Figure 7(f) is not B_1 -EPG.*

382 **Proof.** Let $K = \{1, 2\}$ and $I = \{3, 4, 5\}$. If there exists a B_1 -EPG representation
 383 of F_6 , by Lemma 17, because of the existence of the vertices 6, 7 and 8, none of
 384 the vertices 3, 4 and 5 may intersect 1 between the remaining two, thus such a
 385 representation does not exist. ■

386 **Lemma 19.** *The graph F_7 on Figure $\gamma(g)$ is not B_1 -EPG.*

387 **Proof.** Let $K = \{1, 2\}$ and $I = \{4, 5, 6\}$. If there exists a B_1 -EPG representation
 388 of F_7 , by Lemma 17, because of the existence of the vertices 7 and 8, the vertex
 389 6 must intersect vertex 1 between 3 and 4. But considering $K' = \{1, 3\}$, because
 390 of the existence of the vertices 5 and 6, vertex 4 must intersect vertex 1 between
 391 5 and 6. This contradiction implies that such a representation does not exist. ■

392 **Lemma 20.** *The graphs F_8 , F_9 and $F_{10}(8)$ on Figures $\gamma(h)$, (i) and (j), respec-
 393 tively, are not B_1 -EPG.*

394 **Proof.** Let $K = \{2, 3\}$ and $I = \{1, 6, 7\}$. If there exists a B_1 -EPG representation
 395 of anyone of those graphs, by Lemma 17, because of the existence of the vertices
 396 4 and 5, the vertex 1 must intersect vertex 2 between 6 and 7. In addition, since
 397 $\{2, 6, 8\}$ is a clique, 8 intersects 2 in an edge of $P_6 \cap P_2$ (edge-clique) or in an edge
 398 incident to $P_6 \cap P_2$ (claw-clique). Analogously, because of the clique $\{2, 7, 8\}$, 8
 399 intersects 2 in an edge of $P_7 \cap P_2$ (edge-clique) or in an edge incident to $P_7 \cap P_2$
 400 (claw-clique). In any case, it implies that 8 intersects 2 on two different edges,
 401 each one in a different side of $P_2 \cap P_1$, thus, by Observation 16, P_8 contains the
 402 interval $P_2 \cap P_1$, in contradiction with the fact that 1 and 8 are not adjacent. ■

403 **Lemma 21.** *The graphs $F_{10}(n)$ for $n \geq 8$ on Figure $\gamma(j)$ are not B_1 -EPG.*

404 **Proof.** The case $n = 8$ was considered in the previous Lemma 20, so assume
 405 $n \geq 9$. Let $K = \{2, 3\}$ and $I = \{1, 6, 7\}$. If there exists a B_1 -EPG representation
 406 of anyone of those graphs, by Lemma 17, because of the existence of the vertices
 407 4 and 5, the vertex 1 must intersect vertex 2 between 6 and 7. In addition,
 408 since $\{2, 6, 8\}$ is a clique, 8 intersects 2 in an edge of $P_6 \cap P_2$ (edge-clique) or
 409 in an edge incident to $P_6 \cap P_2$ (claw-clique). Analogously, because of the clique
 410 $\{2, 7, n\}$, n intersects 2 in an edge of $P_7 \cap P_2$ (edge-clique) or in an edge incident
 411 to $P_7 \cap P_2$ (claw-clique). In any case, it implies that 8 and n intersect 2 on two
 412 different edges, each one in a different side of $P_2 \cap P_1$. Therefore, there exist two
 413 consecutive vertices of the path $8, 9, \dots, n$, say the vertices j and $j + 1$, such that
 414 each one intersects P_2 on a different side of $P_2 \cap P_1$. Thus, by Observation 15,
 415 P_j or P_{j+1} must contain the interval $P_2 \cap P_1$, in contradiction with the fact that
 416 neither j nor $j + 1$ is adjacent to 1. ■

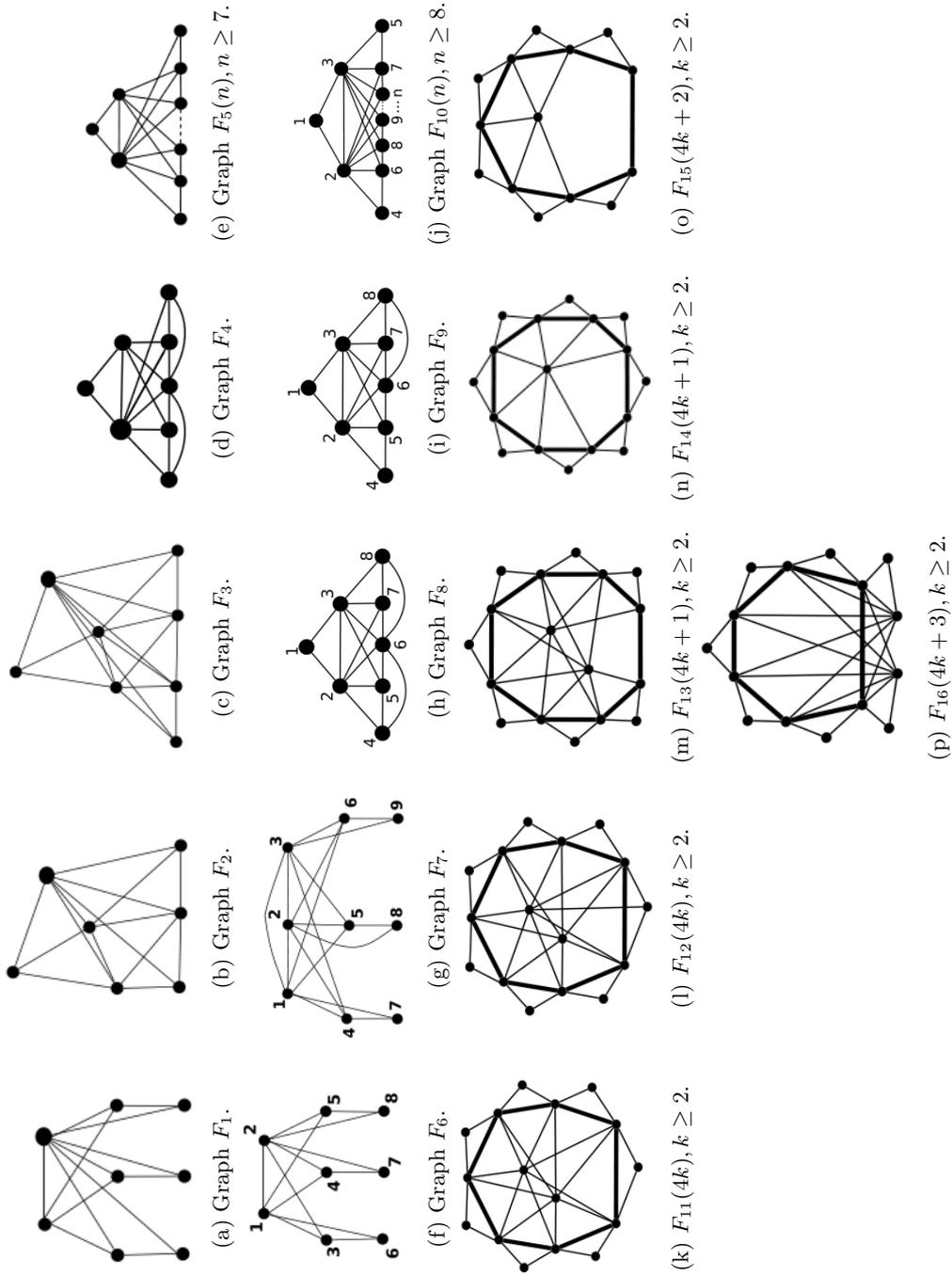


Figure 7. The 16 Chordal induced subgraphs forbidden to VPT (the vertices in the cycle marked by bold edges form a clique).

417 We have proved that every minimal forbidden induced subgraph for VPT
 418 is also a forbidden induced subgraph for Chordal B_1 -EPG. Moreover, there are
 419 graphs in VPT that do not belong to B_1 -EPG, for instance the graph 4-sun S_4
 420 is not in B_1 -EPG, see [12], but it has a VPT representation, see Figures 8(a)
 421 and 8(b). Thus, VPT graphs properly contain Chordal B_1 -EPG graphs. This
 422 ends the proof of Theorem 14.

423 **Corollary 22.** *Each one of the graphs depicted on Figure 7 is a forbidden induced*
 424 *subgraph for the class B_1 -EPG.*

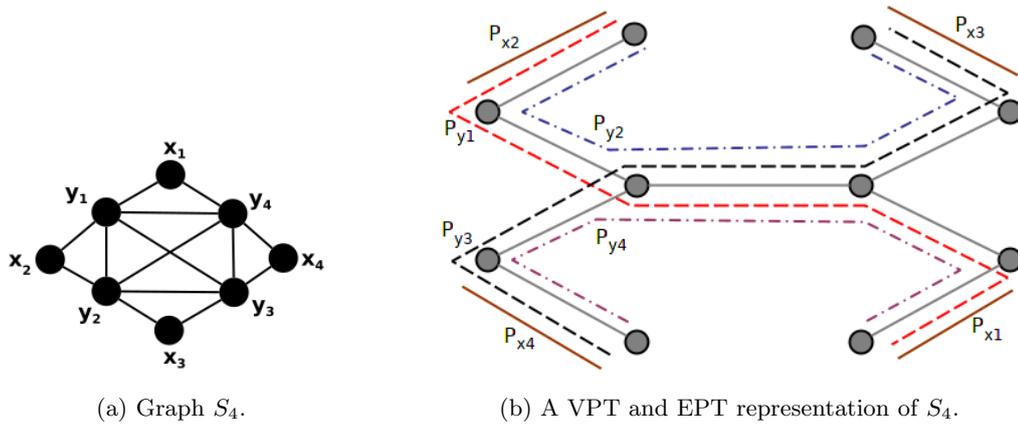


Figure 8. Graph S_4 and one of its possible VPT and EPT representations.

425 **Theorem 23.** *Chordal B_1 -EPG \subsetneq EPT.*

426 **Proof.** Let G be a Chordal B_1 -EPG graph. By the previous Theorem 14, G is
 427 VPT. And, by Lemma 7, $\chi(B(G/C)) \leq 3$ for every maximal clique C of G . In [1]
 428 (see Theorem 10), it was proved that if the chromatic number of the branch graph
 429 of a VPT graph is at most h for every maximal clique, then the graph admits a
 430 VPT representation on a host tree with maximum degree h . Therefore, G admits
 431 a VPT representation on a host tree with maximum degree 3. Finally, in [10] (see
 432 Theorem 2), it was proved that any VPT graph that admits a representation on
 433 a host tree with maximum degree 3 is also an EPT graph. Consequently, G is
 434 EPT.

435 The same graph S_4 used in the proof of the previous theorem (see Figure 8(b))
 436 shows that there are EPT graphs that are not B_1 -EPG. ■

437

5. CONCLUSION AND OPEN QUESTIONS

438 In this paper, we have considered three different path-intersection graph classes:
 439 B_1 -EPG, VPT and EPT graphs. We showed that $\{S_3, S_{3'}, S_{3''}, C_4\}$ -free graphs
 440 and others non-trivial subclasses of B_1 -EPG graphs are Helly- B_1 -EPG, namely
 441 by instance Bipartite, Block, Cactus and Line of Bipartite graphs.

442 We presented an infinite family of forbidden induced subgraphs for the class
 443 B_1 -EPG and in particular we proved that Chordal B_1 -EPG \subset VPT \cap EPT.

444 In [3], Asinowski and Ries described the Split graphs that are B_1 -EPG
 445 graphs in case the stable set or the central size have size three. The graphs
 446 $F_2, F_{11}, F_{13}, F_{14}$ and F_{15} , given in Figure 7 are Split, we have used a different ap-
 447 proach to prove that they are not B_1 -EPG graphs. So one question is pertinent:
 448 Can we characterize Split graphs in general based on the results of this paper?

449 Finally, another interesting research would be to explore families of Helly-
 450 EPG graphs more deeply. We would like to understand the behavior of other
 451 graph classes inside B_1 -EPG graph class, i.e. if given an input graph G that is
 452 an instance of (for example) Weakly Chordal B_1 -EPG. What is the relationship
 453 of G with the EPT/VPT graph class? What happens when we demand that the
 454 representations be Helly- B_1 -EPG? Does recognizing problem remains hard for
 455 each one of these classes?

456

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Chapter 6

Concluding Remarks

If I have seen further, it is by standing upon the shoulders of giants.

Sir Isaac Newton

In Chapter 3, we show that every graph admits a Helly-EPG representation, in particular, is possible to modify the demonstration to prove that every graph admits a monotonic Helly-EPG representation, and $\frac{\mu}{2n} - 1 \leq b_H(G) \leq \mu - 1$. Besides, we relate Helly- B_1 -EPG graphs with L-shaped graphs, a natural family of subclasses of B_1 -EPG. Also, we prove that recognizing (Helly-) B_k -EPG graphs is in \mathcal{NP} , for every fixed k . Finally, we show that recognizing Helly- B_1 -EPG graphs is NP -complete, and it remains NP -complete even when restricted to 2-apex and 3-degenerate graphs. In addition, at the end of the chapter, we prove that Helly- B_k -EPG $\subsetneq B_k$ -EPG for each $k > 0$.

In this way, we suggest asking about the complexity of recognizing Helly- B_k -EPG graphs for each $k > 1$. Also, it seems interesting to present characterizations for Helly- B_k -EPG representations similar to Lemma 6 (especially for $k = 2$, paper of Chapter 3) as well as considering the h -Helly- B_k EPG graphs. Regarding L-shaped graphs, it also seems interesting to analyze the classes Helly- $[\sqcup, \sqcap]$ and Helly- $[\sqcup, \sqcap, \sqcap]$ (recall Theorem 14, also paper of Chapter 3).

In Chapter 4, we have determined the Helly number and strong Helly number of B_k -EPG graphs and B_k -VPG graphs, for $k \geq 0$.

Table 6.1 summarizes the results obtained.

We leave two questions to be investigated concerning the presented results.

1. Given a *specific* EPG or VPG graph, the question is to formulate an algorithm to determine its Helly and strong Helly numbers. See [29], for instance, for such algorithms, applied to general graphs.
2. The values of the Helly and strong Helly numbers, which were determined in

Table 6.1: Helly and Strong Helly Numbers for B_k -EPG and B_k -VPG Graphs

k	B_k -EPG	B_k -VPG
0	2	2
1	3	4
2	4	6
3	8	12
≥ 4	unbounded	unbounded

the chapter, coincided in all cases. Clearly, in general, this is not the case. We leave as an open question, to find the conditions for such equality to occur.

In Chapter 5, we have considered graphs of the intersection of paths, in particular, Chordal B_1 -EPG, VPT, and EPT graphs. We show that graphs $\{S_3, S_{3'}, S_{3''}, C_4\}$ -free and others non-trivial subclasses of B_1 -EPG graphs have the Helly property, namely for instance Bipartite, Block, Cactus and Line of Bipartite graphs.

In addition, combining the results of [2, 8, 46] and some other proofs presented in the chapter, we demonstrate by Theorems 14 and 23 (paper of Chapter 5) that Chordal B_1 -EPG graphs are simultaneously contained in the classes of VPT and EPT graphs.

Asinowski and Ries present in [65] some characterization for special cases of Split B_1 -EPG graphs, when the stable set has size three or when the clique has size three. Observe that the graphs $F_2, F_{11}, F_{13}, F_{14}, F_{15}$, given in Figure 7 (paper of Chapter 5), are Split but we used another strategy to prove that they are not B_1 -EPG graphs. So one question is pertinent: Can we characterize Split graphs in general based on results of this chapter?

Another interesting research would be to explore families of Helly-EPG graphs more deeply. We would like to understand the behavior of other graph classes inside B_1 -EPG graph class, i.e. if given an input graph G that is an instance of (for example) Weakly Chordal B_1 -EPG. What is the relationship of G with the EPT/VPT graph class? What happens when we demand that the representations be Helly- B_1 EPG? Do the recognition problems remain hard for each one of these classes?

In the course of this research, in particular, we studied edge-intersection graphs of paths in a grid such that the paths had at most one bend and the representation has the Helly property for the edges of the paths. The problem of recognizing whether a graph has a B_k -EPG representation is an open problem for $k \geq 3$, i.e. given a graph G , which is the smallest k such that G has a B_k -EPG representation? Also, the problem of recognizing whether a graph has a Helly- B_k -EPG representation remains an open problem for $k \geq 2$. The evidence observed in the EPG graph

literature and the results obtained in this work makes us conjecture that the problem of recognizing both B_k -EPG and Helly- B_k -EPG are both NP -complete problems, but this demonstration is unknown.

The study of the parameters Helly number and strong Helly number for edge-intersection graphs on a grid was mentioned only in [46, 47], which studied only the parameter strong Helly number. It is easy to see that the questions related of this parameters arise naturally when studying the property of the intersecting sets having the property of being k -Helly, thus, another research proposed as the objective of this work was the study of upper and lower bounds for the parameters Helly number and strong Helly number, both for specific classes of EPG and Helly-EPG graphs and also for VPG and Helly-VPG graphs.

In the work of COHEN *et al.* [26], mentioned in Chapter 3, the Cographs that are B_1 -EPG are characterized by a minimal family of forbidden subgraphs. Moreover, when considered in the context of this work, we can ask: concerning to characterization, what are the Cographs Helly- B_1 EPG? Is its recognition also polynomial and can it be done using its co-tree? Is there a difference among these B_1 -EPG and Helly- B_1 EPG families? In addition to the known results for Cographs, we propose potential research topics as problems of recognition or hardness proof for specific classes of graphs B_1 -EPG and Helly- B_1 EPG.

Last but not least, the author of this thesis (Tanilson) conducted research as a sandwich doctorate at the National University of La Plata - UNLP, Argentina, for 1 year (March/2019 until March/2020). The welcome, insertion in the research and workgroup developed during this period must be gratefully acknowledged. Conducting this research at UNLP brought benefits to this doctoral thesis and to the maturity its author as a researcher, since from this period two articles emerged submitted to the SBPO and to DMGT. To continue these works, we hope to explore the Helly-EPG subfamilies.

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